



perfect in sensors.



## POSIROT®

### Magnetic Angle Sensors and Encoders

Product catalog

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Germany

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	PRAS20	PRAS20R	PRAS21	PRAS26	PRAS27	PRDS27	PRAS1	PRDS1		
	A	A	A	A	A	D	A	D		
<b>Measurement range</b>										
0° ... 360°	•	•	•	•	•	•	•	•	•	•
<b>Analog output, absolute</b>										
Voltage 0.5 ... 10 V	•				•	•			•	
Voltage 0.5 ... 4.5 V	•	•	•		•	•			•	
Current 4 ... 20 mA	•				•	•			•	
Redundant version		•				•				
<b>Digital output, absolute</b>										
SSI – RSSI5V, RSSI24V										•
CANopen							•			
CAN SAE J1939							•			
Redundant version CAN							•			
<b>Digital output, incremental</b>										
RS5V, RS24V										•
RS5VF, RS24VF										•
HT24V										•
HT24VF										•
<b>Standard linearity</b>										
	±0.5%		±0.5%		±0.5%		±0.5%		±1°	
<b>Protection class</b>										
Standard	IP60		IP60		IP60		IP67		IP67	
Optional									IP67/IP69*	

A = Analog output D = Digital output

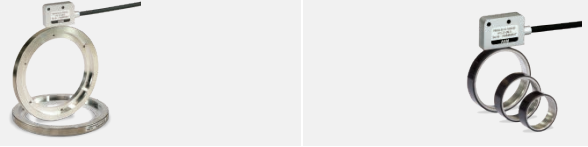
\* = with a suitable connector IP67/IP69

Dust-EX-proof Angle Sensors						
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	PRAS2EX	PRAS3EX	PRAS5EX			
	A	A	A			
<b>Measurement range</b>						
0° ... 360°	•	•	•	•	•	•
<b>Analog output, absolute</b>						
Voltage 0.5 ... 10 V	•	•	•	•	•	•
Voltage 0.5 ... 4.5 V	•	•	•	•	•	•
Current 4 ... 20 mA	•	•	•	•	•	•
Redundant version						
<b>Standard linearity</b>						
	±0.3%		±0.3%		±0.3%	
<b>Protection class</b>						
Standard	IP65		IP65		IP65	
Dust-EX-proof						

												Selection guide										
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A		D		A		D		A		A		D		A		D		A		D		
																						<b>Measurement range</b>
																						0° ... 360°
																						<b>Analog output, absolute</b>
																						Voltage 0.5 ... 10 V
																						Voltage 0.5 ... 4.5 V
																						Current 4 ... 20 mA
																						Redundant version
																						<b>Digital output, absolute</b>
																						SSI – RSSI5V, RSSI24V
																						CANopen
																						CAN SAE J1939
																						Redundant version CAN
																						<b>Digital output, incremental</b>
																						RS5V, RS24V
																						RS5VF, RS24VF
																						HT24V
																						HT24VF
																						<b>Standard linearity</b>
±0.3%		±1°		±0.3%		±1°		±0.3%		±0.3%		±1°		±0.3%		±1°		±0.3%		±1°		
																						<b>Protection class</b>
IP67		IP67		IP68		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		Standard
IP67/IP69*		IP67/IP69*		IP68		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		IP67/IP69*		Optional

A = Analog output D = Digital output

\* = with a suitable connector IP67/IP69

				Magnetic Incremental Encoders
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PMIS4/PMIR5		PMIS4/PMIR7(N)		Measurement range
				0° ... 360°
				<b>Digital output, incremental</b>
				HTL
				TTL
				TTL24V
				<b>Standard linearity</b>
±0.1°		±0.1°		
				<b>Protection class</b>
IP67		IP67		

## Company Profile

### **ASM - Sensors for Displacement. Angle. Inclination.**

With more than 35 years of company tradition ASM is your expert partner for mechatronic displacement, angle and inclination sensors. ASM global headquarters in Moosinning, Germany, represent the heart of the company and are the center for sensor research, development and manufacturing. With a global sales network of more than 30 distributors and company subsidiaries ASM ensures worldwide accessibility to its customers.

The ASM product program includes various sensor technologies and comprises seven product lines offering a broad range of innovative solutions to measure linear displacement, angle and inclination.

### **Product range**

**POSIWIRE®** Cable Extension Position Sensors

**POSITAPE®** Tape Extension Position Sensors

**POSICHRON®** Magnetostrictive Position Sensors

**POSIMAG®** Magnetic Scale Position Sensors

**POSIROT®** Magnetic Angle Sensors

**POSIHALL®** Magnetic Multiturn Angle Sensors

**POSITILT®** Inclination Sensors

### **Quality and reliability**

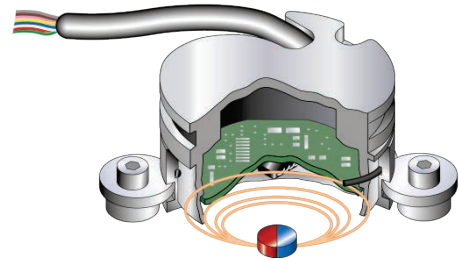
ASM high-quality products are subjected to a stringent quality management certified according to DIN EN ISO 9001:2008.

Your application specific requests are evaluated by ASM product specialists in a comprehensive technical consultation to find out which solution best meets your requirements – this can be a standard or a customer specific technology solution.



## Advantages at a Glance

The absolute POSIROT® angular displacement sensors measure angular displacement and position of rotating objects using a magnetic measuring principle. Because the magnetic encoder technology is entirely contactless and solid state, POSIROT®-sensors are resistant to shock, vibration and dirt, which makes them ideally suited for harsh outdoor applications, where they far outperform traditional optical encoders. Multiple designs are available, from flat, low profile housing to M12 stainless-steel housing to allow for easy and flexible integration on demanding applications



### Technical Advantages

- Measuring range: 0° to 360°
- Magnetic measuring technology
- Contactless or with shaft
- Superb resistance to shock, vibration and dirt
- Protection class up to IP69
- Common analog and digital output signals for easy integration.
- Absolute, analog, incremental and linear measuring

### POSIROT®: The functional principle:

#### Magnetic Absolut

In contrast to optical encoders, POSIROT® sensors utilize a ferromagnetic scale that modulates a magnetic field, which is analyzed and processed by Multihall technology.

#### Magnetic Incremental

##### POSIROT® PMIS-Series

In contrast to optical encoders, the incremental encoders of the POSIROT® PMIS series consist of a magnetoresistive read head and a magnetic ring as a magnetic scale.

##### POSIROT® PRDS-Series

The PRDS series uses a permanent magnet as position generator that modulates a magnetic field, which is analyzed and processed by Multihall technology.



## Applications

POSIROT® angular displacement sensors are specifically designed for the precise measurement of angular positions in harsh environments commonly found in the field of mobile working machines, e.g. cranes, excavators, ships, and wind power plants. POSIROT® angle sensors with protection class IP60 are suited for demanding indoor applications such as large-scale medical equipment.

### Mobile Working Machines

Mobile machines in applications such as agricultural and harvesting machines, communal vehicles or construction machinery require extremely rugged sensor solutions. POSIROT® angle sensors function trouble-free even under difficult operating conditions, such as dirt, temperature, shock or vibration. The Heavy Duty sensors are wear- and maintenance-free and are engineered for a long service-life.



### Safety Applications

Safety critical applications, such as mobile cranes, require double protection against potential sensor failures. POSIROT® angle sensors with redundant electronics ensure correct angle measurement even if an electronic component fails.



### Outdoor- and Hygienic Applications

POSIROT® angle sensors are equipped with completely encapsulated electronics, so that they are able to withstand all kinds of weather conditions. With these properties they are perfectly suited for outdoor use and for hygienic applications with intensive cleaning processes such as food packaging machines.

### Large-Scale Medical Devices

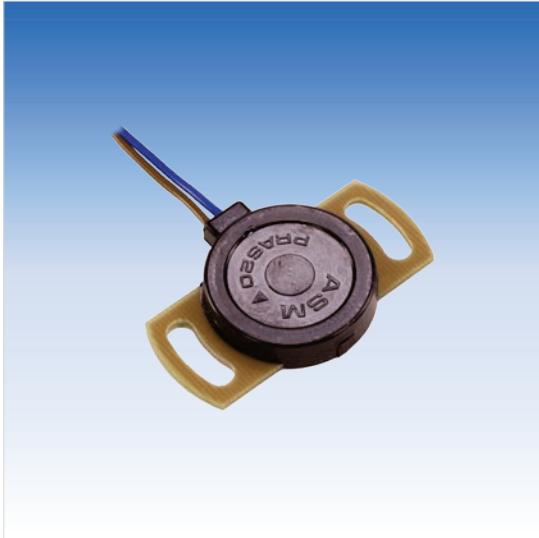
The high-performance POSIROT® sensor line offers tailored solutions for absolute and incremental measurement tasks for large-scale medical equipment, such as surgical tables or computer tomographs. The sensors are characterized by highest precision and reliability even under severe conditions. The sensor integral shielding protects reliably against external magnetic fields.





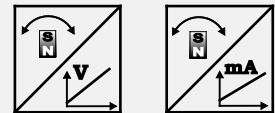
## PRAS20

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP60
- Analog output
- Compact, low profile housing
- Non-contact with external position magnet, no wear
- Housing: Epoxy glass fibre, thermoplastic



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V, ratiometric Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.5% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP60
<b>Housing material</b>	Epoxy glass fibre, thermoplastic
<b>Mounting</b>	Screws M4
<b>Connection</b>	Single wire ETFE 3 x 0.5 mm <sup>2</sup>
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	8 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

**PRAS20** – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

**U2B** = Voltage 0.5 ... 10 V (excitation voltage 11.5 ... 27 V DC)  
**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
**I1B** = Current 4 ... 20 mA, 3 wire (excitation voltage 10 ... 27 V DC)

**3 Signal characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**4 Connection**

**A300** = Single wire ETFE 3 x 0.5 mm<sup>2</sup>, length 300 mm

**Order example**

**PRAS20 – 360 – U6 – CW – A300**

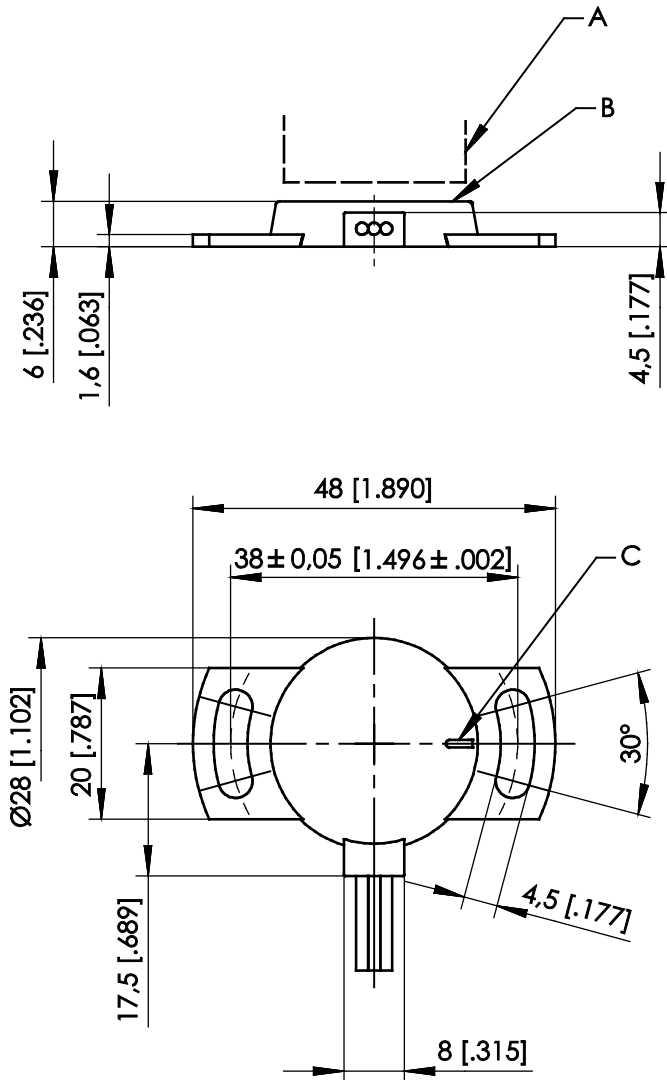
**Accessories:**

**Position magnets (see from page 122)**

**Magnetic shield (see page 15)**



**Dimensions**



- A – Position magnet
- B – Measuring area
- C – Marking

Dimensions in mm [inch]. Weight without cable approx. 8 g.  
Dimensions for information only.  
For guaranteed dimensions consult factory.

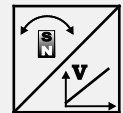
## PRAS20R

### Analog output, redundant



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP60
- Analog output, redundant
- Compact, low profile housing
- Non-contact with external position magnet, no wear
- Redundant second channel



#### Specifications

<b>Output</b>	Voltage 0.5 ... 4.5 V, ratiometric
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.5% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP60
<b>Housing material</b>	Epoxy glass fibre, thermoplastic
<b>Mounting</b>	Screws M4
<b>Connection</b>	Single wire ETFE 6 x 0.5 mm <sup>2</sup>
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	8 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS20R – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)

**3 Signal characteristics**

**CW/CCW** = Signal 1 increasing clockwise, signal 2 increasing counterclockwise  
**CW/CW** = Signal 1 and signal 2 increasing clockwise  
**CCW/CCW** = Signal 1 and signal 2 increasing counterclockwise

**4 Connection**

**A300** = Single wire ETFE 6 x 0.5 mm<sup>2</sup>, length 300 mm

**Order example**

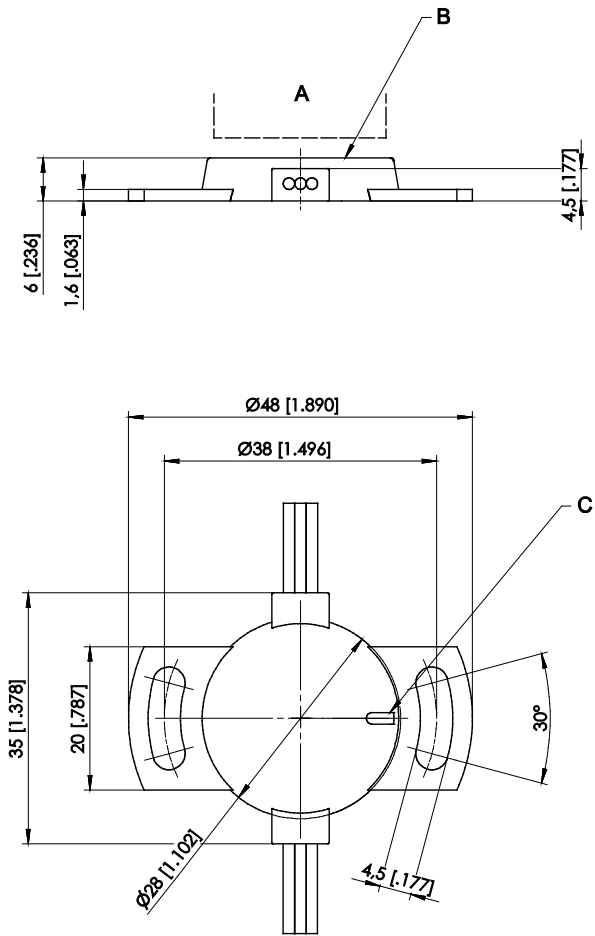
**PRAS20R – 360 – U6 – CW/CCW – A300**

**Accessories:**

**Position magnets (see from page 122)**

**Magnetic shield (see page 15)**

Dimensions



- A – Position magnet
- B – Measuring area
- C – Marking

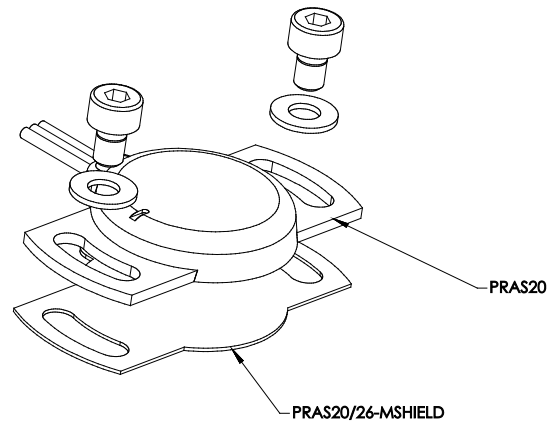
Dimensions in mm [inch]. Weight without cable approx. 8 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**PRAS20 / PRAS20R Magnetic shield**

An optional shield plate is available for the angle sensors PRAS20 and PRAS20R. It can reduce the effect of residual magnetizing in case the sensor has to be mounted on a ferromagnetic material.

**Order code magnetic shield:**

**PRAS20/26-MSHIELD**



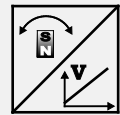
## PRAS21

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP60
- Analog output
- Compact, low profile housing
- Non-contact with external position magnet, no wear
- Housing: Epoxy glass fibre, thermoplastic



#### Specifications

<b>Output</b>	Voltage 0.5 ... 4.5 V, ratiometric
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.5% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP60
<b>Housing material</b>	Epoxy glass fibre, thermoplastic
<b>Mounting</b>	Screws M3
<b>Connection</b>	Single wire ETFE 3 x 0.5 mm <sup>2</sup>
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	5 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS21 – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)

**3 Signal characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**4 Connection**

**A300** = Single wire ETFE 3 x 0.5 mm<sup>2</sup>. length 300 mm

**Order example**

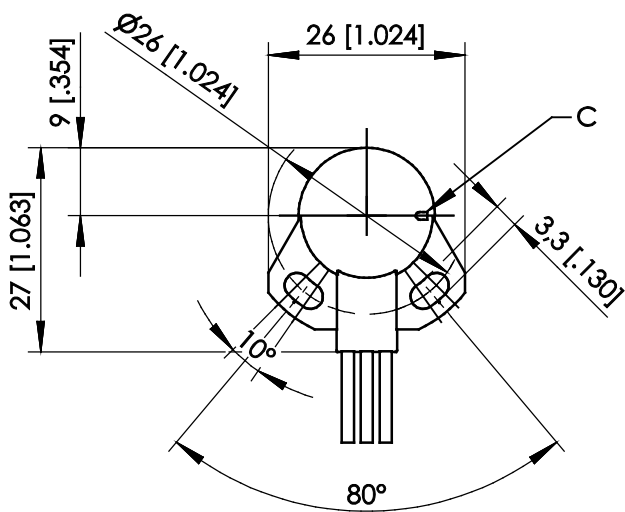
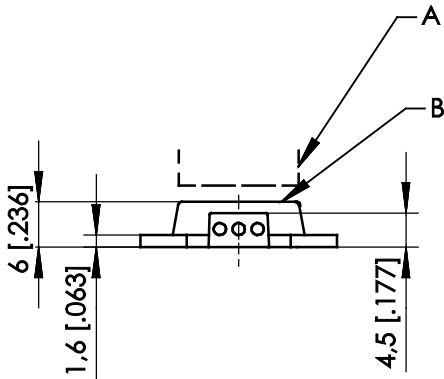
PRAS21 – 360 – U6 – CW – A300

**Accessories:**

**Position magnets (see from page 122)**

**Magnetic shield (see page 19)**

**Dimensions**



A – Position magnet  
B – Measuring area  
C – Marking

Dimensions in mm [inch]. Weight without cable approx. 5 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

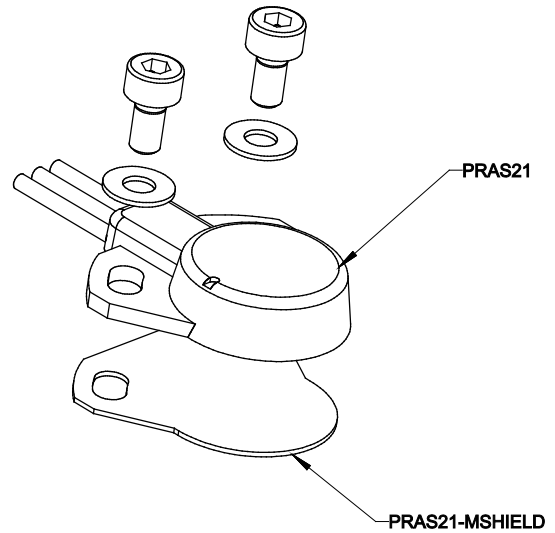


**PRAS21 Magnetic Shield**

An optional shield plate is available for the angle sensor PRAS21. It can reduce the effect of residual magnetizing in case the sensor has to be mounted on a ferromagnetic material.

**Order code magnetic shield:**

**PRAS21-MSHIELD**



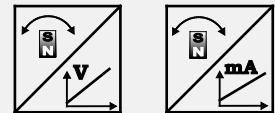
## PRAS26

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP60
- Analog output
- Compact, low profile housing
- Non-contact with external position magnet, no wear
- Housing: Epoxy glass fibre, thermoplastic



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V, ratiometric Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.5% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP60
<b>Housing material</b>	Epoxy glass fibre, thermoplastic
<b>Mounting</b>	Screws M4
<b>Connection</b>	3-pin connector, Tyco Electronics, type "SlimSeal"
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	8 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS26 – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

**U2B** = Voltage 0.5 ... 10 V (excitation voltage 11.5 ... 27 V DC)  
**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
**I1B** = Current 4 ... 20 mA, 3 wire (excitation voltage 10 ... 27 V DC)

**3 Signal characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**4 Connection**

**TE3** = 3-pin connector, Tyco Electronics, type "SlimSeal"

**Order example**

PRAS26 – 360 – U6 – CW – TE3

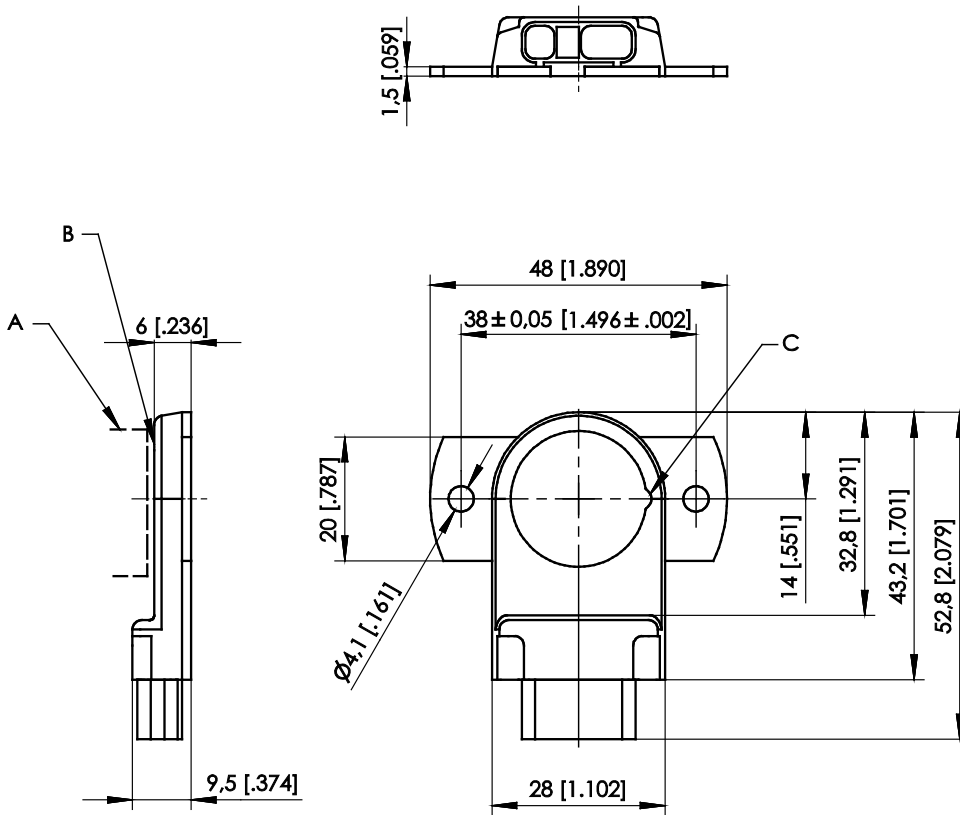
**Accessories:**

**Connector cables (see page 160)**

**Position magnets (see from page 122)**

**Magnetic shield (see page 23)**

**Dimensions**



- A – Position magnet
- B – Measuring area
- C – Marking

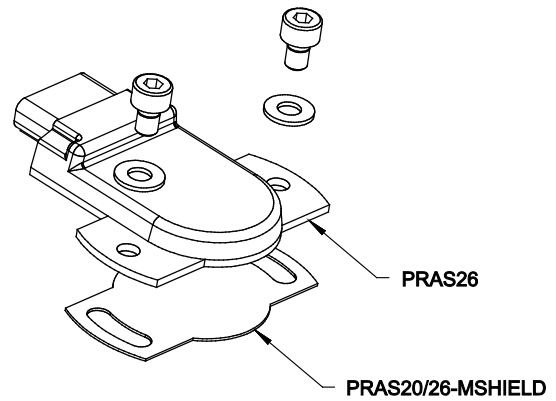
Dimensions in mm [inch]. Weight without cable approx. 8 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**PRAS26 Magnetic shield**

An optional shield plate is available for the angle sensor PRAS26. It can reduce the effect of residual magnetizing in case the sensor has to be mounted on a ferromagnetic material.

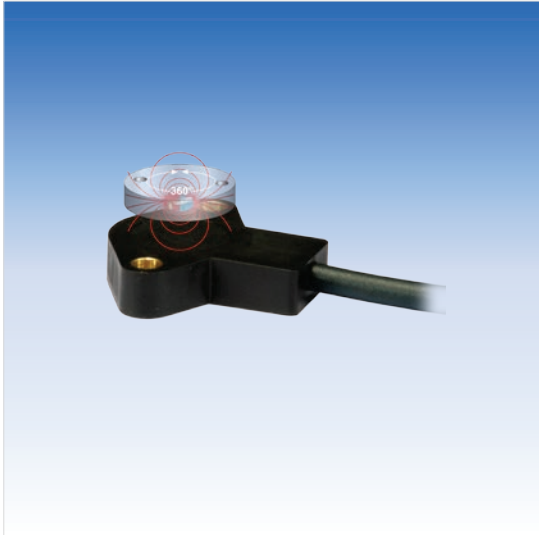
**Order code magnetic shield:**

**PRAS20/26-MSHIELD**



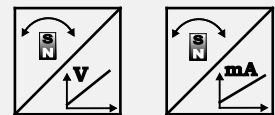
## PRAS27

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67
- Analog output
- Compact, low profile housing
- Non-contact with external position magnet, no wear
- Housing: Plastic



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.5% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67
<b>Housing material</b>	Plastic
<b>Mounting</b>	Screws M4: DIN 912, DIN 6912, DIN 7984
<b>Connection</b>	Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	20 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS27 – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

<b>U2</b>	= Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)
<b>U2B</b>	= Voltage 0.5 ... 10 V (excitation voltage 11.5 ... 27 V DC)
<b>U6</b>	= Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)
<b>U8</b>	= Voltage 0.5 ... 4.5 V (excitation voltage 11 ... 36 V DC)
<b>I1</b>	= Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)
<b>I1B</b>	= Current 4 ... 20 mA, 3 wire (excitation voltage 10 ... 27 V DC)

**3 Signal characteristics**

<b>CW</b>	= Signal increasing CW, clockwise
<b>CCW</b>	= Signal increasing CCW, counterclockwise

**4 Connection**

<b>KAB2M</b>	= Cable, standard length 2 m
<b>KAB2M-DT04/3P/A*</b>	= Cable 2 m with Deutsch connector DT04, 3 pin
<b>KAB2M-DT04/3P/A-S*</b>	= Cable 2 m with Deutsch connector DT04, 3 pin, with protective tube
<b>KAB2M-DT04/4P/A</b>	= Cable 2 m with Deutsch connector DT04, 4 pin
<b>KAB2M-DT04/4P/A-S</b>	= Cable 2 m with Deutsch connector DT04, 4 pin, with protective tube

\* only for output U6

**Order example**

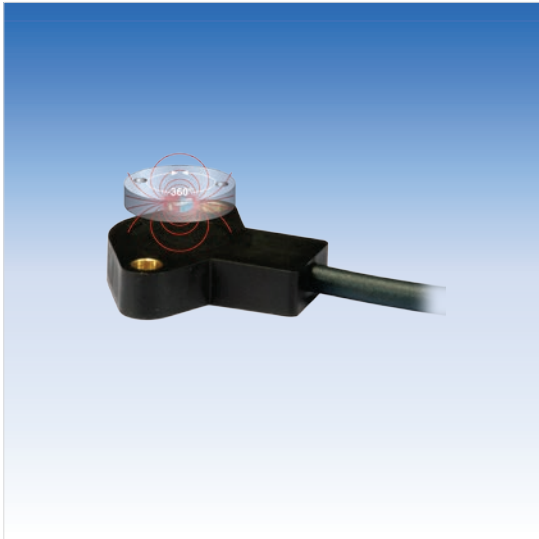
PRAS27 – 360 – U6 – CW – KAB2M

**Accessories:**

**Position magnets (see from page 122)**

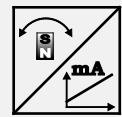
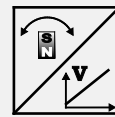
**Magnetic shield (see page 31)**

## Analog output, redundant



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67
- Analog output, redundant
- Compact, low profile housing
- Non-contact with external position magnet, no wear
- Housing: Plastic



### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V, redundant Voltage 0.5 ... 4.5 V, redundant Current 4 ... 20 mA, 3 wire, redundant
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.5% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67
<b>Housing material</b>	Plastic
<b>Mounting</b>	Screws M4: DIN 912, DIN 6912, DIN 7984
<b>Connection</b>	Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	20 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013



**Order code**

PRAS27 – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

**U2R** = Voltage 0.5 ... 10 V, redundant (excitation voltage 18 ... 36 V DC)  
**U8R** = Voltage 0.5 ... 4.5 V, redundant (excitation voltage 11 ... 36 V DC)  
**I1R** = Current 4... 20 mA, 3 wire, redundant (excitation voltage 18 ... 36 V DC)  
(output I1R possible only with CW/CCW signal characteristics)

**3 Signal characteristics**

**CW/CCW** = Signal 1 increasing clockwise, signal 2 increasing counterclockwise  
**CW/CW\*** = Signal 1 and signal 2 increasing clockwise  
**CCW/CCW\*** = Signal 1 and signal 2 increasing counterclockwise

\* not available with output I1R

**4 Connection**

**KAB2M** = Cable, standard length 2 m  
**KAB2M-DT04/6P/A\*** = Cable 2 m with Deutsch connector DT04, 6 pin  
**KAB2M-DT04/6P/A-S\*** = Cable 2 m with Deutsch connector DT04, 6 pin, with protective tube

\* only for output U6R

**Order example**

PRAS27 – 360 – U2R – CW/CCW – KAB2M

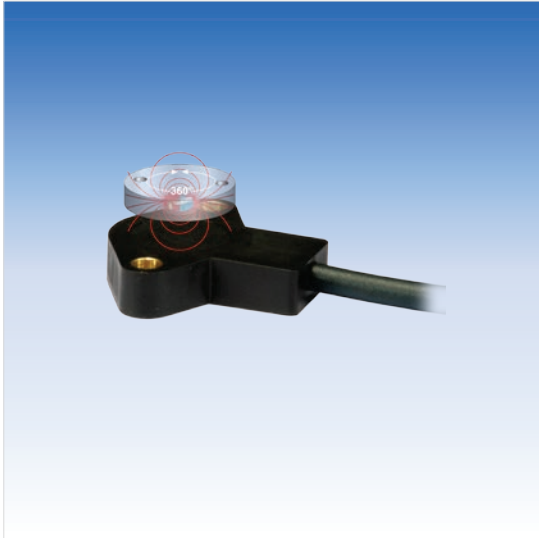
**Accessories:**

**Position magnets (see from page 122)**

**Magnetic shield (see page 31)**

**PRDS27**

**Digital output CAN**



**Sensor features**

- **Measurement range 0 ... 360°**
- **Protection class IP67**
- **Digital output CAN**
- **Non-contact with external position magnet, no wear**
- **Housing: Plastic**
- **Redundant version available**



**Specifications**

<b>Output</b>	CANopen (CiA 301-V4.02/406-V3.2) CAN SAE J1939
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	0.05° max.
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67
<b>Housing material</b>	Plastic
<b>Mounting</b>	Screws M4: DIN 912, DIN 6912, DIN 7984
<b>Connection</b>	Cable 0.3 m, 5-pin connector M12 Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	20 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS27 – 1 – 2

**1 Output**

<b>CANOP</b>	= CANopen
<b>CANJ1939</b>	= CAN SAE J1939
<b>CANOPR</b>	= CANopen, redundant
<b>CANJ1939R</b>	= CAN SAE J1939, redundant

**2 Connection**

<b>KAB0,3M-M12/CAN</b>	= Cable 0.3 m with connector M12, 5 pin
<b>KAB0,3M-DT04/4P/A</b>	= Cable 0.3 m with Deutsch connector DT04, 4 pin
<b>KAB0,3M-DT04/4P/A-S</b>	= Cable 0.3 m with Deutsch connector DT04, 4 pin, with protective tube

**Order example**

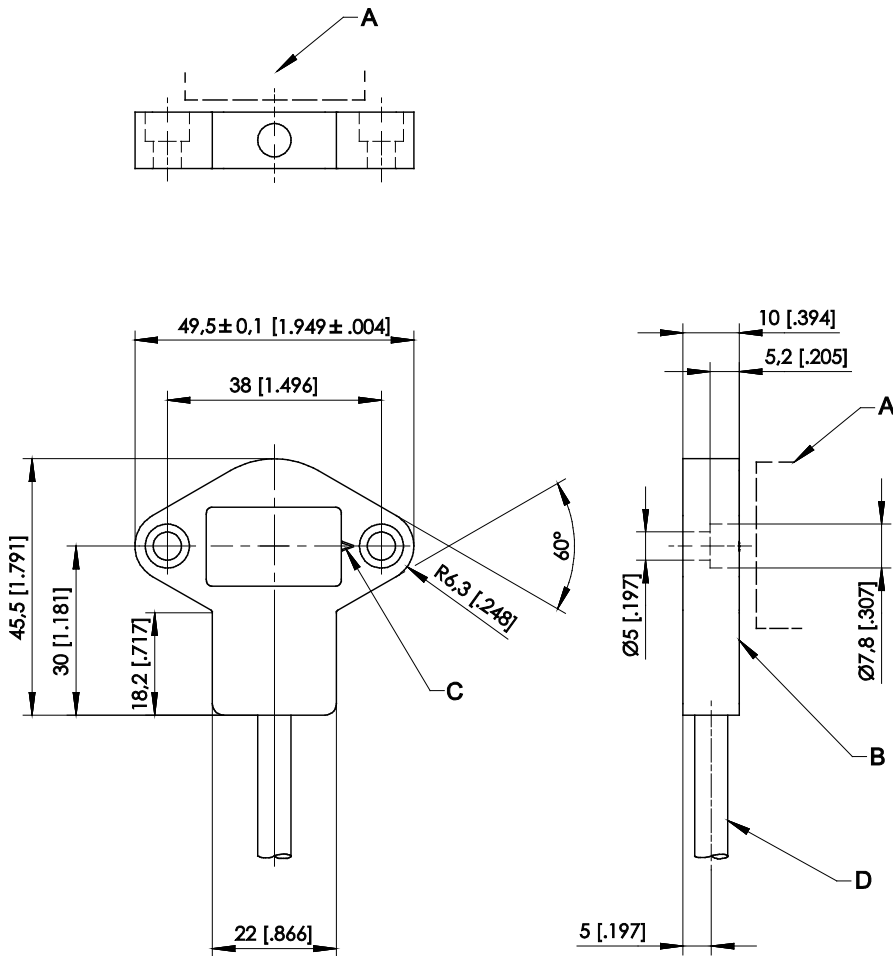
**PRDS27 – CANOP – KAB0,3M – DT04/4P/A**

**Accessories:**

**Position magnets (see from page 122)**

**Magnetic shield (see page 31)**

**Dimensions (analog and digital version)**



- A – Position magnet
- B – Measuring area
- C – Marking
- D – Cable

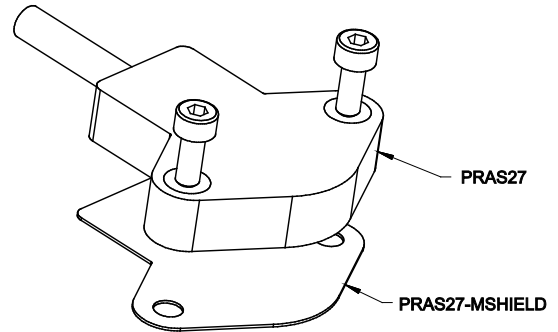
Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**PRAS27 Magnetic Shield**

An optional shield plate is available for the angle sensors PRAS27 and PRDS27. It can reduce the effect of residual magnetizing in case the sensor has to be mounted on a ferromagnetic material.

**Order code magnetic shield:**

**PRAS27-MSHIELD**



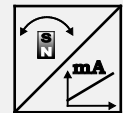
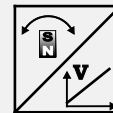
## PRAS1

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Analog output
- Magnetic measurement principle
- Non-contact with external position magnet, no wear
- Housing: Stainless steel



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (with IP67/IP69 connector cable)
<b>Housing material</b>	Stainless steel
<b>Mounting</b>	M12 x 1
<b>Connection</b>	5-pin connector M12 (compatible to 4-pin connector)
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	35 g approx.
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS1 – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

- U2** = Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)
- U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)
- U8** = Voltage 0.5 ... 4.5 V (excitation voltage 11 ... 36 V DC)
- I1** = Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)

**3 Signal characteristics**

- CW** = Signal increasing CW, clockwise
- CCW** = Signal increasing CCW, counterclockwise

**4 Connection**

- M12A5** = 5-pin connector M12 (compatible to 4-pin connector)

**Order example**

PRAS1 – 360 – I1 – CW – M12A5

**Accessories:**

**Connector cable (see page 157)**

**Position magnets (see from page 122)**

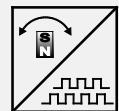
## PRDS1

### Incremental output



#### Sensor features

- **Measurement range 0 ... 360°**
- **Protection class IP67/IP69**
- **Incremental output**
- **Magnetic measurement principle**
- **Non-contact with external position magnet, no wear**
- **Housing: Stainless steel**



#### Specifications

<b>Output</b>	Incremental encoder output, RS422-/HTL compatible
<b>Measurement range</b>	0 ... 360°
<b>Resolution (pulses per revolution)</b>	1 / 2 / 4 / 8 / 16 / 25 / 32 / 45 / 50 / 64 / 75 / 90 / 100 / 125 / 128 / 256 / 512 / 1024
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (with IP67/IP69 connector cable)
<b>Max. output frequency</b>	200 kHz (the quadrature counter of the subsequent circuit must be able to process >200 kHz)
<b>Material</b>	Stainless steel
<b>Mounting</b>	M12 x 1
<b>Connection</b>	8-pin connector M12
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	35 g approx.
<b>EMC</b>	DIN EN 61326-1:2013



**Order code**

PRDS1 – 1 – 2 KHZ – 3 – 4

**1 Resolution (pulses per revolution)**

1 / 2 / 4 / 8 / 16 / 25 / 32 / 45 / 50 / 64 / 75 / 90 / 100 / 125 / 128 / 256 / 512 / 1024

**2 Maximum pulse frequency**

**50** = 50 kHz (standard)  
**200** = 200 kHz

**3 Output**

**RS5V** = RS422 compatible output with excitation 5 V DC  
**RS24V** = RS422 compatible output with excitation 10 ... 36 V  
**HT24V** = HTL compatible output with excitation 18 ... 36 V

**4 Connection**

**M12A8** = 8-pin connector M12

**Order example**

PRDS1 – 1024 – 50 KHZ – RS5V – M12A8

**Accessories:**

**Connector cable (see page 158)**

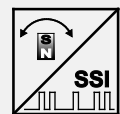
**Position magnets (see page 122)**

## Digital output SSI



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Digital output SSI
- Magnetic measurement principle
- Non-contact with external position magnet, no wear
- Housing: Stainless steel



### Specifications

<b>Output</b>	Synchronous serial SSI
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	12 Bit (4096 steps) per revolution
<b>Repeatability</b>	±0.1° (typical)
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel
<b>Mounting</b>	M12 x 1
<b>Connection</b>	8-pin connector M12
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	35 g approx.
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS1 – 1 – 2 – 3

**1 Output**

**RSSI5V** = Synchronous serial output with excitation 5 V DC  
**RSSI24V** = Synchronous serial output with excitation 10 ... 36 V

**2 Code characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**3 Connection**

**M12A8** = 8-pin connector M12

**Order example**

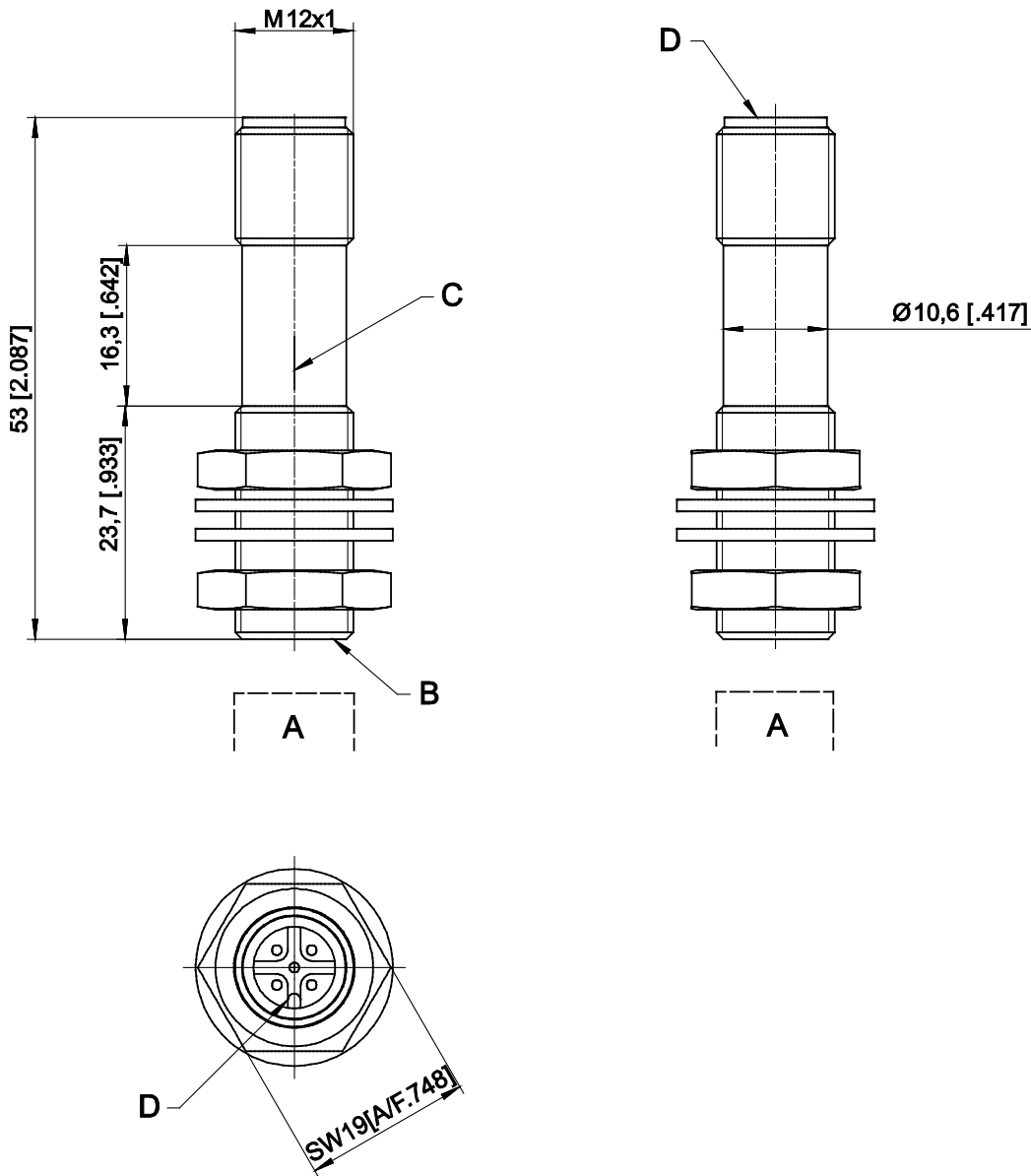
PRDS1 – RSSI5V – CW – M12A8

**Accessories:**

**Connector cable (see page 158)**

**Position magnets (see from page 122)**

**Dimensions (analog and digital version)**



- A – Position magnet
- B – Measuring area
- C – Marking
- D – Connector M12

Dimensions in mm [inch]. Weight approx. 35 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

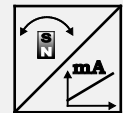
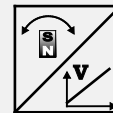
## PRAS2

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Analog output
- Flat housing – 20 mm / 25 mm thickness
- Non-contact with external position magnet, no wear
- Housing: Aluminium



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Housing material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	5-pin connector M12 (compatible to 4-pin connector) Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	50 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS2 – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

<b>U2</b>	= Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)
<b>U2B</b>	= Voltage 0.5 ... 10 V (excitation voltage 11.5 ... 27 V DC)
<b>U6</b>	= Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)
<b>U8</b>	= Voltage 0.5 ... 4.5 V (excitation voltage 11 ... 36 V DC)
<b>I1</b>	= Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)
<b>I1B</b>	= Current 4 ... 20 mA, 3 wire (excitation voltage 10 ... 27 V DC)

**3 Signal characteristics**

<b>CW</b>	= Signal increasing CW, clockwise
<b>CCW</b>	= Signal increasing CCW, counterclockwise

**4 Connection**

<b>M12A5</b>	= 5-pin connector M12 axial (compatible with 4-pin connector)
<b>M12R5</b>	= 5-pin connector M12 radial (compatible with 4-pin connector)
<b>KAB2M</b>	= Cable, standard length 2 m
<b>KAB2M-DT04/3P/A*</b>	= Cable 2 m with Deutsch connector DT04, 3 pin
<b>KAB2M-DT04/3P/A-S*</b>	= Cable 2 m with Deutsch connector DT04, 3 pin, with protective tube
<b>KAB2M-DT04/4P/A</b>	= Cable 2 m with Deutsch connector DT04, 4 pin
<b>KAB2M-DT04/4P/A-S</b>	= Cable 2 m with Deutsch connector DT04, 4 pin, with protective tube

\* only for output U6

**Order example**

PRAS2 – 360 – I1 – CW – M12A5

**Accessories:**

**Connector cable (see page 157)**

**Position magnets (see from page 122)**

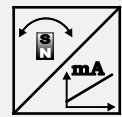
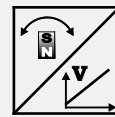
**Mounting (see page 133)**

## Analog output, redundant



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Analog output, redundant
- Flat housing – 20 mm / 25 mm thickness
- Non-contact with external position magnet, no wear
- Housing: Aluminium



### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V, redundant Voltage 0.5 ... 4.5 V, redundant Current 4 ... 20 mA, 3 wire, redundant
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Housing material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	50 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS2 – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

<b>U2R</b>	= Voltage 0.5 ... 10 V, redundant (excitation voltage 18 ... 36 V DC)
<b>U6R</b>	= Voltage 0.5 ... 4.5 V ratiometric, redundant (excitation voltage 5 V DC)
<b>U8R</b>	= Voltage 0.5 ... 4.5 V, redundant (excitation voltage 11 ... 36 V DC)
<b>I1R</b>	= Current 4... 20 mA, 3 wire, redundant (excitation voltage 18 ... 36 V DC) (output I1R possible only with CW/CCW signal characteristics)

**3 Signal characteristics**

<b>CW/CCW</b>	= Signal 1 increasing clockwise, signal 2 increasing counterclockwise
<b>CW/CW*</b>	= Signal 1 and signal 2 increasing clockwise
<b>CCW/CCW*</b>	= Signal 1 and signal 2 increasing counterclockwise

\* not available with output I1R

**4 Connection**

<b>M12A8</b>	= 8-pin connector M12 axial
<b>M12R8</b>	= 8-pin connector M12 radial
<b>KAB2M</b>	= Cable, standard length 2 m
<b>KAB2M-DT04/6P/A*</b>	= Cable 2 m with Deutsch connector DT04, 6 pin
<b>KAB2M-DT04/6P/A-S*</b>	= Cable 2 m with Deutsch connector DT04, 6 pin, with protective tube

\* only for output U6R

**Order example**

PRAS2 – 360 – U2R – CW/CCW – M12R8

**Accessories:**

**Connector cable (see page 158)**

**Position magnets (see from page 122)**

**Mounting (see page 133)**



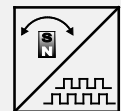
## PRDS2

### Incremental output



#### Sensor features

- **Measurement range 0 ... 360°**
- **Protection class IP67/IP69**
- **Incremental output**
- **Magnetic measurement principle**
- **Non-contact with external position magnet, no wear**
- **Housing: Aluminium**



#### Specifications

<b>Output</b>	Incremental encoder output RS422-/HTL compatible, filtered output
<b>Measurement range</b>	0 ... 360°
<b>Resolution (pulses per revolution)</b>	25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	5-pin connector M12 Cable, standard length 2 m
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	50 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS2 – 1 – 2 – 3

**1 Resolution (pulses per revolution)**

25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024

**2 Output**

**RS5VF** = RS422 compatible output with excitation 5 V DC, filtered output  
**RS24VF** = RS422 compatible output with excitation 10 ... 36 V, filtered output  
**HT24VF** = HTL compatible output with excitation 18 ... 36 V, filtered output

**3 Connection**

**M12A8** = 8-pin connector M12, axial  
**M12R8** = 8-pin connector M12, radial  
**KAB2M** = Cable, standard length 2 m

**Order example**

**PRDS2 – 1024 – RS24VF – M12A8**

**Accessories:**

**Connector cable (see page 158)**

**Position magnets (see from page 122)**

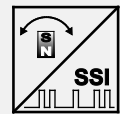
**Mounting (see page 133)**

## Digital output SSI



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Digital output SSI
- Magnetic measurement principle
- Non-contact with external position magnet, no wear
- Housing: Aluminium



### Specifications

<b>Output</b>	Synchronous serial SSI
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	12 Bit (4096 steps) per revolution
<b>Repeatability</b>	±0.1° (typical)
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	50 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS2 – 1 – 2 – 3

**1 Output**

**RSSI5V** = Synchronous serial output with excitation 5 V DC  
**RSSI24V** = Synchronous serial output with excitation 10 ... 36 V

**2 Code characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**3 Connection**

**M12A8** = 8-pin connector M12, axial  
**M12R8** = 8-pin connector M12, radial  
**KAB2M** = Cable, standard length 2 m  
**KAB2M-DT04/6P/A** = Cable 2 m with Deutsch connector DT04, 6 pin  
**KAB2M-DT04/6P/A-S** = Cable 2 m with Deutsch connector DT04, 6 pin, with protective tube

**Order example**

PRDS2 – RSSI5V – CW – M12A8

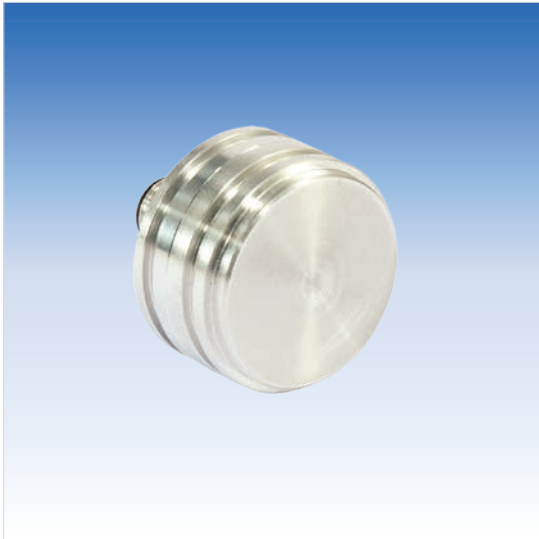
**Accessories:**

**Connector cable (see page 158)**

**Position magnets (see from page 122)**

**Mounting (see page 133)**

## Digital output CAN



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Digital output CAN
- Non-contact with external position magnet, no wear
- Housing: Aluminium
- Redundant version available



### Specifications

<b>Output</b>	CANopen (CiA 301-V4.02/406-V3.2) CAN SAE J1939
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	0.05° max.
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Housing material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	5-pin connector M12 Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	50 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS2 – 1 – 2

**1 Output**

<b>CANOP</b>	= CANopen
<b>CANJ1939</b>	= CAN SAE J1939
<b>CANOPR</b>	= CANopen, redundant
<b>CANJ1939R</b>	= CAN SAE J1939, redundant

**2 Connection**

<b>M12A5/CAN</b>	= 5-pin connector M12 axial
<b>M12R5/CAN</b>	= 5-pin connector M12 radial
<b>KAB0,3M-DT04/4P/A</b>	= Cable 0.3 m with Deutsch connector DT04, 4 pin
<b>KAB0,3M-DT04/4P/A-S</b>	= Cable 0.3 m with Deutsch connector DT04, 4 pin, with protective tube

**Order example**

PRDS2 – CANOP – M12A5/CAN

**Accessories:**

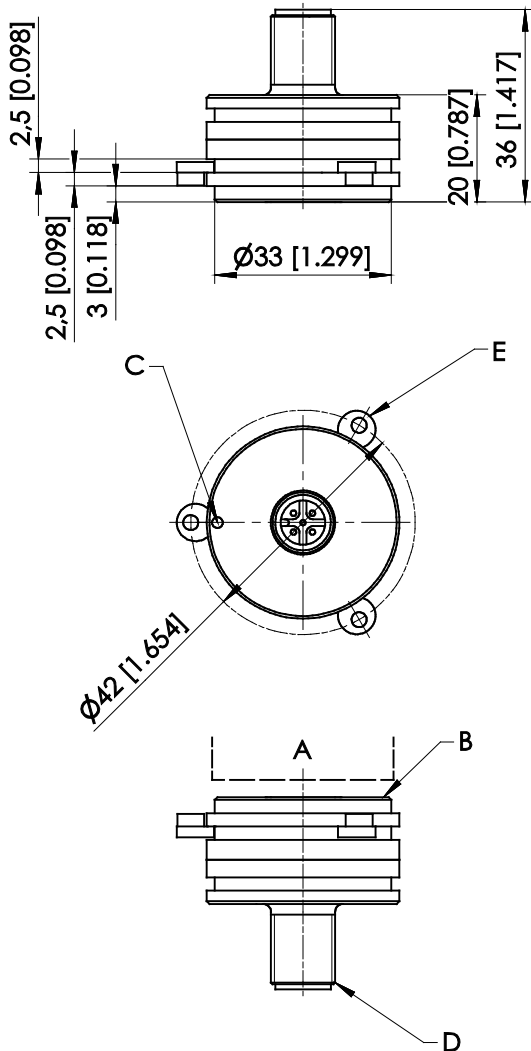
**Connector cable (see page 159)**

**Position magnets (see from page 122)**

**Mounting (see page 133)**

**Dimensions (analog and digital version)**

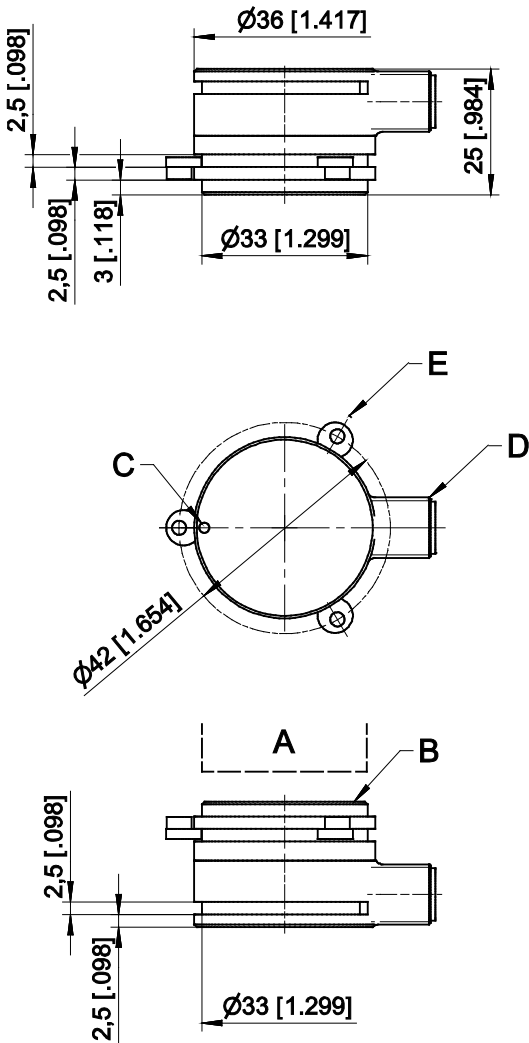
**Connector M12, axial**



- A – Position magnet
- B – Measuring area
- C – Marking
- D – Connector M12
- E – Mounting clamps PRPT-BFS1

Dimensions in mm [inch]. Weight approx. 50 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**Connector M12, radial**

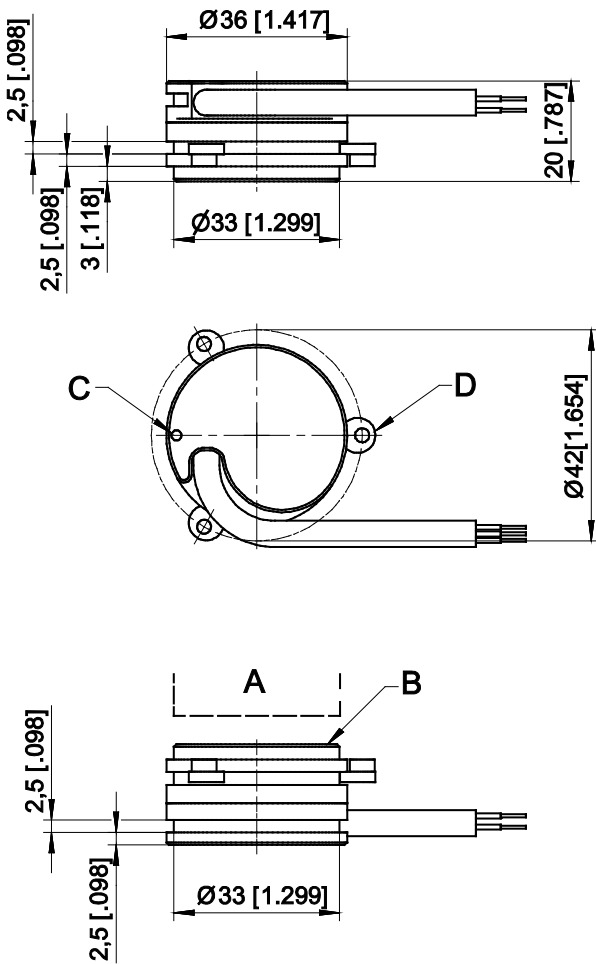


- A – Position magnet
- B – Measuring area
- C – Marking
- D – Connector M12

Dimensions in mm [inch]. Weight approx. 50 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.



**Cable output**




- A – Position magnet
- B – Measuring area
- C – Marking
- D – Mounting clamps PRPT-BFS1

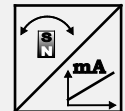
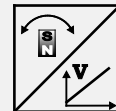
Dimensions in mm [inch]. Weight without cable approx. 40 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**PRAS2EX**  
**Analog output**



**Sensor features**

- Measurement range 0 ... 360°
- Protection class IP65
- Analog output
- Non-contact with external position magnet
-  II 3D Ex tc IIC T80°C Dc X (X = examined with low impact energy of 4J)



**Specifications**

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V, ratiometric Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP65
<b>Housing material</b>	Stainless steel
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	5-pin connector M12 (compatible to 4-pin connector)
<b>Temperature range</b>	-20 ... +40°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	180 g approx.
<b>EMC</b>	DIN EN 61326-1:2013
<b>Dust-EX proof</b>	DIN EN 60079-0 (June 2014), DIN EN 60079-31 (December 2014)

**Order code**

PRAS2EX – 1 – 2 – 3 – 4

**1 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**2 Output**

**U2** = Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)  
**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
**I1** = Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)

**3 Signal characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**4 Connection**

**M12A5** = 5-pin connector M12 axial (compatible with 4-pin connector)  
**M12R5** = 5-pin connector M12 radial (compatible with 4-pin connector)

**Order example**

PRAS2EX – 360 – I1 – CW – M12A5

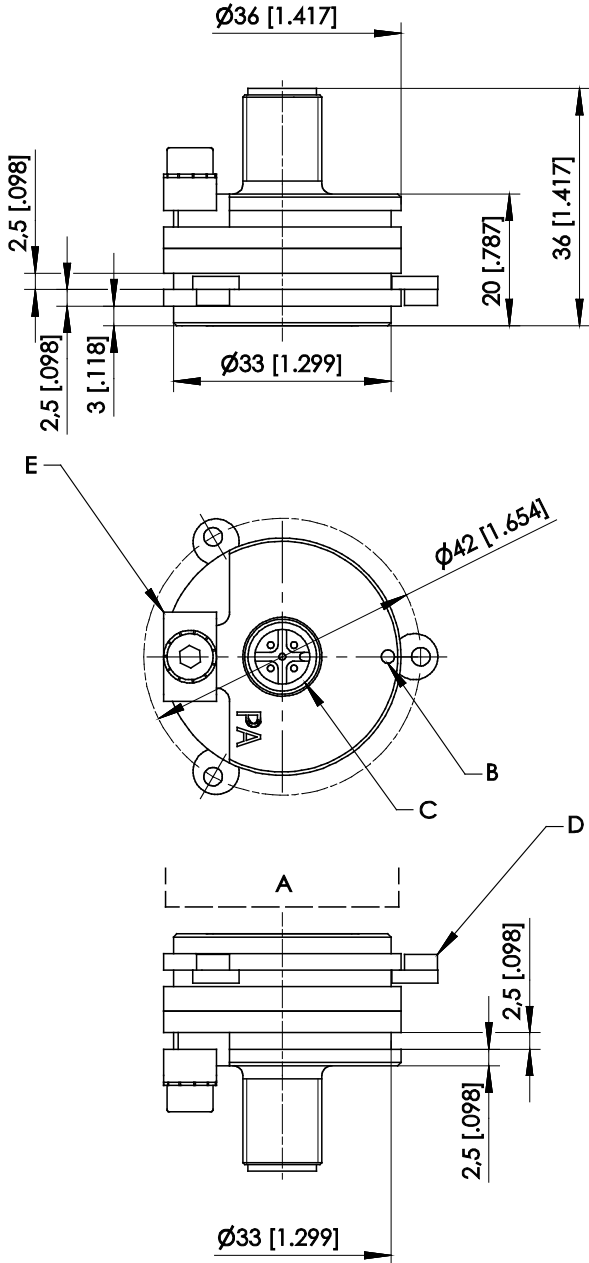
**Accessories:**

**Position magnets (see from page 122)**

**Mounting (see from page 133)**

**Dimensions**

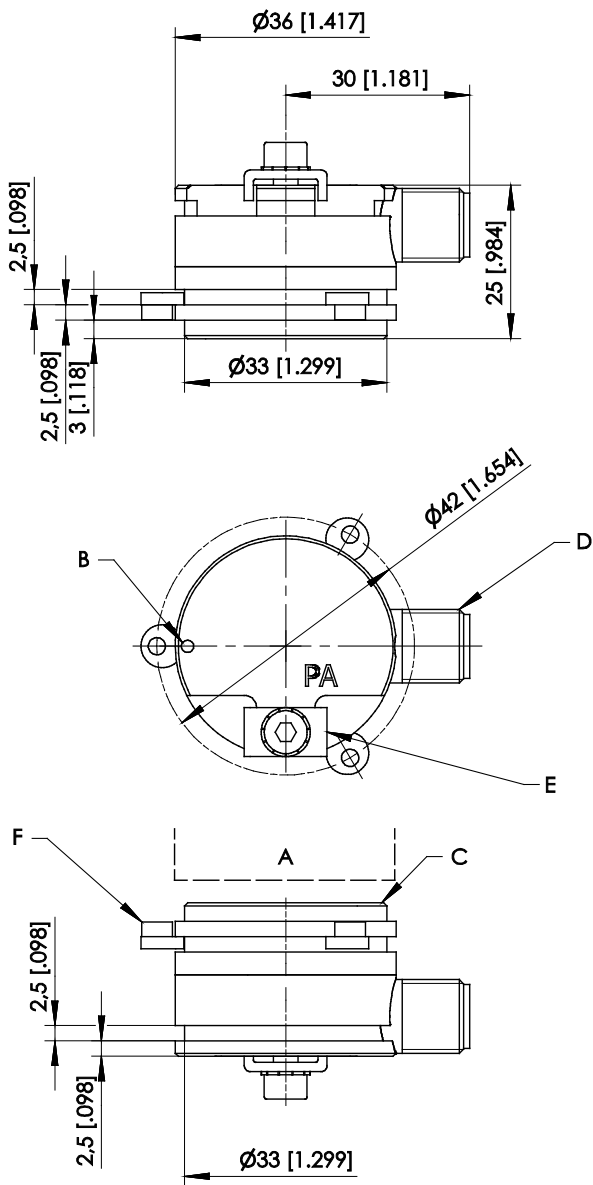
**Connector M12, axial**



- A – Position magnet
- B – Marking
- C – Connector M12
- D – Mounting clamps PRPT-BFS1
- E – Earthing

Dimensions in mm [inch]. Weight approx. 180 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**Connector M12, radial**



- A – Position magnet
- B – Marking
- C – Measuring area
- D – Connector M12
- E – Earthing
- F – Mounting clamps PRPT-BFS1

Dimensions in mm [inch]. Weight approx. 180 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

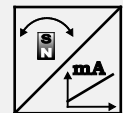
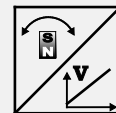
## PRAS3

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Analog output
- Magnetic measurement principle
- With 10 mm shaft or 6 mm hollow shaft
- Housing: Aluminium



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Housing material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	5-pin connector M12 (compatible to 4-pin connector) Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Life cycle of bearings</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (mech.)</b>	10.000 r.p.m.
<b>Allowable shaft load</b>	100 N radial / 100 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	250 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS3 – 1 – 2 – 3 – 4 – 5

**1 Shaft**

**V** = 10 mm shaft  
**H** = 6 mm hollow shaft

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

**U2** = Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)  
**U2B** = Voltage 0.5 ... 10 V (excitation voltage 11.5 ... 27 V DC)  
**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
**U8** = Voltage 0.5 ... 4.5 V (excitation voltage 11 ... 36 V DC)  
**I1** = Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)  
**I1B** = Current 4 ... 20 mA, 3 wire (excitation voltage 10 ... 27 V DC)

**4 Signal characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**5 Connection**

**M12A5** = 5-pin connector M12 axial (compatible with 4-pin connector)  
**M12R5** = 5-pin connector M12 radial (compatible with 4-pin connector)  
**KAB2M** = Cable, standard length 2 m  
**KAB2M-DT04/3P/A\*** = Cable 2 m with Deutsch connector DT04, 3 pin  
**KAB2M-DT04/3P/A-S\*** = Cable 2 m with Deutsch connector DT04, 3 pin, with protective tube  
**KAB2M-DT04/4P/A** = Cable 2 m with Deutsch connector DT04, 4 pin  
**KAB2M-DT04/4P/A-S** = Cable 2 m with Deutsch connector DT04, 4 pin, with protective tube

\* only for output U6

**Order example**

PRAS3 – V – 360 – I1 – CW – M12A5

**Accessories:**

**Connector cable (see page 157)**

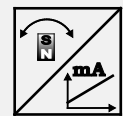
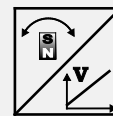
**Mounting plates (see page 133)**

## Analog output, redundant



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Analog output, redundant
- Magnetic measurement principle
- With 10 mm shaft or 6 mm hollow shaft
- Housing: Aluminium



### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V, redundant Voltage 0.5 ... 4.5 V, redundant Current 4 ... 20 mA, 3 wire, redundant
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Signal characteristics</b>	CW, CCW
<b>Housing material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Life cycle of bearings</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (mech.)</b>	10.000 r.p.m.
<b>Allowable shaft load</b>	100 N radial / 100 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	250 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013



**Order code**

PRAS3 – 1 – 2 – 3 – 4 – 5

**1 Shaft**

V = 10 mm shaft  
 H = 6 mm hollow shaft

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

U2R = Voltage 0.5 ... 10 V, redundant (excitation voltage 18 ... 36 V DC)  
 U6R = Voltage 0.5 ... 4.5 V ratiometric, redundant (excitation voltage 5 V DC)  
 U8R = Voltage 0.5 ... 4.5 V, redundant (excitation voltage 11 ... 36 V DC)  
 I1R = Current 4... 20 mA, 3 wire, redundant (excitation voltage 18 ... 36 V DC)  
 (output I1R possible only with CW/CCW signal characteristics)

**4 Signal characteristics**

CW/CCW = Signal 1 increasing clockwise, signal 2 increasing counterclockwise  
 CW/CW\* = Signal 1 and signal 2 increasing clockwise  
 CCW/CCW\* = Signal 1 and signal 2 increasing counterclockwise

\* not available with output I1R

**5 Connection**

M12A8 = 8-pin connector M12 axial  
 M12R8 = 8-pin connector M12 radial  
 KAB2M = Cable, standard length 2 m  
 KAB2M-DT04/6P/A\* = Cable 2 m with Deutsch connector DT04, 6 pin  
 KAB2M-DT04/6P/A-S\* = Cable 2 m with Deutsch connector DT04, 6 pin, with protective tube

\* only for output U6R

**Order example**

PRAS3 – V – 360 – U2R – CW/CCW – M12R8

**Accessories:**

**Connector cable (see page 158)**

**Mounting plates (see page 133)**

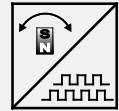
## PRDS3

### Incremental output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Incremental output
- Magnetic measurement principle
- With 10 mm shaft or 6 mm hollow shaft
- Housing: Aluminium



#### Specifications

<b>Output</b>	Incremental encoder output RS422-/HTL compatible, filtered output
<b>Measurement range</b>	0 ... 360°
<b>Resolution (pulses per revolution)</b>	25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024
<b>Linearity</b>	±1% (typical)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Housing material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	5-pin connector M12 Cable, standard length 2 m
<b>Temperature range</b>	-40 ... +85°C
<b>Life cycle of bearings</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (mech.)</b>	10.000 r.p.m.
<b>Allowable shaft load</b>	100 N radial / 100 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	250 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS3 – 1 – 2 – 3 – 4

**1 Shaft**

V = Shaft 10 mm  
H = Hollow shaft 6 mm

**2 Resolution (pulses per revolution)**

25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024

**3 Output**

RS5VF = RS422 compatible output with excitation 5 V DC, filtered output  
RS24VF = RS422 compatible output with excitation 10 ... 36 V, filtered output  
HT24VF = HTL compatible output with excitation 18 ... 36 V, filtered output

**4 Connection**

M12A8 = 8-pin connector M12, axial  
M12R8 = 8-pin connector M12, radial  
KAB2M = Cable, standard length 2 m

**Order example**

**PRDS3 – V – 1024 – HT24VF – M12R8**

**Accessories:**

**Connector cable (see page 158)**

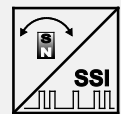
**Mounting plates (see page 133)**

## Digital output SSI



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Digital output SSI
- Magnetic measurement principle
- With 10 mm shaft or 6 mm hollow shaft
- Housing: Aluminium



### Specifications

<b>Output</b>	Synchronous serial SSI
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	12 Bit (4096 steps) per revolution
<b>Repeatability</b>	±0.1° (typical)
<b>Linearity</b>	±1% (typical)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Life cycle of bearings</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (mech.)</b>	10.000 r.p.m.
<b>Allowable shaft load</b>	100 N radial / 100 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	250 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS3 – 1 – 2 – 3 – 4

**1 Shaft**

V = Shaft 10 mm  
 H = Hollow shaft 6 mm

**2 Output**

RSSI5V = Synchronous serial output with excitation 5 V DC  
 RSSI24V = Synchronous serial output with excitation 10 ... 36 V

**3 Code characteristics**

CW = Signal increasing CW, clockwise  
 CCW = Signal increasing CCW, counterclockwise

**4 Connection**

M12A8 = 8-pin connector M12, axial  
 M12R8 = 8-pin connector M12, radial  
 KAB2M = Cable, standard length 2 m  
 KAB2M-DT04/6P/A = Cable 2 m with Deutsch connector DT04, 6 pin  
 KAB2M-DT04/6P/A-S = Cable 2 m with Deutsch connector DT04, 6 pin, with protective tube

**Order example**

PRDS3 – V – RSSI24V – CW – M12R8

**Accessories:**

**Connector cable (see page 158)**

**Mounting plates (see page 133)**

## Digital output CAN



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Digital output CAN
- With 10 mm shaft or 6 mm hollow shaft
- Housing: Aluminium
- Redundant version available



### Specifications

<b>Output</b>	CANopen (CiA 301-V4.02/406-V3.2) CAN SAE J1939
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	0.05° max.
<b>Linearity</b>	±1% (typical)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable) IP67 (cable output)
<b>Material</b>	Aluminium
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	5-pin connector M12 Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Life cycle of bearings</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (mech.)</b>	10.000 r.p.m.
<b>Allowable shaft load</b>	100 N radial / 100 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	250 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**PRDS3 – 1 – 2 – 3**1 Shaft**

V = Shaft 10 mm  
H = Hollow shaft 6 mm

**2 Output**

CANOP = CANopen  
CANJ1939 = CAN SAE J1939  
CANOPR = CANopen, redundant  
CANJ1939R = CAN SAE J1939, redundant

**3 Connection**

M12A5/CAN = 5-pin connector M12 axial  
M12R5/CAN = 5-pin connector M12 radial  
KAB0,3M-DT04/4P/A = Cable 0.3 m with Deutsch connector DT04, 4 pin  
KAB0,3M-DT04/4P/A-S = Cable 0.3 m with Deutsch connector DT04, 4 pin, with protective tube

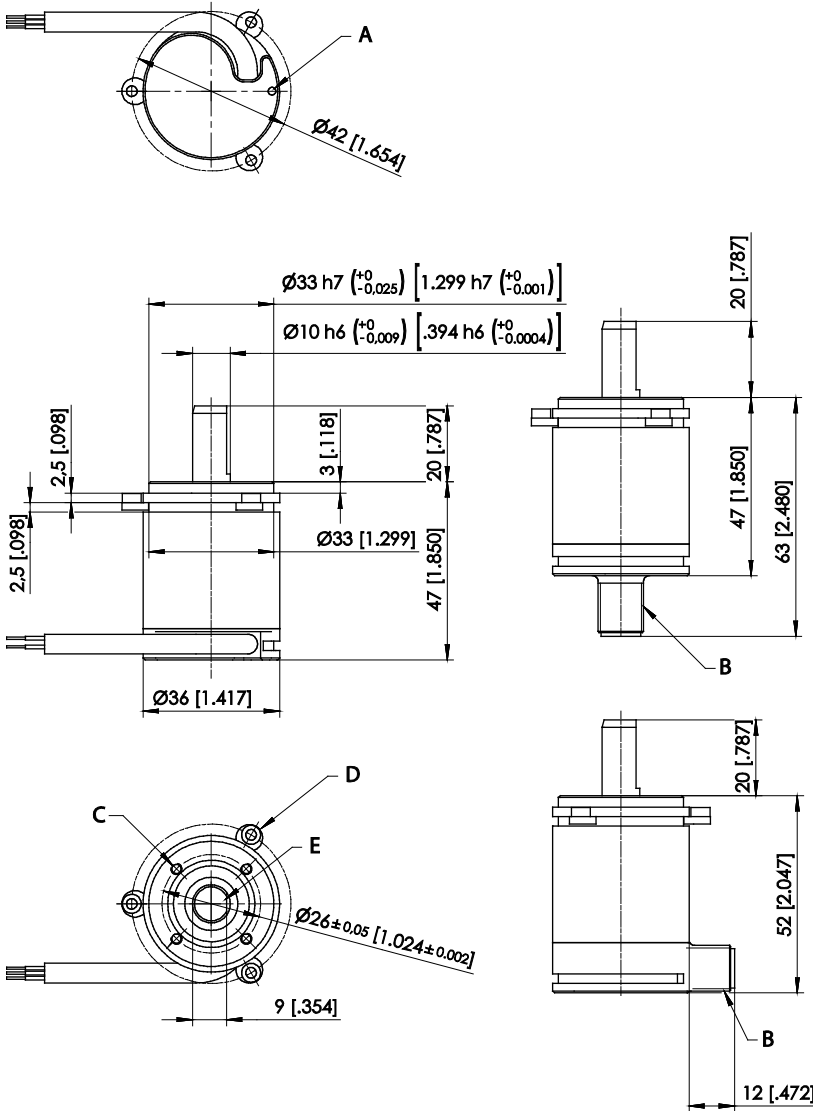
**Order example**

**PRDS3 – V – CANOP – M12A5/CAN**

**Accessories:****Connector cable (see page 159)****Mounting plates (see page 133)**

**Dimensions (analog and digital version)**

**Version with shaft**

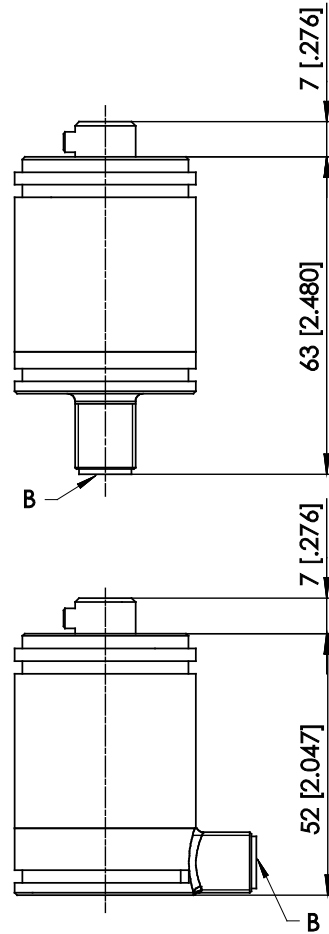
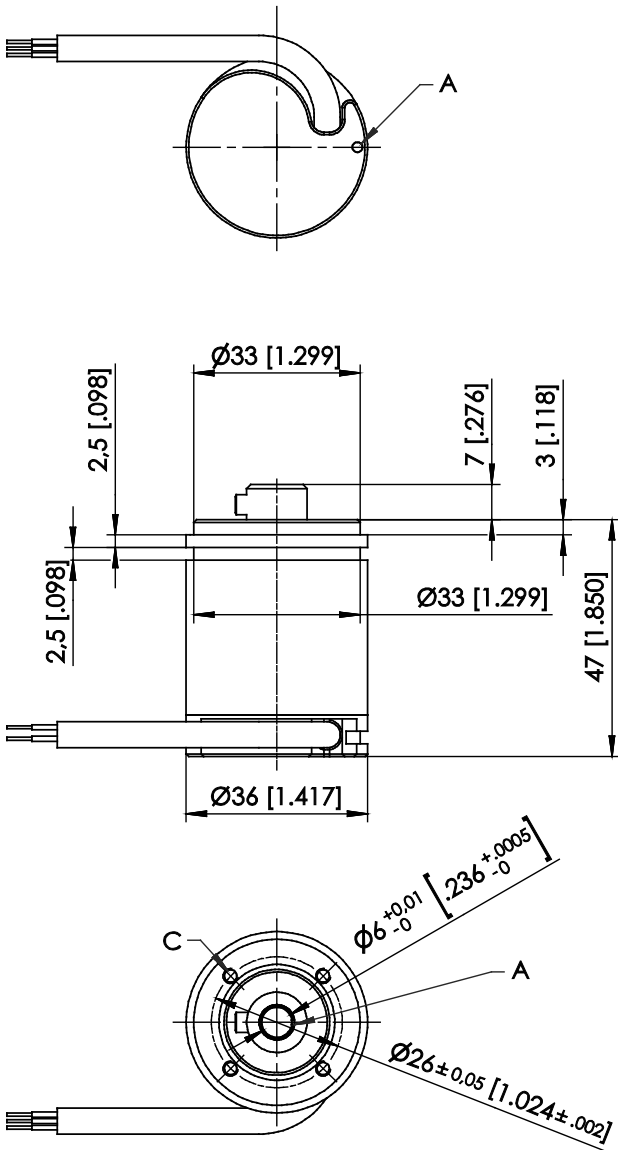


- A – Marking
- B – Connector M12
- C – 4x M3 – 5 [.197] deep  
screw hole orientation to marking not defined!
- D - Mounting clamps PRPT-BFS1
- E - Flat

Dimensions in mm [inch].  
Weight approx. 250 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.



**Version with hollow shaft**




- A – Marking
- B – Connector M12
- C – 4x M3 – 5 [.197] deep  
screw hole orientation to marking not defined!

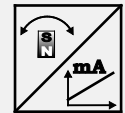
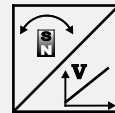
Dimensions in mm [inch].  
Weight approx. 250 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**PRAS3EX**  
**Analog output**



**Sensor features**

- Measurement range 0 ... 360°
- Protection class IP65
- Analog output
- With 10 mm shaft or 6 mm hollow shaft
-  II 3D Ex tc IIIC T80°C Dc X (X = examined with low impact energy of 4J)



**Specifications**

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V, ratiometric Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Protection class</b>	IP65
<b>Housing material</b>	Stainless steel
<b>Mounting</b>	Clamps, mounting plate
<b>Connection</b>	5-pin connector M12 (compatible with 4-pin connector)
<b>Temperature range</b>	-20 ... +40°C
<b>Life cycle of bearings</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (mech.)</b>	1000 r.p.m.
<b>Allowable shaft load</b>	100 N radial / 100 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	330 g approx.
<b>EMC</b>	DIN EN 61326-1:2013
<b>Dust-EX proof</b>	DIN EN 60079-0 (June 2014), DIN EN 60079-31 (December 2014)

**Order code**

PRAS3EX – 1 – 2 – 3 – 4 – 5

**1 Shaft**

V = 10 mm shaft  
H = 6 mm hollow shaft

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

U2 = Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)  
U6 = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
I1 = Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)

**4 Signal characteristics**

CW = Signal increasing CW, clockwise  
CCW = Signal increasing CCW, counterclockwise

**5 Connection**

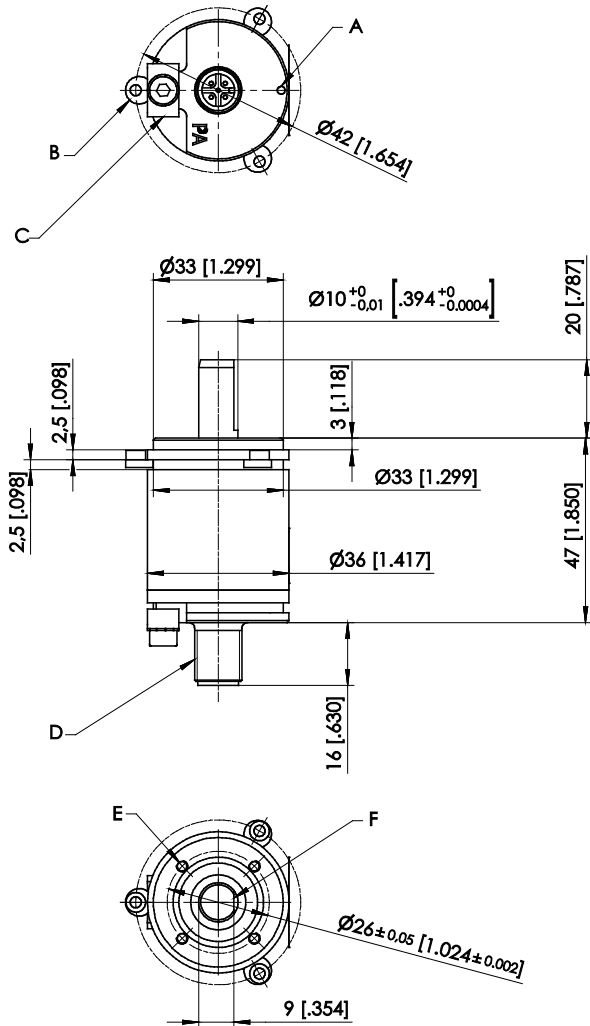
M12A5 = 5-pin connector M12 axial (compatible with 4-pin connector)  
M12R5 = 5-pin connector M12 radial (compatible with 4-pin connector)

**Order example**

PRAS3EX – V – 360 – I1 – CW – M12A5

**Dimensions**

**Connector M12, axial**



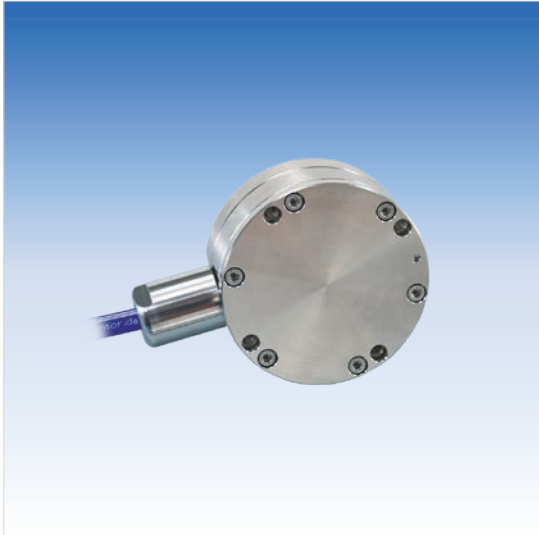
- A – Marking
- B – Mounting clamps PRTP-BFS1
- C – Earthing
- D – Connector M12
- E – 4x M3 – 5 [.197] deep,  
screw hole orientation to marking not defined!!
- F – Flat

Dimensions in mm [inch]. Weight approx. 290 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.



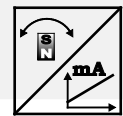
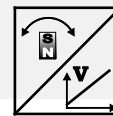
## PRAS4

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP68 (10 bar)
- Analog output
- Subaqueous version up to 100 m depth, continuous use
- Non-contact with external position magnet, no wear
- Housing: Stainless steel 1.4404



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V, ratiometric Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°) f.s.
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°) f.s.
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP68 (10 bar, up to 100m, continuous operation)
<b>Housing material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	Cable, standard length 2 m
<b>Temperature range</b>	-20 ... +85°C (up to +30°C immersed in sea water)
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	1250 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

**PRAS4**    –    1    –    2    –    3    –    4    –    5    –    6    –    7

**1 Mechanical connection**

**K**                      = Non-contact with external position magnet

**2 Measurement range (0 ... 15° up to 0 ... 360°, in increments of 15°)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

**U2**                      = Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)  
**U6**                      = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
**I1**                        = Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)

**4 Signal characteristics**

**CW**                     = Signal increasing CW, clockwise  
**CCW**                    = Signal increasing CCW, counterclockwise

**5 Connection**

**KAB2M**                = Cable, standard length 2 m

**6 Housing material**

**VA**                      = 1.4404 / screws A4

**7 Pressure resistance**

**WP**                     = 10 bar

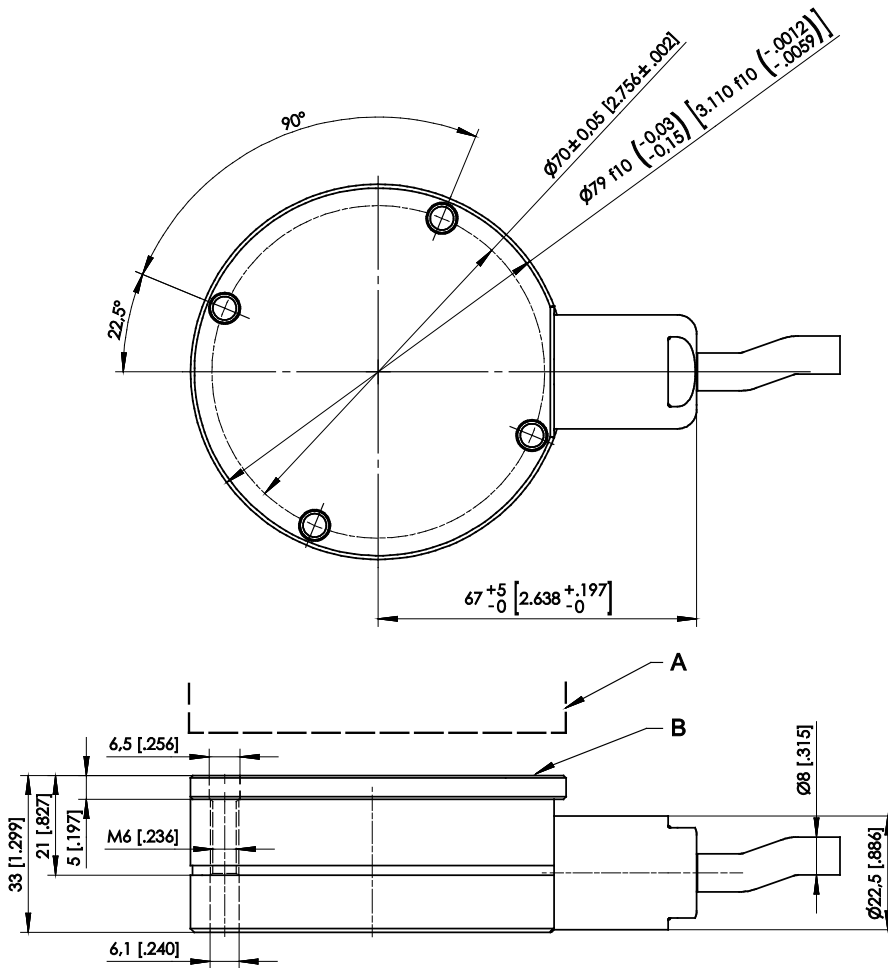
**Order example**

**PRAS4 – K – 360 – I1 – CW – KAB2M – VA – WP**

**Accessories:**

**Position magnets (see from page 122)**

**Dimensions**



A – Position magnet  
B – Marking

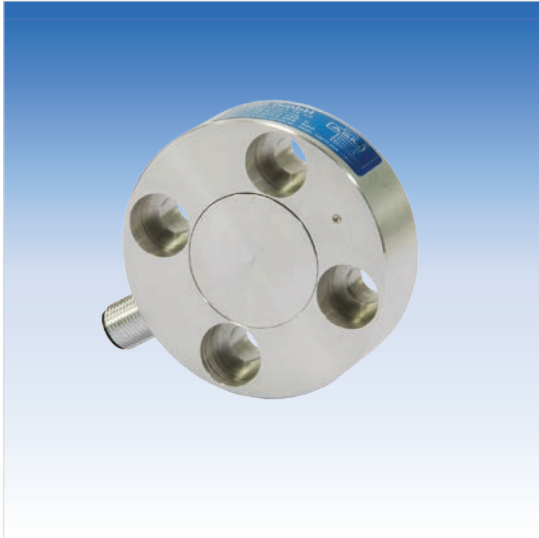
IP68 / 100 m, continuous use.

Dimensions in mm [inch]. Weight without cable approx. 1250 g.  
Dimensions informative only.  
For guaranteed dimensions please consult factory.



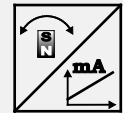
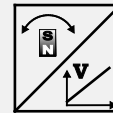
## PRAS5

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69, IP68 optional
- Analog output
- Magnetic measurement principle
- With 10 mm shaft or non-contact
- Housing: Stainless steel 1.4404



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet (only version K)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Housing material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M8
<b>Connection</b>	5-pin connector M12 (compatible to 4-pin connector) Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Life cycle of bearings (shaft version)</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (shaft version)</b>	10.000 r.p.m.
<b>Allowable shaft load (shaft version)</b>	120 N radial / 120 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx., 890 g approx. with shaft (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS5 – 1 – 2 – 3 – 4 – 5 – 6

**1 Mechanical connection**

**V** = Shaft 10 mm  
**K** = Non-contact with external magnet

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

**U2** = Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)  
**U2B** = Voltage 0.5 ... 10 V (excitation voltage 11.5 ... 27 V DC)  
**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
**U8** = Voltage 0.5 ... 4.5 V (excitation voltage 11 ... 36 V DC)  
**I1** = Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)  
**I1B** = Current 4 ... 20 mA, 3 wire (excitation voltage 10 ... 27 V DC)

**4 Signal characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**5 Connection**

**M12A5** = 5-pin connector M12 axial (compatible with 4-pin connector)  
**M12R5** = 5-pin connector M12 radial (compatible with 4-pin connector)  
**KAB2M** = Cable, standard length 2 m  
**KAB2M-DT04/3P/A\*** = Cable 2 m with Deutsch connector DT04, 3 pin  
**KAB2M-DT04/3P/A-S\*** = Cable 2 m with Deutsch connector DT04, 3 pin, with protective tube  
**KAB2M-DT04/4P/A** = Cable 2 m with Deutsch connector DT04, 4 pin  
**KAB2M-DT04/4P/A-S** = Cable 2 m with Deutsch connector DT04, 4 pin, with protective tube

\* only for output U6

**6 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

**PRAS5 – V – 360 – I1 – CW – M12A5 – VA**

**Accessories:**

**Connector cable (see page 157)**

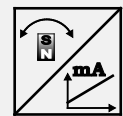
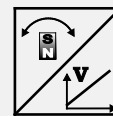
**Position magnets (see from page 122)**

## Analog output, redundant



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69, IP68 optional
- Analog output, redundant
- Magnetic measurement principle
- With 10 mm shaft or non-contact
- Housing: Stainless steel 1.4404



### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V, redundant Voltage 0.5 ... 4.5 V, redundant Current 4 ... 20 mA, 3 wire, redundant
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet (only version K)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Housing material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M8
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Life cycle of bearings (shaft version)</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (shaft version)</b>	10.000 r.p.m.
<b>Allowable shaft load</b>	120 N radial / 120 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx., 890 g approx. with shaft (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS5 – 1 – 2 – 3 – 4 – 5 – 6

**1 Mechanical connection**

V = Shaft 10 mm  
K = Non-contact with external magnet

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

U2R = Voltage 0.5 ... 10 V, redundant (excitation voltage 18 ... 36 V DC)  
U6R = Voltage 0.5 ... 4.5 V ratiometric, redundant (excitation voltage 5 V DC)  
U8R = Voltage 0.5 ... 4.5 V, redundant (excitation voltage 11 ... 36 V DC)  
I1R = Current 4... 20 mA, 3 wire, redundant (excitation voltage 18 ... 36 V DC)  
(output I1R possible only with CW/CCW signal characteristics)

**4 Signal characteristics**

CW/CCW = Signal 1 increasing clockwise, signal 2 increasing counterclockwise  
CW/CW\* = Signal 1 and signal 2 increasing clockwise  
CCW/CCW\* = Signal 1 and signal 2 increasing counterclockwise

\* not available with output I1R

**5 Connection**

M12A8 = 8-pin connector M12 axial  
M12R8 = 8-pin connector M12 radial  
KAB2M = Cable, standard length 2 m  
KAB2M-DT04/6P/A\* = Cable 2 m with Deutsch connector DT04, 6 pin  
KAB2M-DT04/6P/A-S\* = Cable 2 m with Deutsch connector DT04, 6 pin, with protective tube  
KAB2M-DT04/8P/A = Cable 2 m with Deutsch connector DT04, 8 pin  
KAB2M-DT04/8P/A-S = Cable 2 m with Deutsch connector DT04, 8 pin, with protective tube

\* only for output U6R

**6 Housing material**

VA = Stainless steel 1.4404

**Order example**

PRAS5 – V – 360 – U2R – CW/CCW – M12R8 – VA

**Accessories:**

**Connector cable (see page 158)**

**Position magnets (see from page 122)**

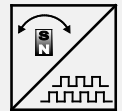
## PRDS5

### Incremental output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69, IP68 optional
- Incremental output
- Magnetic measurement principle
- With 10 mm shaft or non-contact with external magnet
- Housing: Stainless steel 1.4404



#### Specifications

<b>Output</b>	Incremental encoder output RS422-/HTL compatible, filtered output
<b>Measurement range</b>	0 ... 360°
<b>Resolution (pulses per revolution)</b>	25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet (only version K)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M8
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Life cycle of bearings (shaft version)</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (shaft version)</b>	10.000 r.p.m.
<b>Allowable shaft load</b>	120 N radial / 120 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx., 890 g approx. with shaft (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

Order code

PRDS5 – 1 – 2 – 3 – 4 – 5

**1 Mechanical connection**

V = Shaft 10 mm  
K = Non-contact with external magnet

**2 Resolution**

25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024

**3 Output**

RS5VF = RS422 compatible output with excitation 5 V DC, filtered output  
RS24VF = RS422 compatible output with excitation 10 ... 36 V, filtered output  
HT24VF = HTL compatible output with excitation 18 ... 36 V, filtered output

**4 Connection**

M12A8 = 8-pin connector M12, axial  
M12R8 = 8-pin connector M12, radial  
KAB2M = Cable, standard length 2 m  
KAB2M-DT04/8P/A = Cable 2 m with Deutsch connector DT04, 8 pin  
KAB2M-DT04/8P/A-S = Cable 2 m with Deutsch connector DT04, 8 pin, with protective tube

**5 Housing material**

VA = Stainless steel 1.4404

Order example

PRDS5 – V – 1024 – RS24VF – M12A8 – VA

Accessories:

Connector cable (see page 158)

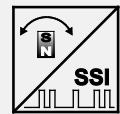
Position magnets (see from page 122)

## Digital output SSI



### Sensor features

- **Measurement range 0 ... 360°**
- **Protection class IP67/IP69, IP68 optional**
- **Digital output SSI**
- **Magnetic measurement principle**
- **With 10 mm shaft or non-contact with external magnet**
- **Housing: Stainless steel 1.4404**



### Specifications

<b>Output</b>	Synchronous serial SSI
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	12 Bit (4096 steps) per revolution
<b>Repeatability</b>	±0.1° (typical)
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet (only version K)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M8
<b>Temperature range</b>	-40 ... +85°C
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Life cycle of bearings (shaft version)</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (shaft version)</b>	10.000 r.p.m.
<b>Allowable shaft load</b>	120 N radial / 120 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx., 890 g approx. with shaft (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS5 – 1 – 2 – 3 – 4 – 5

**1 Mechanical connection**

V = Shaft 10 mm  
K = Non-contact with external magnet

**2 Output**

RSSI5V = Synchronous serial output with excitation 5 V DC  
RSSI24V = Synchronous serial output with excitation 10 ... 36 V

**3 Code characteristics**

CW = Signal increasing CW, clockwise  
CCW = Signal increasing CCW, counterclockwise

**4 Connection**

M12A8 = 8-pin connector M12, axial  
M12R8 = 8-pin connector M12, radial  
KAB2M = Cable, standard length 2 m  
KAB2M-DT04/6P/A = Cable 2 m with Deutsch connector DT04, 6 pin  
KAB2M-DT04/6P/A-S = Cable 2 m with Deutsch connector DT04, 6 pin, with protective tube

**5 Housing material**

VA = Stainless steel 1.4404

**Order example**

PRDS5 – K – RSSI24V – CW – M12A8 – VA

**Accessories:**

**Connector cable (see page 158)**

**Position magnets (see from page 122)**



## Digital output CAN



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69, IP68 optional
- Digital output CAN
- With 10 mm shaft or non-contact with external magnet
- Housing: Stainless steel 1.4404
- Redundant version available



### Specifications

<b>Output</b>	CANopen (CiA 301-V4.02/406-V3.2) CAN SAE J1939
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	0.05° max.
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet (only version K)
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M8
<b>Connection</b>	5-pin connector M12 Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Life cycle of bearings (shaft version)</b>	100 x 10 <sup>6</sup> revolutions (<1500 r.p.m.)
<b>Revolutions per minute (shaft version)</b>	10.000 r.p.m.
<b>Allowable shaft load</b>	120 N radial / 120 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx., 890 g approx. with shaft (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS5 – 1 – 2 – 3 – 4

**1 Shaft**

V = Shaft 10 mm  
K = Non-contact with external magnet

**2 Output**

CANOP = CANopen  
CANJ1939 = CAN SAE J1939  
CANOPR = CANopen, redundant  
CANJ1939R = CAN SAE J1939, redundant

**3 Connection**

M12A5/CAN = 5-pin connector M12 axial  
M12R5/CAN = 5-pin connector M12 radial  
KAB0,3M-DT04/4P/A = Cable 0.3 m with Deutsch connector DT04, 4 pin  
KAB0,3M-DT04/4P/A-S = Cable 0.3 m with Deutsch connector DT04, 4 pin, with protective tube

**4 Housing material**

VA = Stainless steel 1.4404

**Order example**

PRDS5 – V – CANOP – M12A5/CAN – VA

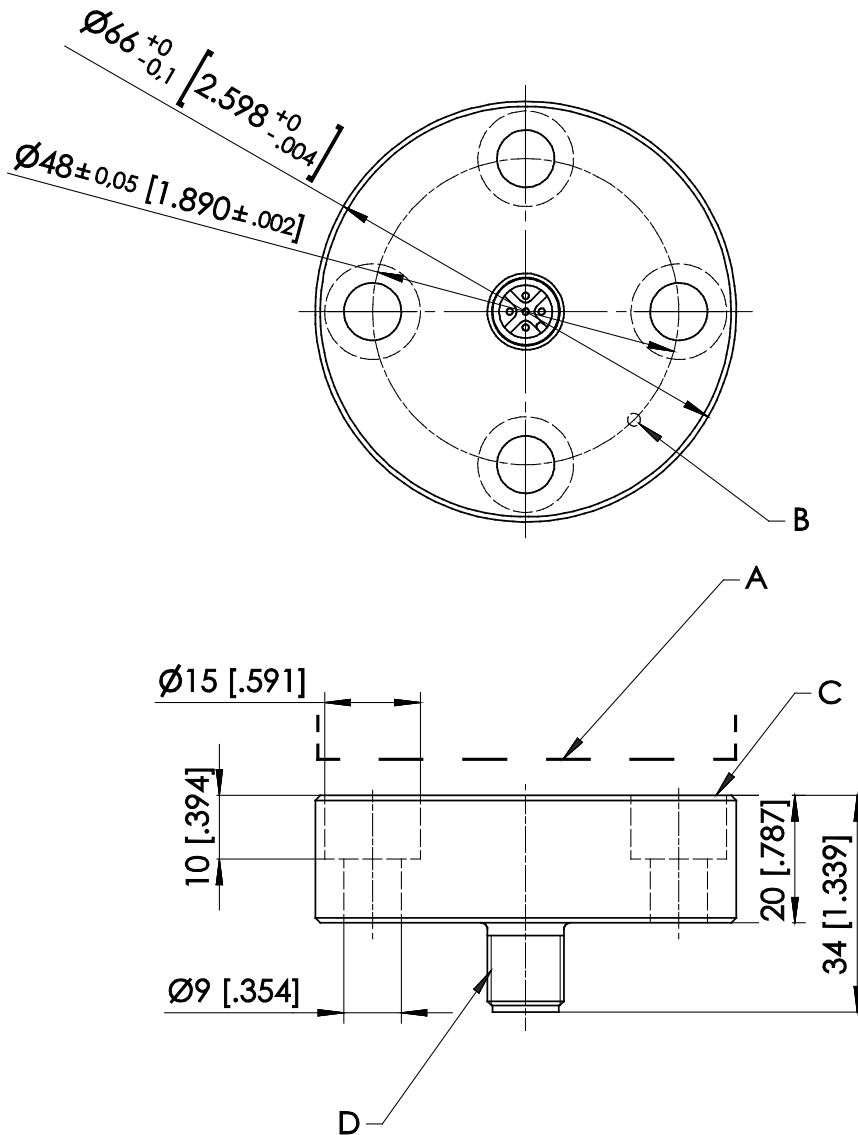
**Accessories:**

**Connector cable (see page 159)**

**Position magnets (see from page 122)**

**Dimensions (analog and digital version)**

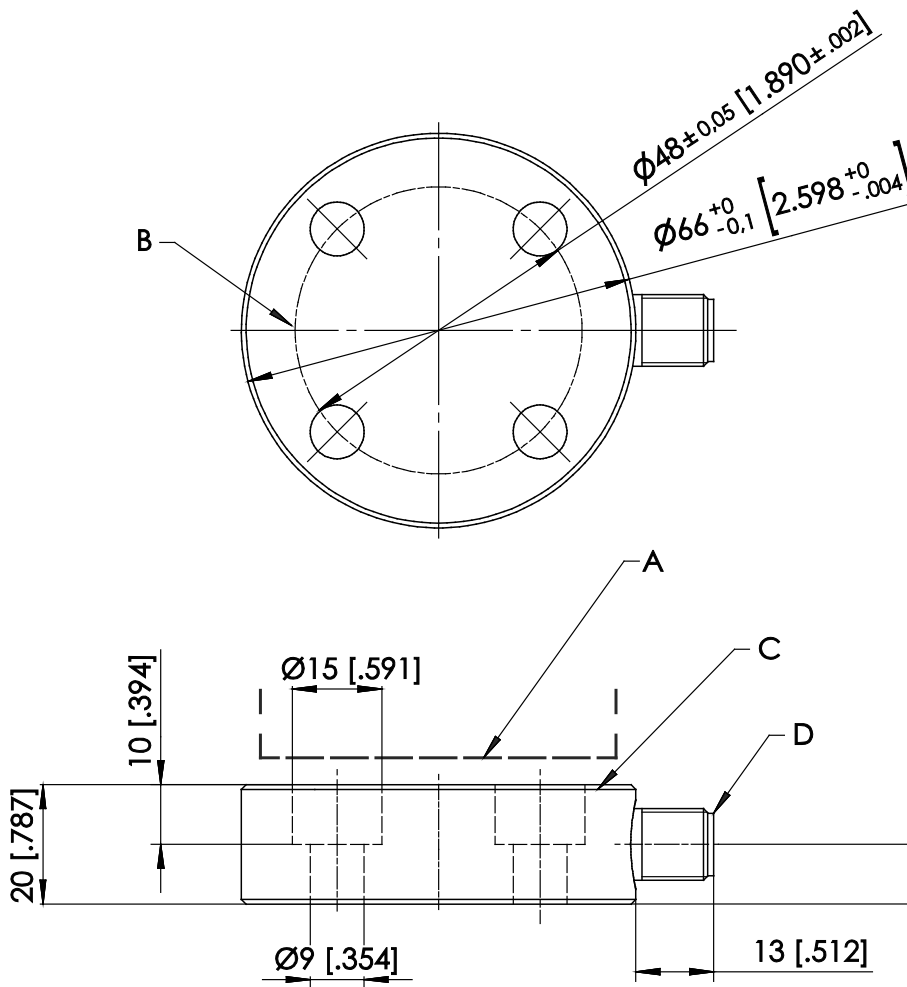
Contactless, connector M12, axial



- A – Position magnet
- B – Marking
- C – Measuring area
- D – Connector M12

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

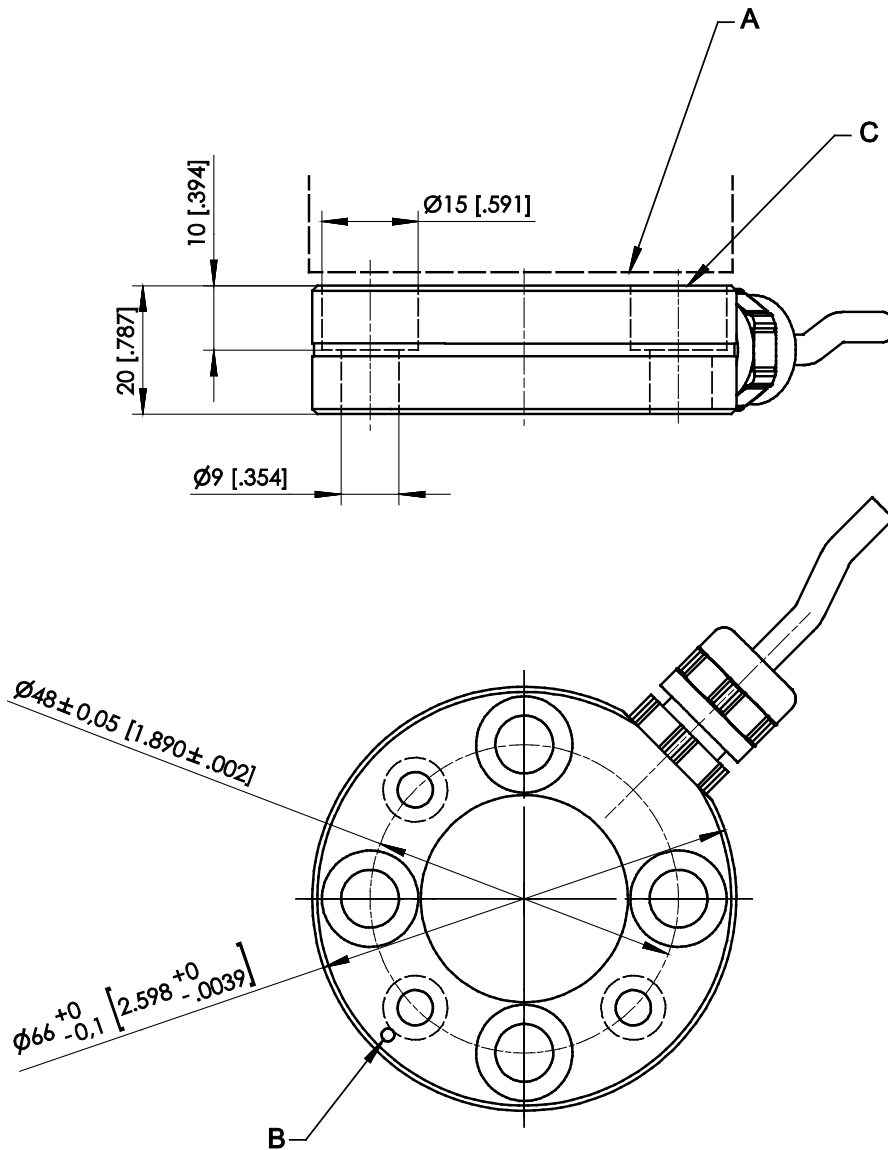
Contactless, connector M12, radial



- A – Position magnet
- B – Marking
- C – Measuring area
- D – Connector M12

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

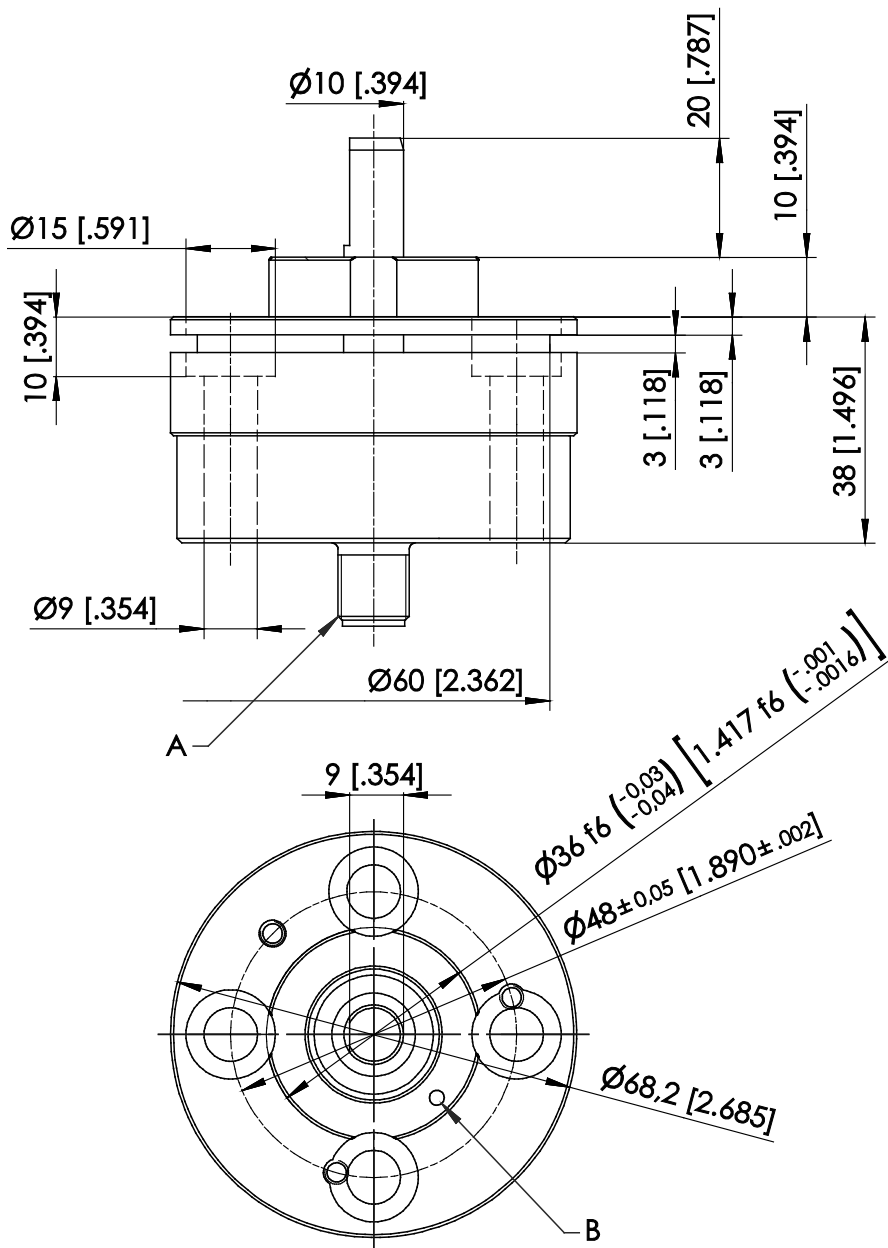
**Cable version, contactless**



- A – Position magnet
- B – Marking
- C – Measurement area

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

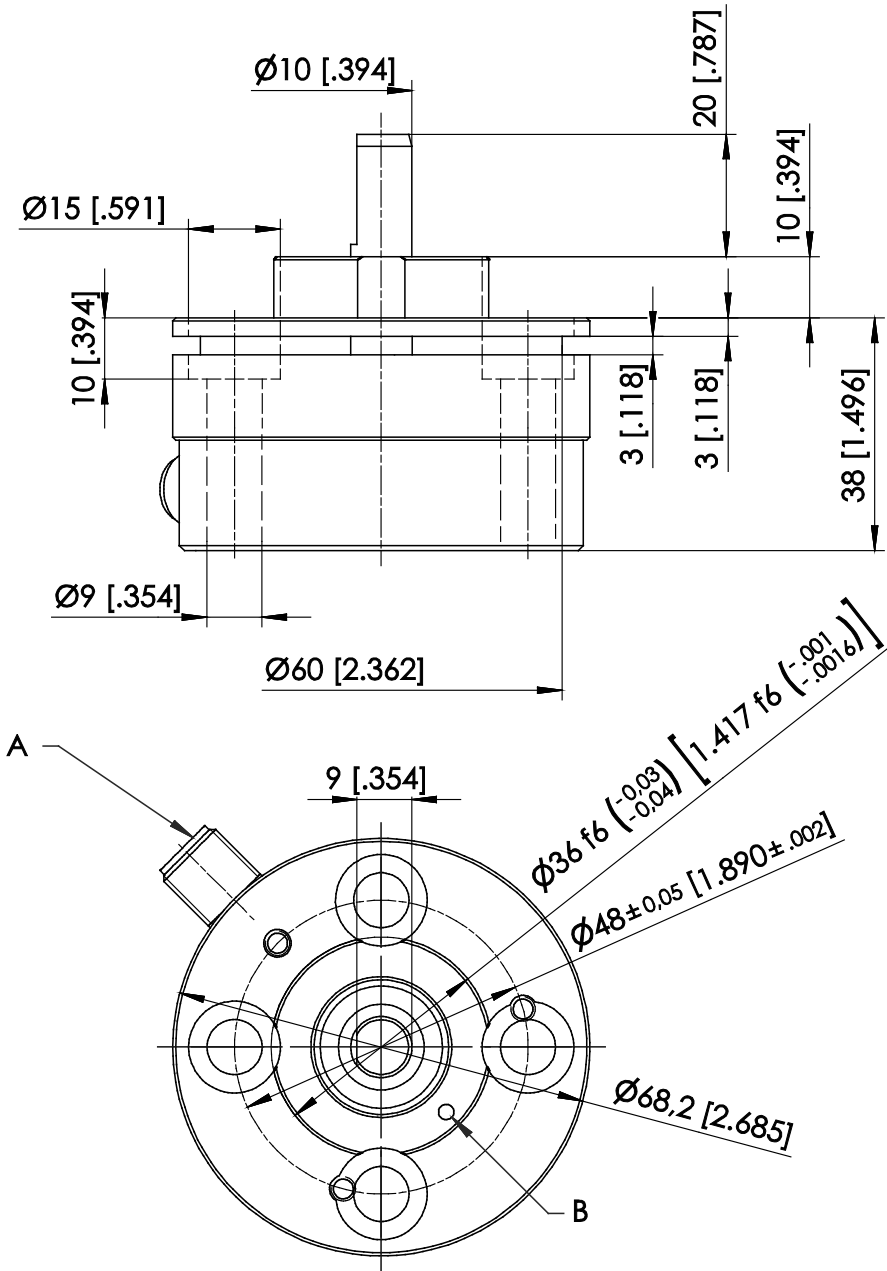
With shaft, connector M12, axial



A – Connector M12  
B – Marking

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

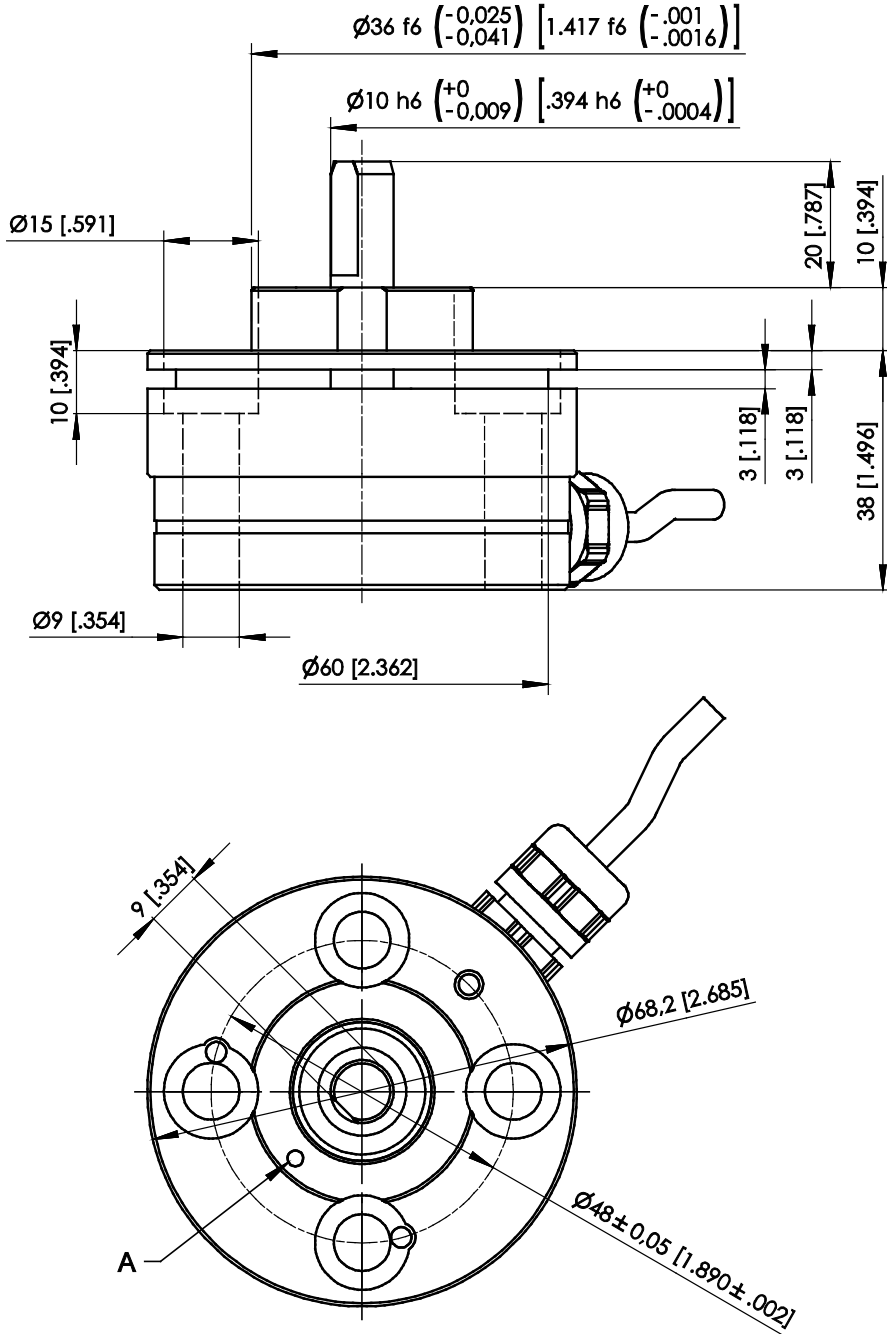
With shaft, connector M12, radial



A – Connector M12  
B – Marking

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**Cable version, with shaft**



A – Marking


Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

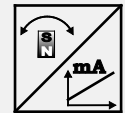
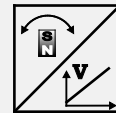


**PRAS5EX**  
**Analog output**



**Sensor features**

- Measurement range 0 ... 360°
- Protection class IP65
- Analog output
- With 10 mm shaft or non-contact
-  II 3D Ex tc IIIC T80°C Dc X (X = examined with low impact energy of 4J)



**Specifications**

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V, ratiometric Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP65
<b>Housing material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M8
<b>Connection</b>	5-pin connector M12 (compatible to 4-pin connector)
<b>Temperature range</b>	-20 ... +40°C
<b>Life cycle of bearings (shaft version)</b>	100 x 10 <sup>6</sup> revolutions (<1000 r.p.m.)
<b>Revolutions per minute (shaft version)</b>	1000 r.p.m.
<b>Allowable shaft load</b>	120 N radial / 120 N axial
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx., 890 g with shaft
<b>EMC</b>	DIN EN 61326-1:2013
<b>Dust-EX proof</b>	DIN EN 60079-0 (June 2014), DIN EN 60079-31 (December 2014)

**Order code**

PRAS5EX – 1 – 2 – 3 – 4 – 5 – 6

**1 Mechanical connection**

**V** = Shaft 10 mm  
**K** = Non-contact with external magnet

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

**U2** = Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)  
**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
**I1** = Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)

**4 Signal characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**5 Connection**

**M12A5** = 5-pin connector M12 axial (compatible with 4-pin connector)  
**M12R5** = 5-pin connector M12 radial (compatible with 4-pin connector)

**6 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

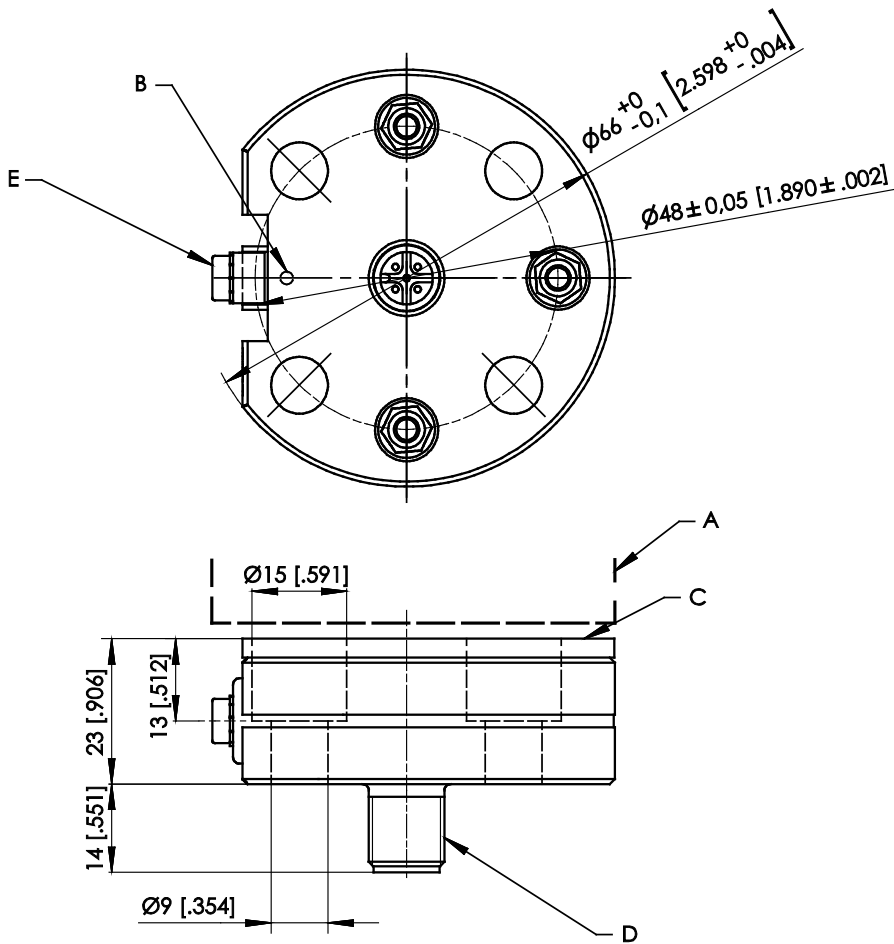
PRAS5EX – V – 360 – I1 – CW – M12A5 – VA

**Accessories:**

**Position magnets (see from page 122)**

**Dimensions**

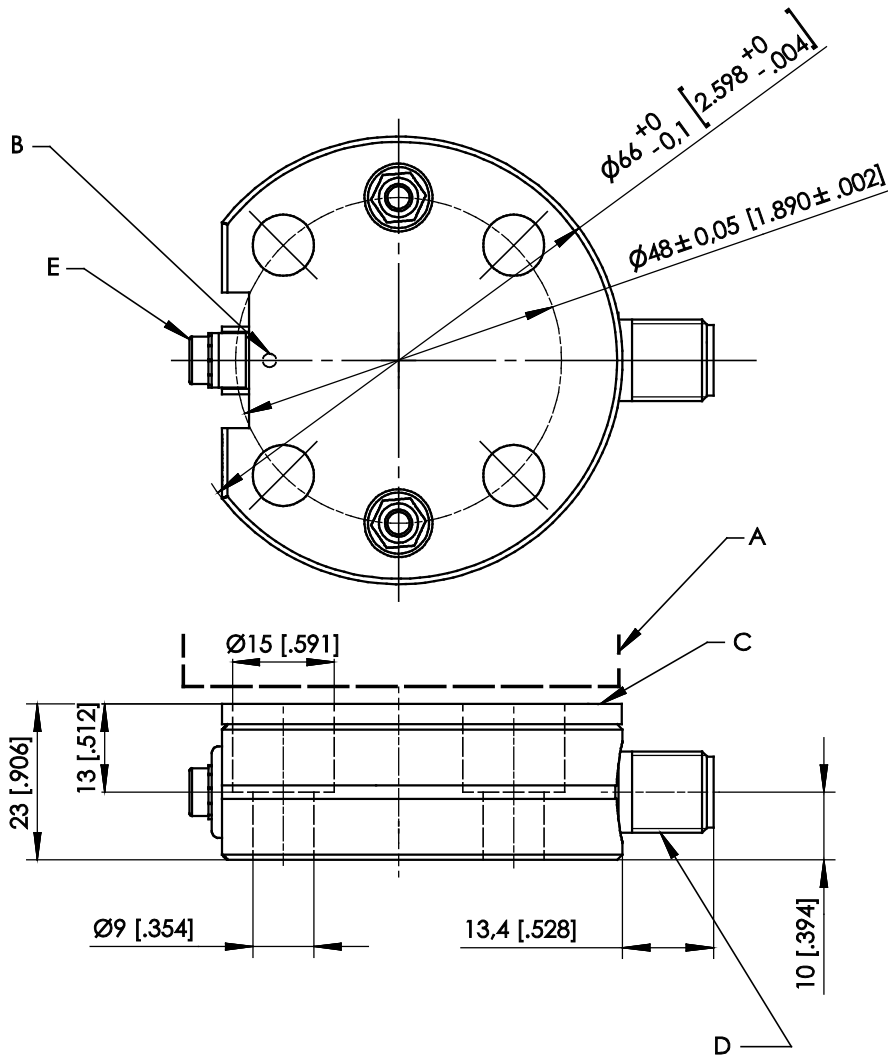
**Contactless, connector M12, axial**



- A – Position magnet
- B – Marking
- C – Measuring area
- D – Connector M12
- E – Earthing

Dimensions in mm [inch]. Weight approx. 390 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

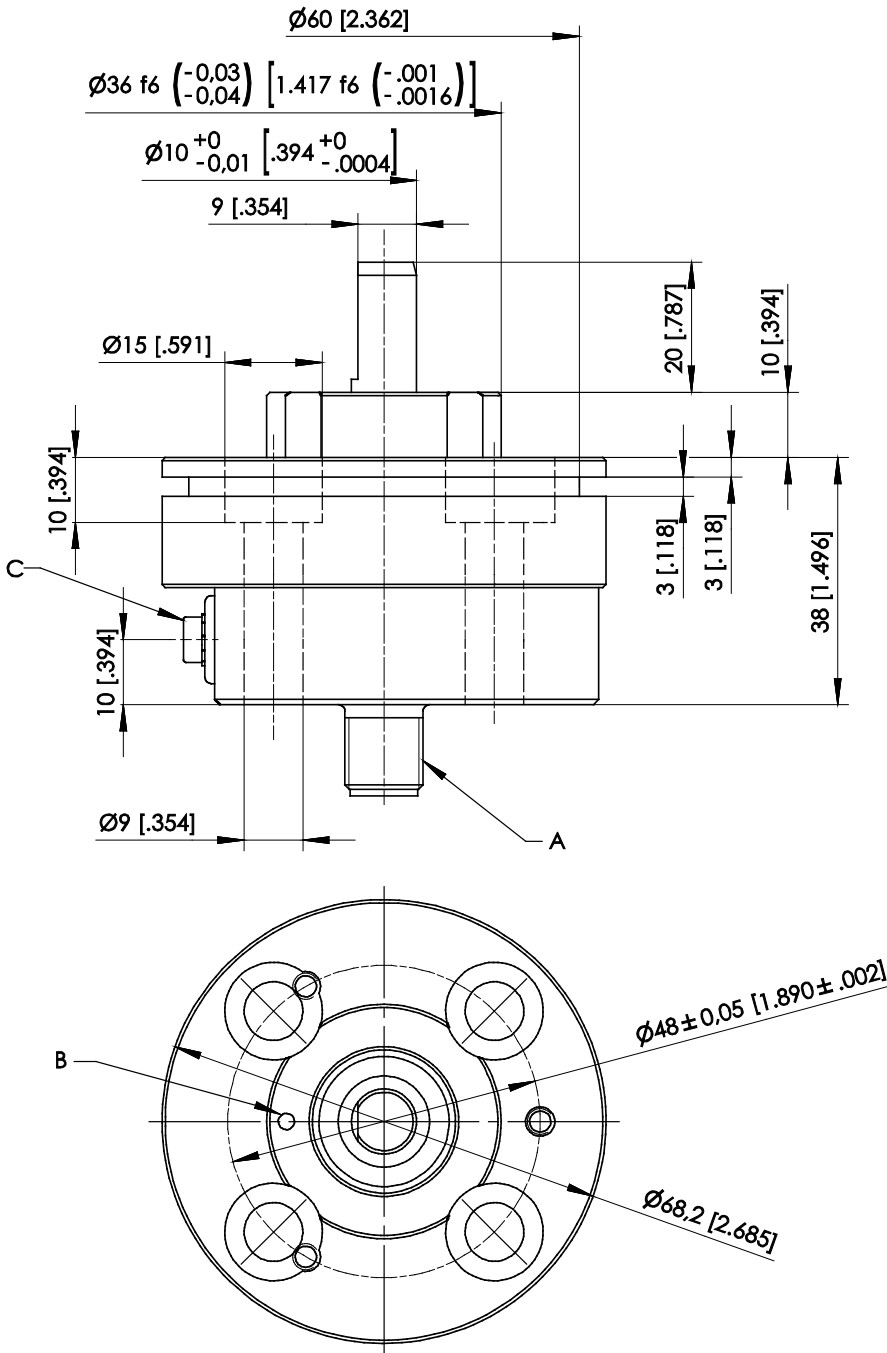
Contactless, connector M12, radial



- A – Position magnet
- B – Marking
- C – Measuring area
- D – Connector M12
- E – Earthing

Dimensions in mm [inch]. Weight approx. 390 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

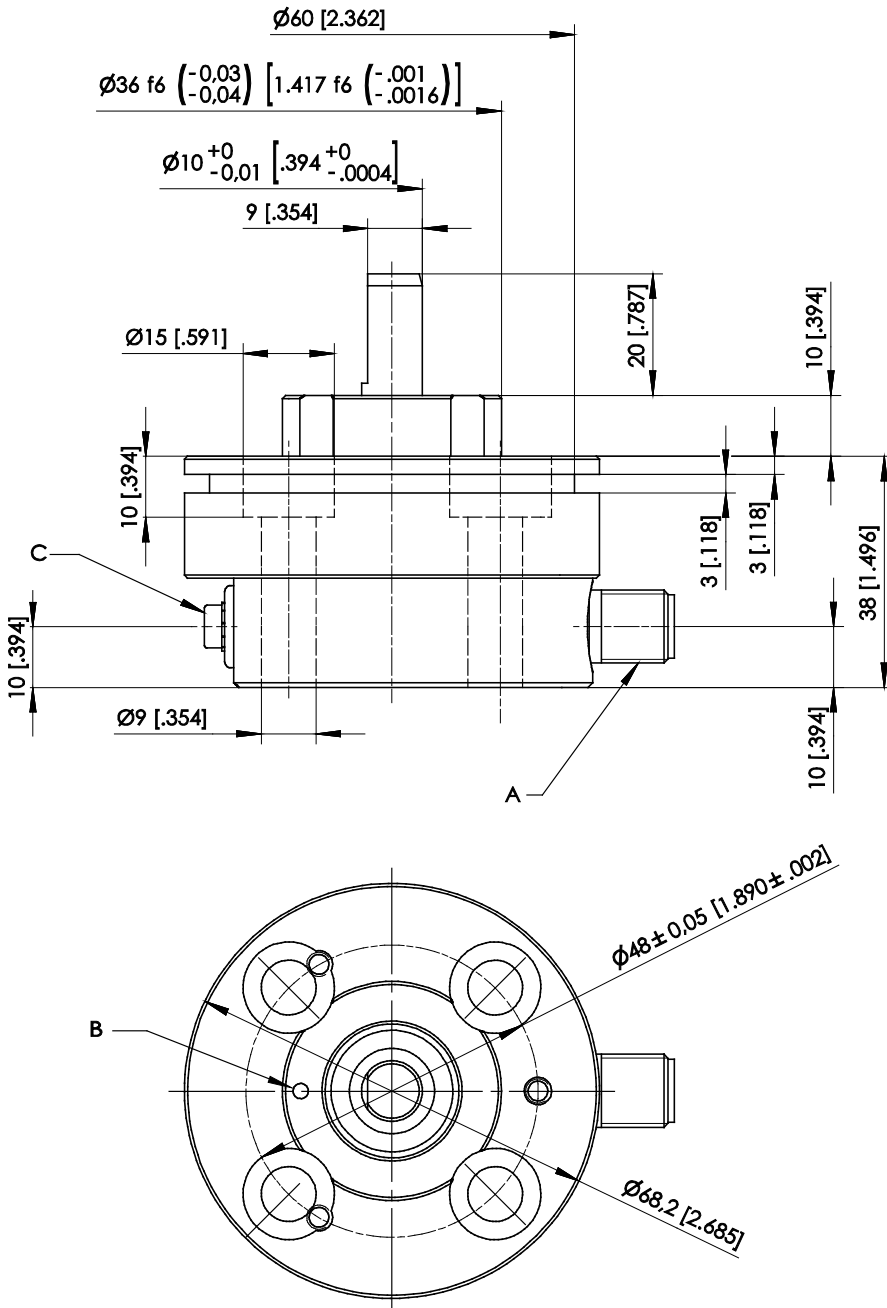
With shaft, connector M12, axial



A – Connector M12  
B – Marking  
C – Earthing

Dimensions in mm [inch]. Weight approx. 890 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

With shaft, connector M12, radial



A – Connector M12  
B – Marking  
C – Earthing

Dimensions in mm [inch]. Weight approx. 890 g.  
Dimensions informative only.  
For guaranteed dimensions consult factory.

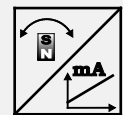
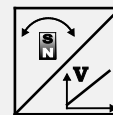
## PRAS6

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Analog output
- Magnetic measurement principle
- Non-contact with external position magnet, no wear
- Housing: Stainless steel 1.4404



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Housing material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	5-pin connector M12 (compatible to 4-pin connector) Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS6 – 1 – 2 – 3 – 4 – 5 – 6

**1 Mechanical connection**

**K** = Non-contact with external position magnet

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

**U2** = Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)  
**U2B** = Voltage 0.5 ... 10 V (excitation voltage 11.5 ... 27 V DC)  
**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
**U8** = Voltage 0.5 ... 4.5 V (excitation voltage 11 ... 36 V DC)  
**I1** = Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)  
**I1B** = Current 4 ... 20 mA, 3 wire (excitation voltage 10 ... 27 V DC)

**4 Signal characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**5 Connection**

**M12A5** = 5-pin connector M12 axial (compatible with 4-pin connector)  
**M12R5** = 5-pin connector M12 radial (compatible with 4-pin connector)  
**KAB2M** = Cable, standard length 2 m  
**KAB2M-DT04/3P/A\*** = Cable 2 m with Deutsch connector DT04, 3 pin  
**KAB2M-DT04/3P/A-S\*** = Cable 2 m with Deutsch connector DT04, 3 pin, with protective tube  
**KAB2M-DT04/4P/A** = Cable 2 m with Deutsch connector DT04, 4 pin  
**KAB2M-DT04/4P/A-S** = Cable 2 m with Deutsch connector DT04, 4 pin, with protective tube

\* only for output U6

**6 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

PRAS6 – K – 360 – I1 – CW – M12A5 – VA

**Accessories:**

**Connector cable (see page 157)**

**Position magnets (see from page 122)**

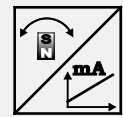
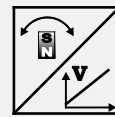


## Analog output, redundant



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Analog output, redundant
- Magnetic measurement principle
- Non-contact with external position magnet, no wear
- Housing: Stainless steel 1.4404



### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V, redundant Voltage 0.5 ... 4.5 V, redundant Current 4 ... 20 mA, 3 wire, redundant
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Housing material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRAS6 – 1 – 2 – 3 – 4 – 5 – 6

**1 Mechanical connection**

**K** = Non-contact with external position magnet

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

**U2R** = Voltage 0.5 ... 10 V, redundant (excitation voltage 18 ... 36 V DC)  
**U6R** = Voltage 0.5 ... 4.5 V ratiometric, redundant (excitation voltage 5 V DC)  
**U8R** = Voltage 0.5 ... 4.5 V, redundant (excitation voltage 11 ... 36 V DC)  
**I1R** = Current 4... 20 mA, 3 wire, redundant (excitation voltage 18 ... 36 V DC)  
 (output I1R possible only with CW/CCW signal characteristics)

**4 Signal characteristics**

**CW/CCW** = Signal 1 increasing clockwise, signal 2 increasing counterclockwise  
**CW/CW\*** = Signal 1 and signal 2 increasing clockwise  
**CCW/CCW\*** = Signal 1 and signal 2 increasing counterclockwise

\* not available with output I1R

**5 Connection**

**M12A8** = 8-pin connector M12 axial  
**M12R8** = 8-pin connector M12 radial  
**KAB2M** = Cable, standard length 2 m  
**KAB2M-DT04/6P/A\*** = Cable 2 m with Deutsch connector DT04, 6 pin  
**KAB2M-DT04/6P/A-S\*** = Cable 2 m with Deutsch connector DT04, 6 pin, with protective tube  
**KAB2M-DT04/8P/A** = Cable 2 m with Deutsch connector DT04, 8 pin  
**KAB2M-DT04/8P/A-S** = Cable 2 m with Deutsch connector DT04, 8 pin, with protective tube

\* only for output U6R

**6 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

PRAS6 – K – 360 – U2R – CW/CCW – M12R8 – VA

**Accessories:**

**Connector cable (see page 158)**

**Position magnets (see from page 122)**

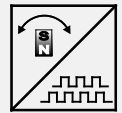
## PRDS6

### Incremental output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Incremental output
- Magnetic measurement principle
- Non-contact with external position magnet
- Housing: Stainless steel 1.4404



#### Specifications

<b>Output</b>	Incremental encoder output RS422-/HTL compatible, filtered output
<b>Measurement range</b>	0 ... 360°
<b>Resolution (pulses per revolution)</b>	25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS6 – 1 – 2 – 3 – 4 – 5

**1 Mechanical connection**

**K** = Non-contact with external position magnet

**2 Resolution**

25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024

**3 Output**

**RS5VF** = RS422 compatible output with excitation 5 V DC, filtered output  
**RS24VF** = RS422 compatible output with excitation 10 ... 36 V, filtered output  
**HT24VF** = HTL compatible output with excitation 18 ... 36 V, filtered output

**4 Connection**

**M12A8** = 8-pin connector M12, axial  
**M12R8** = 8-pin connector M12, radial  
**KAB2M** = Cable, standard length 2 m  
**KAB2M-DT04/8P/A** = Cable 2 m with Deutsch connector DT04, 8 pin  
**KAB2M-DT04/8P/A-S** = Cable 2 m with Deutsch connector DT04, 8 pin, with protective tube

**5 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

PRDS6 – K – 1024 – RS24VF – M12A8 – VA

**Accessories:**

**Connector cable (see page 158)**

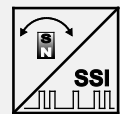
**Position magnets (see from page 122)**

## Digital output SSI



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Digital output SSI
- Magnetic measurement principle
- Non-contact with external position magnet
- Housing: Stainless steel 1.4404



### Specifications

<b>Output</b>	Synchronous serial SSI
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	12 Bit (4096 steps) per revolution
<b>Repeatability</b>	±0.1° (typical)
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	8-pin connector M12 Cable, standard length 2 m Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS6 – 1 – 2 – 3 – 4 – 5

**1 Mechanical connection**

**K** = Non-contact with external position magnet

**2 Output**

**RSSI5V** = Synchronous serial output with excitation 5 V DC  
**RSSI24V** = Synchronous serial output with excitation 10 ... 36 V

**3 Code characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**4 Connection**

**M12A8** = 8-pin connector M12, axial  
**M12R8** = 8-pin connector M12, radial  
**KAB2M** = Cable, standard length 2 m  
**KAB2M-DT04/6P/A** = Cable 2 m with Deutsch connector DT04, 6 pin  
**KAB2M-DT04/6P/A-S** = Cable 2 m with Deutsch connector DT04, 6 pin, with protective tube

**5 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

PRDS6 – K – RSSI24V – CW – M12A8 – VA

**Accessories:**

**Connector cable (see page 158)**

**Position magnets (see from page 122)**

## Digital output CAN



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Digital output CAN
- Non-contact with external position magnet
- Housing: Stainless steel 1.4404
- Redundant version available



### Specifications

<b>Output</b>	CANopen (CiA 301-V4.02/406-V3.2) CAN SAE J1939
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	0.05° max.
<b>Linearity</b>	±1% (typical)
<b>Rated Distance sensor /magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	5-pin connector M12 Cable with Deutsch connector DT04
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx. (without cable)
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS6 – 1 – 2 – 3 – 4

**1 Shaft**

**K** = Non-contact with external position magnet

**2 Output**

**CANOP** = CANopen  
**CANJ1939** = CAN SAE J1939  
**CANOPR** = CANopen, redundant  
**CANJ1939R** = CAN SAE J1939, redundant

**3 Connection**

**M12A5/CAN** = 5-pin connector M12 axial  
**M12R5/CAN** = 5-pin connector M12 radial  
**KAB0,3M-DT04/4P/A** = Cable 0.3 m with Deutsch connector DT04, 4 pin  
**KAB0,3M-DT04/4P/A-S** = Cable 0.3 m with Deutsch connector DT04, 4 pin, with protective tube

**4 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

**PRDS6 – K – CANOP – M12A5/CAN – VA**

**Accessories:**

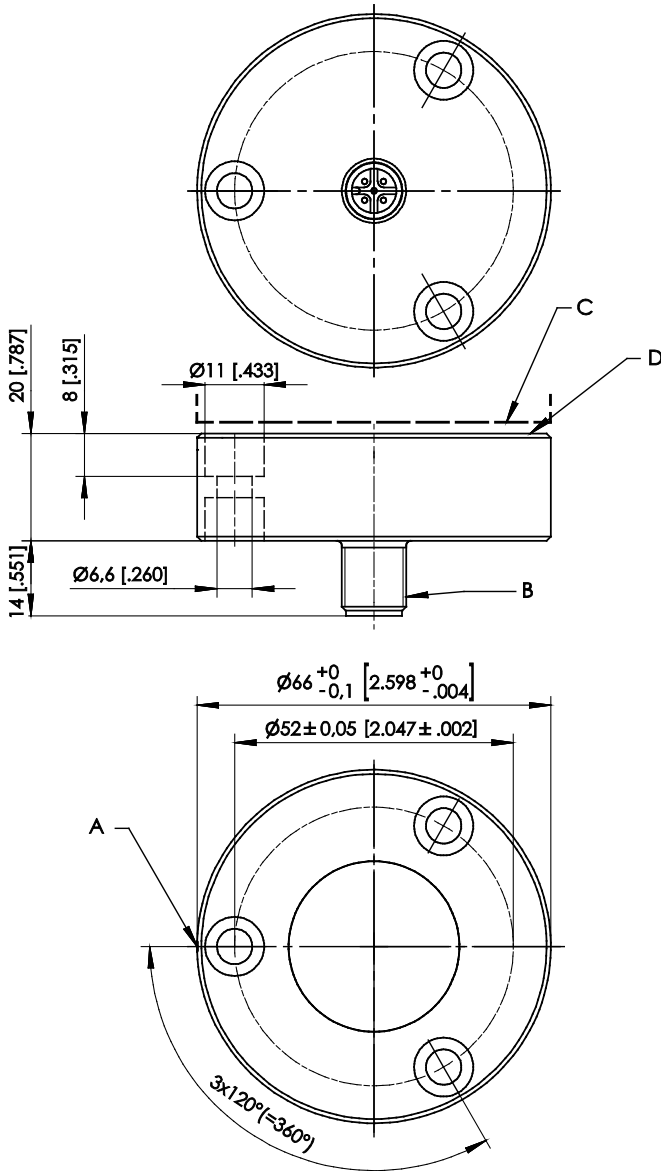
**Connector cable (see page 159)**

**Position magnets (see from page 122)**



**Dimensions (analog and digital version)**

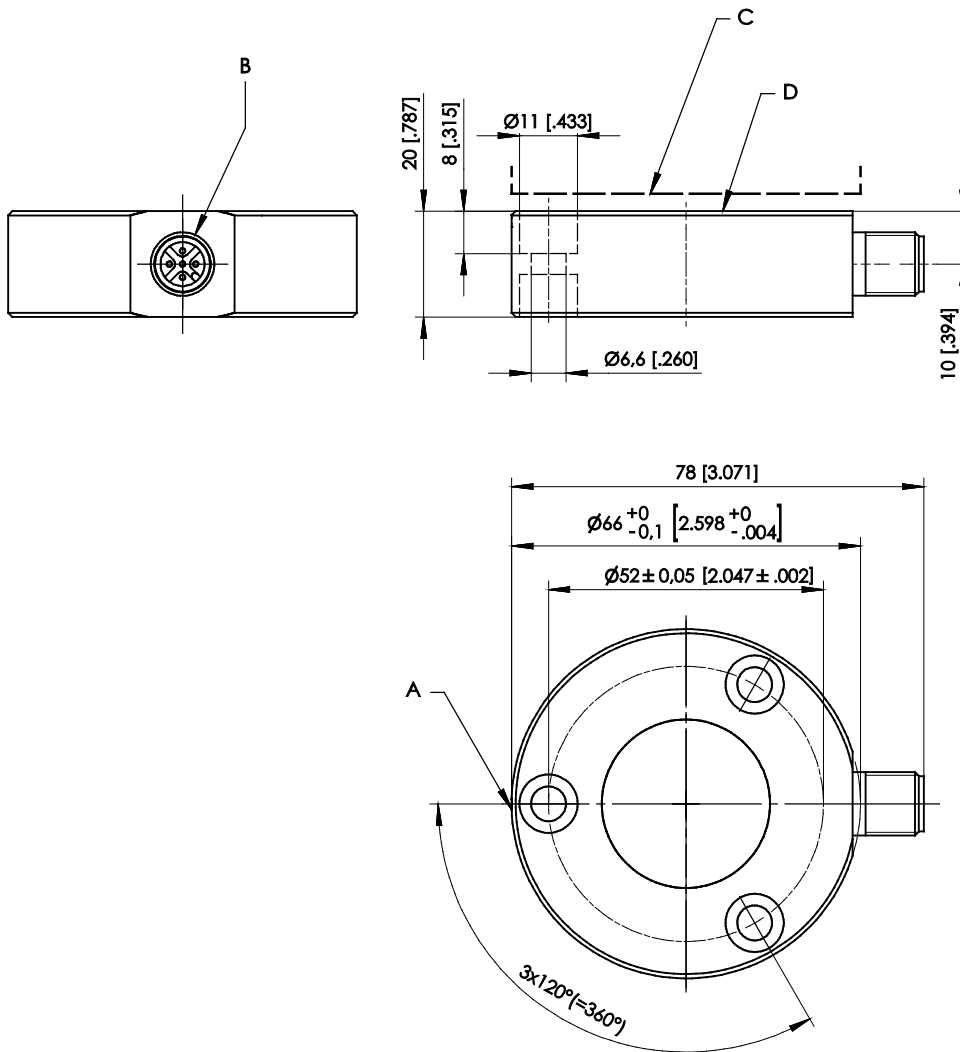
**Connector M12, axial**



- A – Marking
- B – Connector M12
- C – Position magnet
- D – Measurement area

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

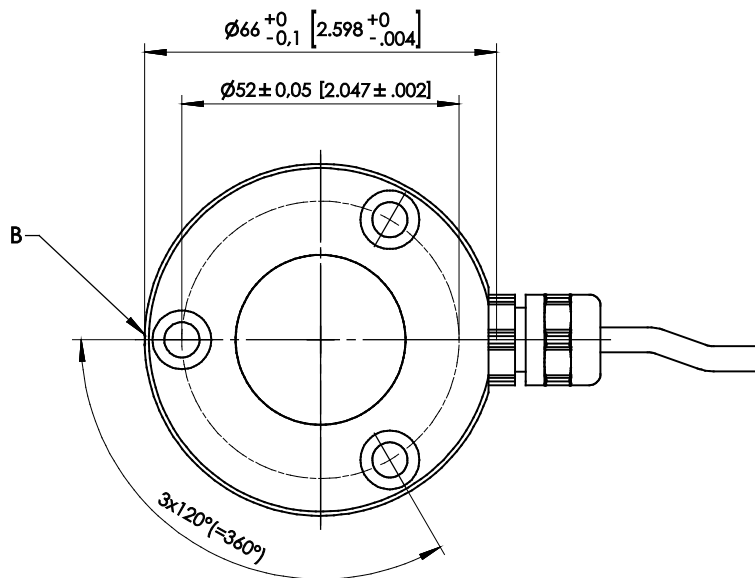
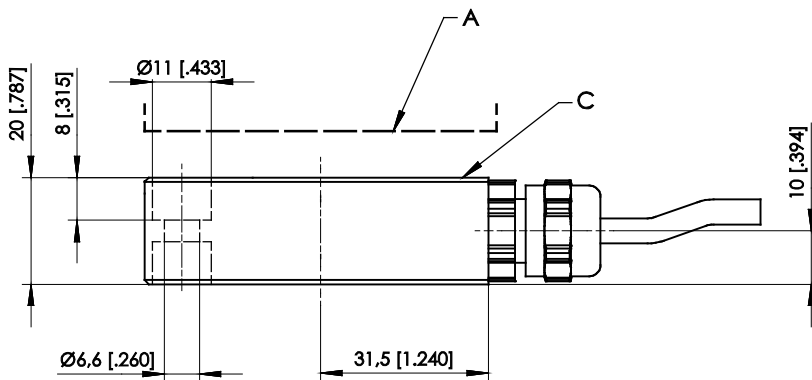
**Connector M12, radial**



- A – Marking
- B – Connector M12
- C – Position magnet
- D – Measurement area

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**Cable version**



- A – Position magnet
- B – Marking
- C – Measurement area

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

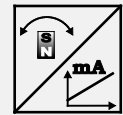
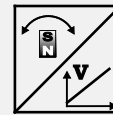
## PRAS7

### Analog output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Analog output
- Non-contact with external position magnet, no wear
- Housing: Stainless steel 1.4404
- Application: hygienic areas



#### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V Current 4 ... 20 mA, 3 wire
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Housing material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	5-pin connector M12 (compatible to 4-pin connector)
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx.
<b>EMC</b>	DIN EN 61326-1:2013

Order code

PRAS7 – 1 – 2 – 3 – 4 – 5 – 6

**1 Mechanical connection**

**K** = Non-contact with external position magnet

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

**U2** = Voltage 0.5 ... 10 V (excitation voltage 18 ... 36 V DC)  
**U2B** = Voltage 0.5 ... 10 V (excitation voltage 11.5 ... 27 V DC)  
**U6** = Voltage 0.5 ... 4.5 V ratiometric (excitation voltage 5 V DC)  
**U8** = Voltage 0.5 ... 4.5 V (excitation voltage 11 ... 36 V DC)  
**I1** = Current 4 ... 20 mA, 3 wire (excitation voltage 18 ... 36 V DC)  
**I1B** = Current 4 ... 20 mA, 3 wire (excitation voltage 10 ... 27 V DC)

**4 Signal characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**5 Connection**

**M12A5** = 5-pin connector M12 axial (compatible with 4-pin connector)  
**M12R5** = 5-pin connector M12 radial (compatible with 4-pin connector)

**6 Housing material**

**VA** = Stainless steel 1.4404

Order example

PRAS7 – K – 360 – I1 – CW – M12A5 – VA

Accessories:

Connector cable (see page 157)

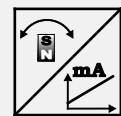
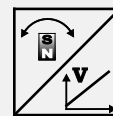
Position magnets (see from page 122)

## Analog output, redundant



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Analog output, redundant
- Non-contact with external position magnet, no wear
- Housing: Stainless steel 1.4404
- Application: hygienic areas



### Specifications

<b>Output</b>	Voltage 0.5 ... 10 V, redundant Voltage 0.5 ... 4.5 V, redundant Current 4 ... 20 mA, 3 wire, redundant
<b>Measurement range</b>	0 ... 15° to 0 ... 360° (in 15° increments)
<b>Resolution</b>	0.03% (60 ... 360°); 0.1% (15 ... 45°)
<b>Repeatability</b>	±0.03% (60 ... 360°); ±0.1% (15 ... 45°)
<b>Linearity</b>	±0.3% f.s. (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Housing material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	8-pin connector M12
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx.
<b>EMC</b>	DIN EN 61326-1:2013

Order code

PRAS7 – 1 – 2 – 3 – 4 – 5 – 6

**1 Mechanical connection**

**K** = Non-contact with external position magnet

**2 Measurement range (0 ... 15° to 0 ... 360°, in 15° increments)**

15 / 30 / 45 / ... / 345 / 360

**3 Output**

**U2R** = Voltage 0.5 ... 10 V, redundant (excitation voltage 18 ... 36 V DC)  
**U6R** = Voltage 0.5 ... 4.5 V ratiometric, redundant (excitation voltage 5 V DC)  
**U8R** = Voltage 0.5 ... 4.5 V, redundant (excitation voltage 11 ... 36 V DC)  
**I1R** = Current 4... 20 mA, 3 wire, redundant (excitation voltage 18 ... 36 V DC)  
 (output I1R possible only with CW/CCW signal characteristics)

**4 Signal characteristics**

**CW/CCW** = Signal 1 increasing clockwise, signal 2 increasing counterclockwise  
**CW/CW\*** = Signal 1 and signal 2 increasing clockwise  
**CCW/CCW\*** = Signal 1 and signal 2 increasing counterclockwise

\* not available with output I1R

**5 Connection**

**M12A8** = 8-pin connector M12 axial  
**M12R8** = 8-pin connector M12 radial

**6 Housing material**

**VA** = Stainless steel 1.4404

Order example

PRAS7 – K – 360 – U2R – CW/CCW – M12R8 – VA

Accessories:

Connector cable (see page 158)

Position magnets (see from page 122)

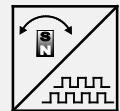
## PRDS7

### Incremental output



#### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Incremental output
- Non-contact with external position magnet
- Housing: Stainless steel 1.4404
- Application: hygienic areas



#### Specifications

<b>Output</b>	Incremental encoder output RS422-/HTL compatible, filtered output
<b>Measurement range</b>	0 ... 360°
<b>Resolution (pulses per revolution)</b>	25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	8-pin connector M12
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx.
<b>EMC</b>	DIN EN 61326-1:2013



**Order code**

PRDS7 – 1 – 2 – 3 – 4 – 5

**1 Mechanical connection**

**K** = Non-contact with external position magnet

**2 Resolution**

25 / 50 / 100 / 200 / 256 / 300 / 400 / 500 / 512 / 1000 / 1024

**3 Output**

**RS5VF** = RS422 compatible output with excitation 5 V DC, filtered output  
**RS24VF** = RS422 compatible output with excitation 10 ... 36 V, filtered output  
**HT24VF** = HTL compatible output with excitation 18 ... 36 V, filtered output

**4 Connection**

**M12A8** = 8-pin connector M12, axial  
**M12R8** = 8-pin connector M12, radial

**5 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

PRDS7 – K – 1024 – RS24VF – M12A8 – VA

**Accessories:**

**Connector cable (see page 158)**

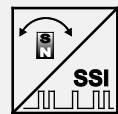
**Position magnets (see from page 122)**

## Digital output SSI



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Digital output SSI
- Non-contact with external position magnet
- Housing: Stainless steel 1.4404
- Application: hygienic areas



### Specifications

<b>Output</b>	Synchronous serial SSI
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	12 Bit (4096 steps) per revolution
<b>Repeatability</b>	±0.1° (typical)
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	8-pin connector M12
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx.
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS7 – 1 – 2 – 3 – 4 – 5

**1 Mechanical connection**

**K** = Non-contact with external position magnet

**2 Output**

**RSSI5V** = Synchronous serial output with excitation 5 V DC  
**RSSI24V** = Synchronous serial output with excitation 10 ... 36 V

**3 Code characteristics**

**CW** = Signal increasing CW, clockwise  
**CCW** = Signal increasing CCW, counterclockwise

**4 Connection**

**M12A8** = 8-pin connector M12, axial  
**M12R8** = 8-pin connector M12 radial

**5 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

PRDS7 – K – RSSI24V – CW – M12A8 – VA

**Accessories:**

**Connector cable (see page 158)**

**Position magnets (see from page 122)**

## Digital output CAN



### Sensor features

- Measurement range 0 ... 360°
- Protection class IP67/IP69
- Digital output CAN
- Non-contact with external position magnet
- Housing: Stainless steel 1.4404
- Redundant version available



### Specifications

<b>Output</b>	CANopen (CiA 301-V4.02/406-V3.2) CAN SAE J1939
<b>Measurement range</b>	0 ... 360°
<b>Resolution</b>	0.05° max.
<b>Linearity</b>	±1% (typical)
<b>Rated distance sensor / magnet</b>	Depending on the position magnet
<b>Protection class</b>	IP67/IP69 (connector output with IP67/IP69 connector cable)
<b>Material</b>	Stainless steel 1.4404
<b>Mounting</b>	Screws M6
<b>Connection</b>	5-pin connector M12
<b>Temperature range</b>	-40 ... +85°C
<b>Shock</b>	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles
<b>Weight</b>	390 g approx.
<b>EMC</b>	DIN EN 61326-1:2013

**Order code**

PRDS7 - 1 - 2 - 3 - 4

**1 Shaft**

**K** = Non-contact with external position magnet

**2 Output**

**CANOP** = CANopen  
**CANJ1939** = CAN SAE J1939  
**CANOPR** = CANopen, redundant  
**CANJ1939R** = CAN SAE J1939, redundant

**3 Connection**

**M12A5/CAN** = 5-pin connector M12 axial  
**M12R5/CAN** = 5-pin connector M12 radial

**4 Housing material**

**VA** = Stainless steel 1.4404

**Order example**

**PRDS7 - K - CANOP - M12A5/CAN - VA**

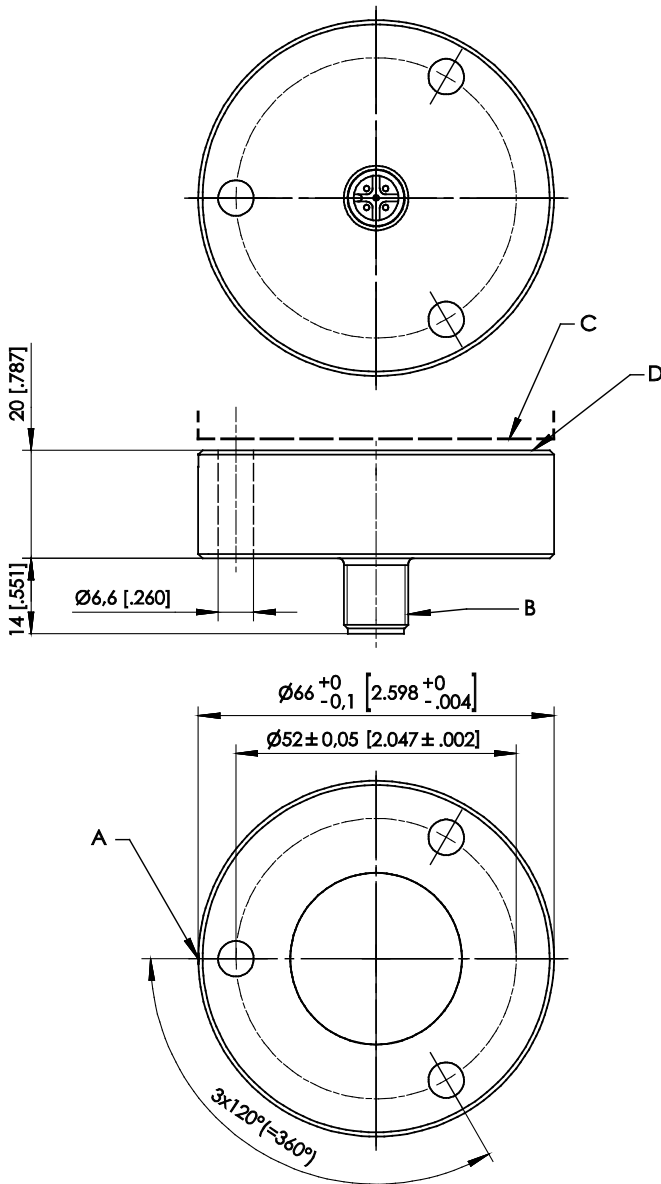
**Accessories:**

**Connector cable (see page 159)**

**Position magnets (see from page 122)**

**Dimensions (analog and digital version)**

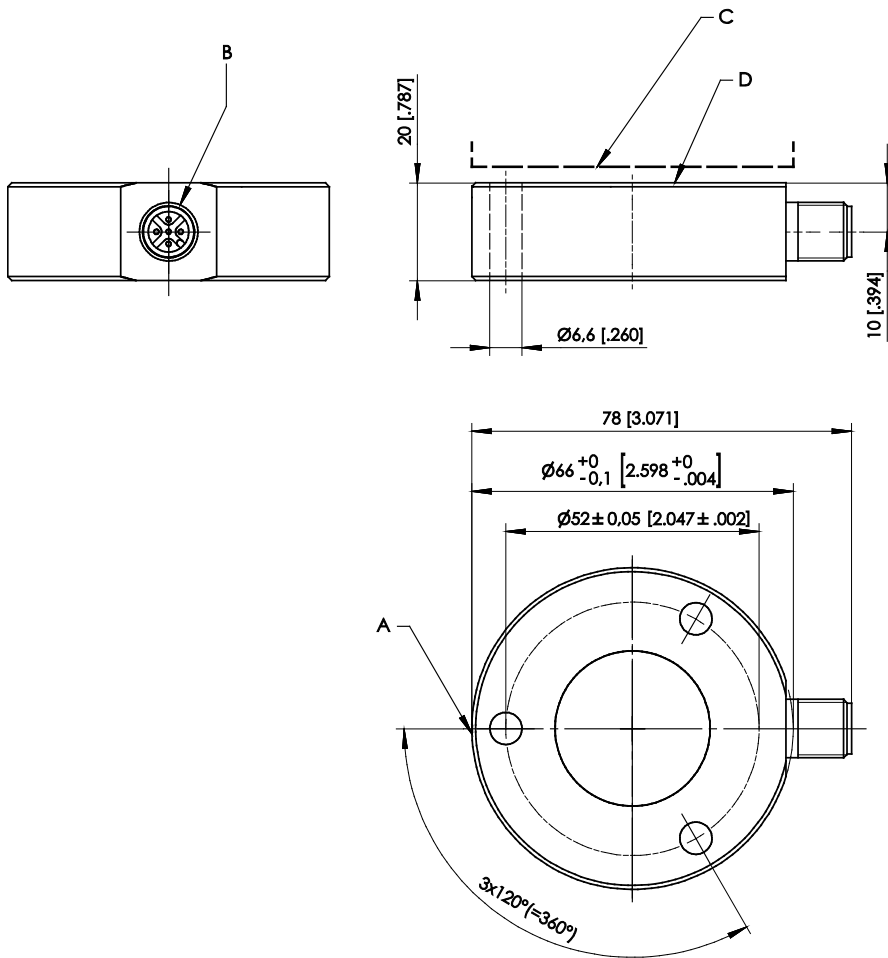
**Connector M12, axial**



- A – Position magnet
- B – Marking
- C – Measurement area
- D – Connector M12

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

**Connector M12, radial**



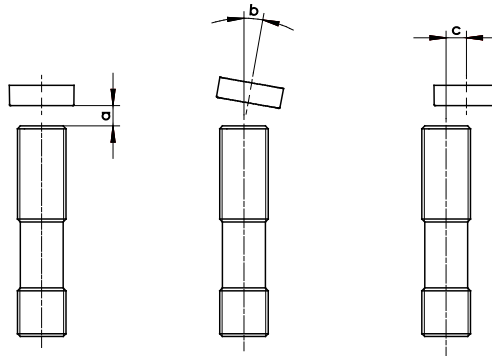
- A – Position magnet
- B – Marking
- C – Measurement area
- D – Connector M12

Dimensions in mm [inch].  
Dimensions informative only.  
For guaranteed dimensions consult factory.

## Position magnets

### Measuring error by misalignment of the position magnet

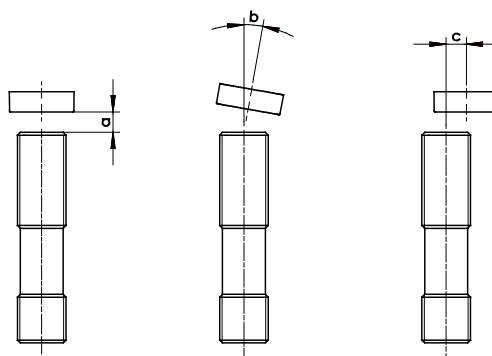
Sensor	Position magnet	Air gap [mm]	Parallelism [°]	Error by axial misalignment [°]					
		(a)	(b)	(c)	0.2 mm	0.5 mm	1 mm	2 mm	3 mm
PRAS20	PRMAG20	0 ... 7	0 ... 5	0.1	0.3	0.7	2	4.6	–
PRAS21	PRMAG21	0 ... 2	0 ... 5	0.15	0.3	0.9	3.6	9.6	–
PRAS26	PRMAG22	0 ... 10	0 ... 5	0	0	0.7	1.5	3.8	7
	PRMAG-M10	0 ... 3	0 ... 5	0.1	0.1	0.5	2	7	–
PRAS27	PRMAG20	0 ... 7.5	0 ... 5	0.1	0.3	0.7	2	4.6	–
PRDS27	PRMAG21	0 ... 2.5	0 ... 5	0.15	0.3	0.9	3.6	9.6	–
	PRMAG22	0 ... 10.5	0 ... 5	0	0	0.7	1.5	3.8	7
	PRMAG-M10	0 ... 3.5	0 ... 5	0.1	0.1	0.5	2	7	–





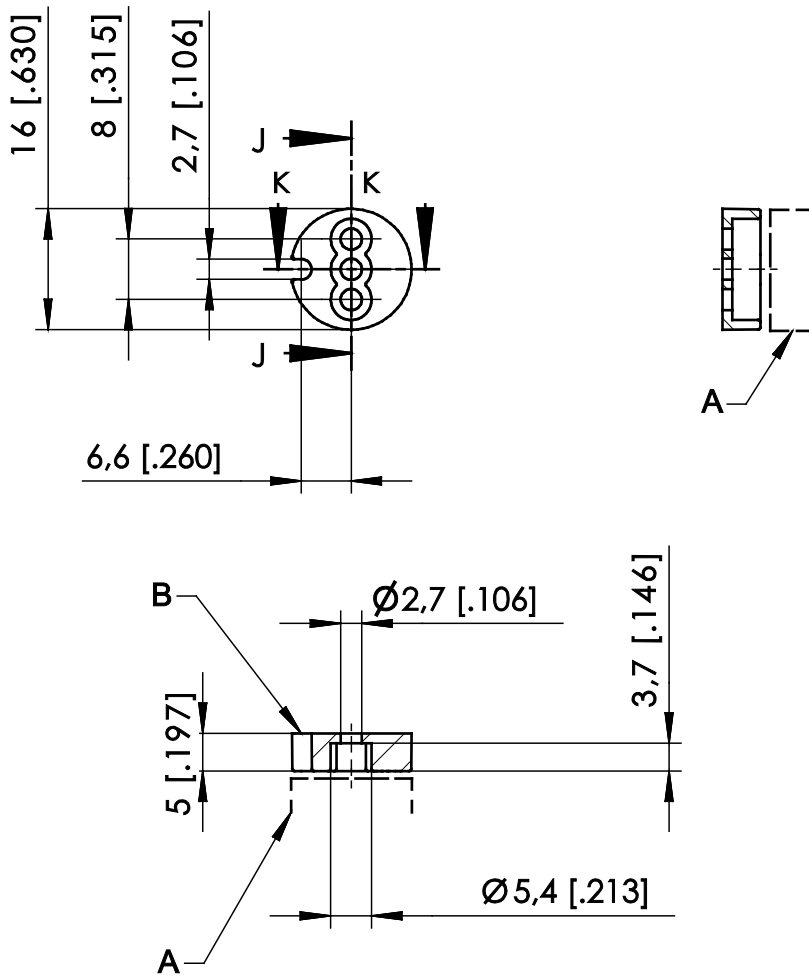
### Measuring error by misalignment of the position magnet

Sensor	Position magnet	Air gap [mm]	Parallelism [°]	Error by axial misalignment [°]					
				(a)	(b)	(c)	0.2 mm	0.5 mm	1 mm
PRAS1 PRDS1	PRMAG20	0 ... 6.5	0 ... 5	0.15	0.4	0.8	2.2	5	–
	PRMAG21	0 ... 4	0 ... 5	0.2	0.4	1	3.8	10	–
	PRMAG22	0 ... 9.5	0 ... 5	0.1	0.4	1	2.2	4.5	8
	PRMAG-M10	0 ... 5	0 ... 5	0.1	0.1	0.5	2	7	–
PRAS2 PRDS2	PRMAG2-Z-VA	0 ... 9	0 ... 5	0.1	0.2	0.6	1.5	4.5	8.5
	PRMAG20	0 ... 6	0 ... 5	0.15	0.4	0.8	2.2	5	–
	PRMAG21	0 ... 3.5	0 ... 5	0.2	0.4	1	3.8	10	–
	PRMAG22	0 ... 9	0 ... 5	0.1	0.4	1	2.2	4.5	8
PRAS4	PRMAG5-Z-VA-WP	0 ... 6.5	0 ... 5	0.1	0.2	0.6	1.5	4.5	8.5
PRAS5	PRMAG2-Z-(VA)	0 ... 8.5	0 ... 5	0.1	0.2	0.6	1.5	4.5	8.5
PRAS6	PRMAG5-Z-(VA)	0 ... 7.5	0 ... 5	0.1	0.2	0.6	1.5	4.5	8.5
PRAS7	PRMAG6-Z-(VA)	0 ... 7.5	0 ... 5	0.1	0.2	0.6	1.5	4.5	8.5
PRDS5	PRMAG7-Z-VA	0 ... 7.5	0 ... 5	0.1	0.2	0.6	1.5	4.5	8.5
PRDS6 PRDS7	PRMAG20	0 ... 5.5	0 ... 5	0.15	0.4	0.8	2.2	5	–
	PRMAG21	0 ... 3	0 ... 5	0.2	0.4	1	3.8	10	–
	PRMAG22	0 ... 8.5	0 ... 5	0.1	0.4	1	2.2	4.5	8





**PRMAG21**



A – Sensor  
B – Marking

Order code	Weight	Material	Moment of inertia
<b>PRMAG21</b>	approx. 3 g	zinc coated steel; plastic	0.1 kgmm <sup>2</sup>

A misalignment of the position magnet has an effect on the linearity.

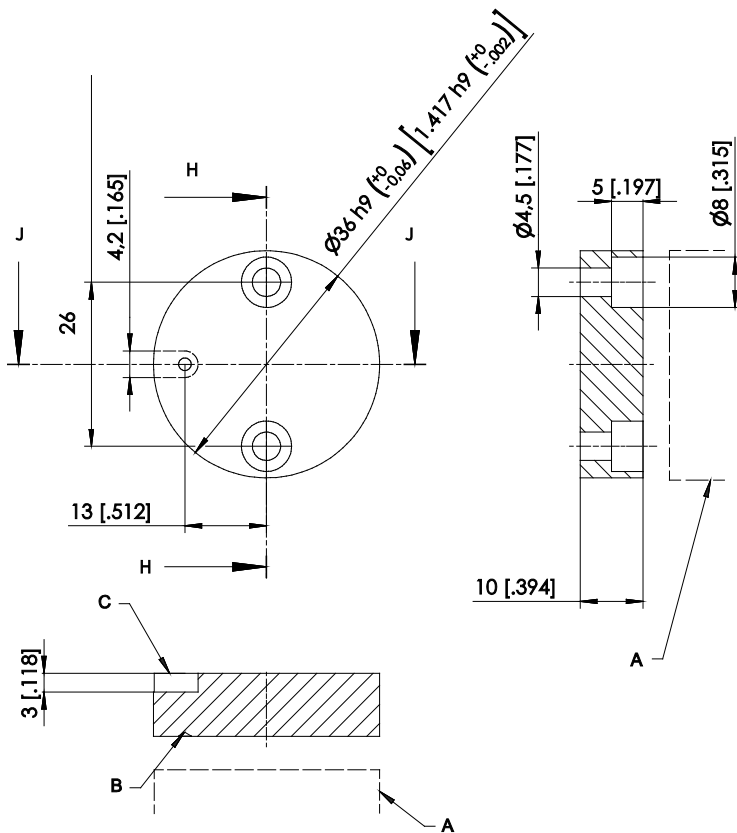
Dimensions in mm [inch]

Dimensions informative only.

For guaranteed dimensions please consult factory.



**PRMAG2-Z / PRMAG2-Z-VA**



- A – Sensor
- B – Marking
- C – Notch

Order code	Weight	Material	Moment of inertia
<b>PRMAG2-Z</b>	approx. 30 g	AlMgSi1	4.9 kgmm <sup>2</sup>
<b>PRMAG2-Z-VA</b>	approx. 67 g	stainless steel 1.4404	10.9 kgmm <sup>2</sup>

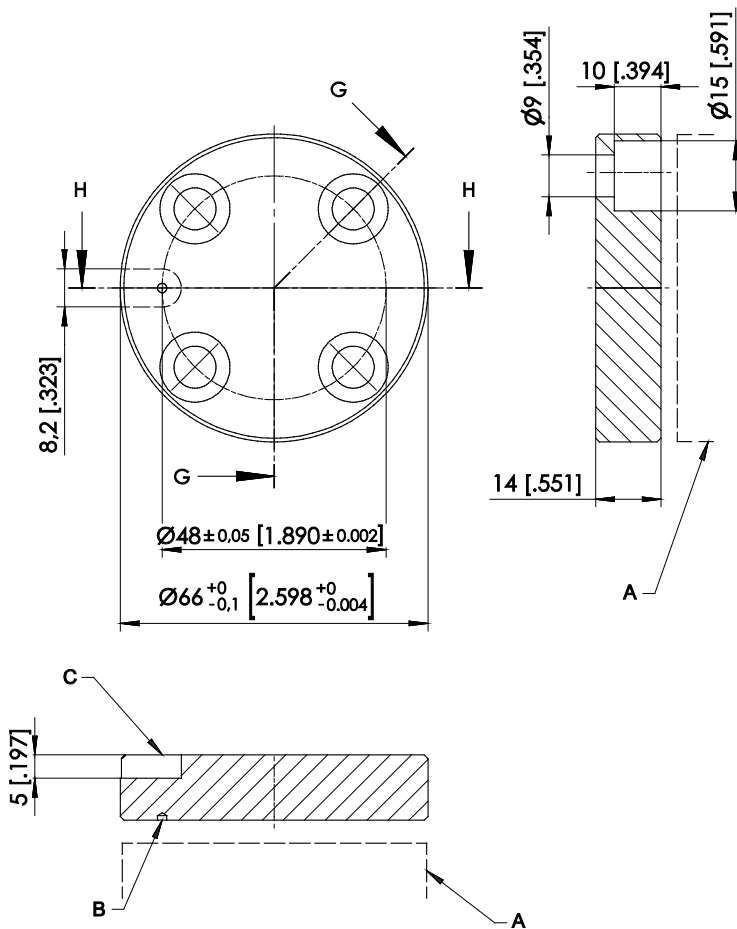
A misalignment of the position magnet has an effect on the linearity.

Dimensions in mm [inch].

Dimensions informative only.

For guaranteed dimensions please consult factory.

**PRMAG5-Z / PRMAG5-Z-VA**



A – Sensor  
B – Marking  
C – Notch

Order code	Weight	Material	Moment of inertia
<b>PRMAG5-Z</b>	approx. 110 g	AlMgSi1	59,9 kgmm <sup>2</sup>
<b>PRMAG5-Z-VA</b>	approx. 275 g	stainless steel 1.4404	149,9 kgmm <sup>2</sup>

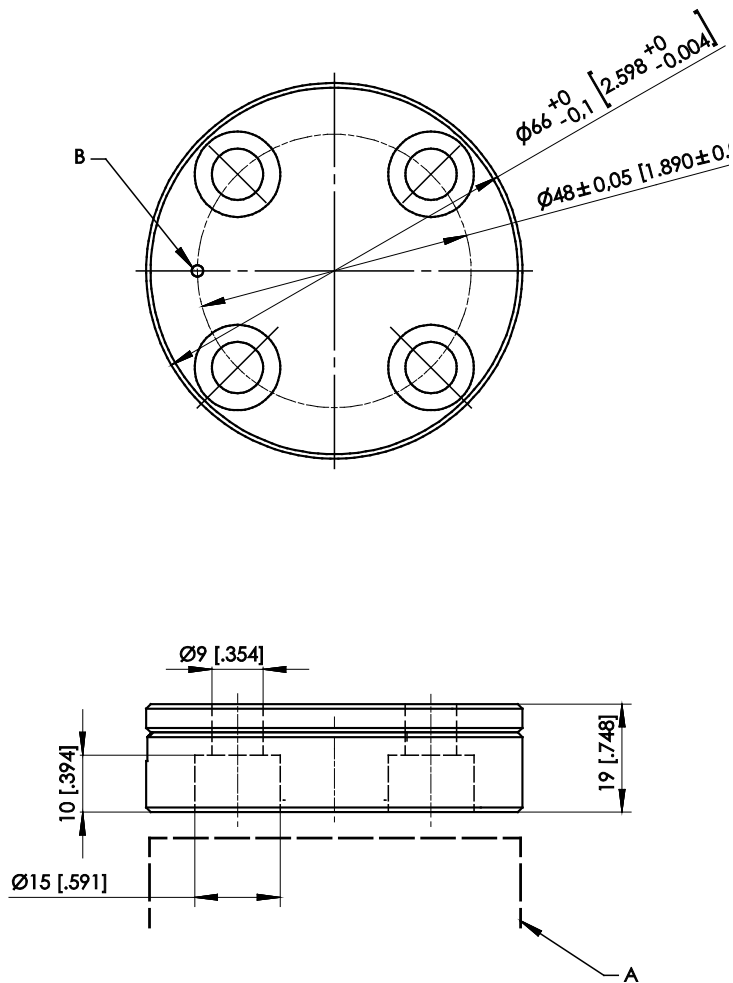
A misalignment of the position magnet has an effect on the linearity.

Dimensions in mm [inch].

Dimensions informative only.

For guaranteed dimensions please consult factory.

**PRMAG5-Z-VA-WP**



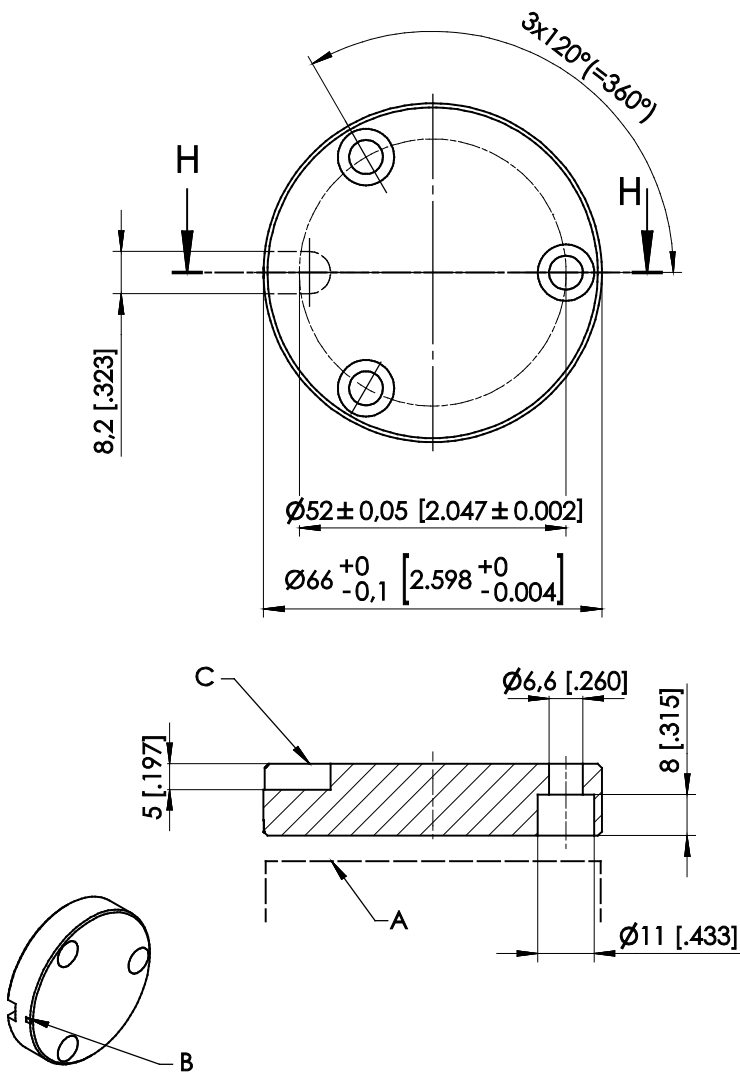
A – Position magnet  
B – Marking

Order code	Weight	Material	Moment of inertia
PRMAG5-Z-VA-WP	approx. 292 g	stainless steel 1.4404	175 kgmm <sup>2</sup>

IP68 / 100 m, continuous use.  
A misalignment of the position magnet has an effect on the linearity.

Dimensions in mm [inch]  
Dimensions informative only.  
For guaranteed dimensions please consult factory.

**PRMAG6-Z / PRMAG6-Z-VA**



A – Sensor  
B – Marking  
C – Notch

Order code	Weight	Material	Moment of inertia
<b>PRMAG6-Z</b>	approx. 110 g	AlMgSi1,	65 kgmm <sup>2</sup>
<b>PRMAG6-Z-VA</b>	approx. 315 g	stainless steel 1.4404	190 kgmm <sup>2</sup>

A misalignment of the position magnet has an effect on the linearity.

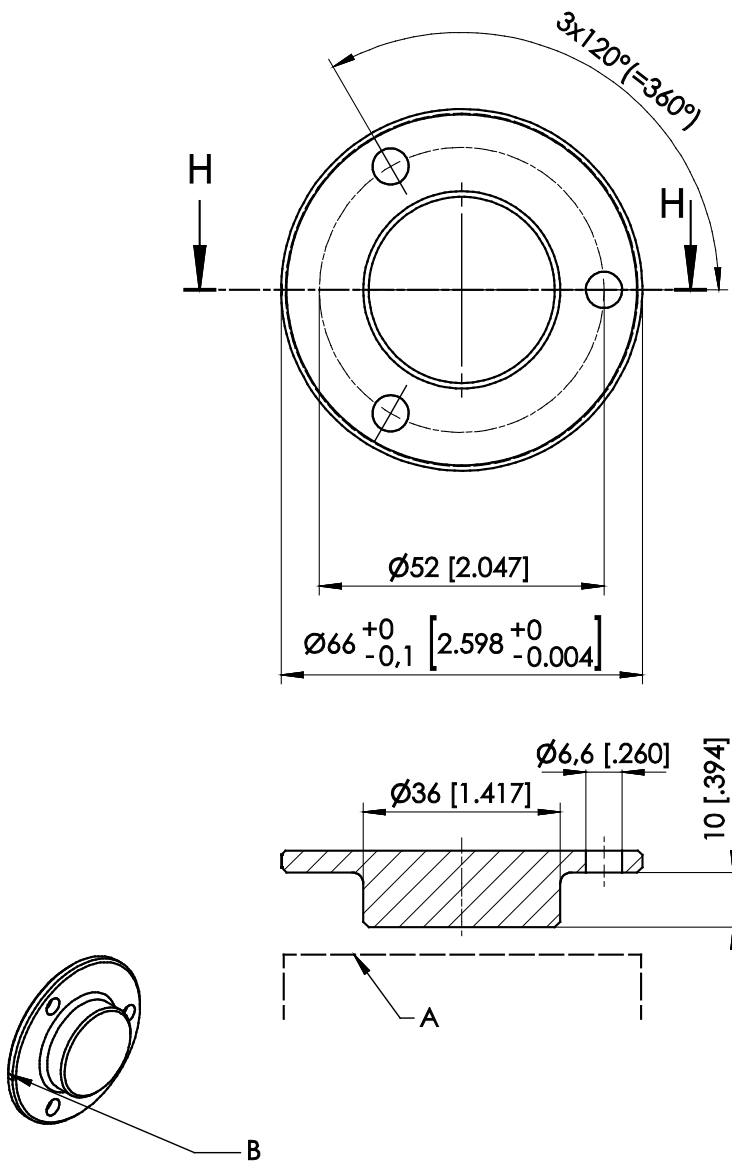
Dimensions in mm [inch].

Dimensions informative only.

For guaranteed dimensions please consult factory.



**PRMAG7-Z-VA**



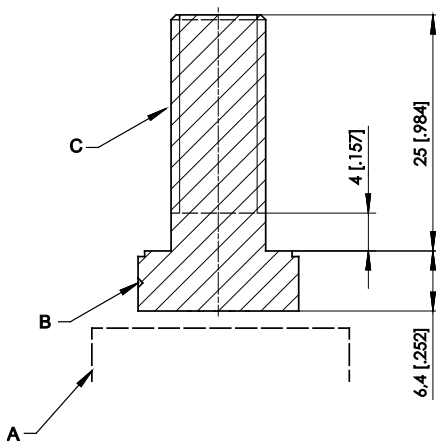
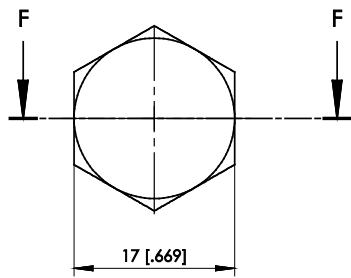
A – Sensor  
B – Marking

Order code	Weight	Material	Moment of inertia
PRMAG7-Z-VA	approx. 146 g	stainless steel 1.4404	68 kgmm <sup>2</sup>

A misalignment of the position magnet has an effect on the linearity.

Dimensions in mm [inch]  
Dimensions informative only.  
For guaranteed dimensions please consult factory.

**PRMAG-M10**



- A – Sensor
- B – Marking
- C – Thread M10

Order code	Weight	Material	Moment of inertia
<b>PRMAG-M10</b>	approx. 30 g	stainless steel A2	1.3 kgmm <sup>2</sup>

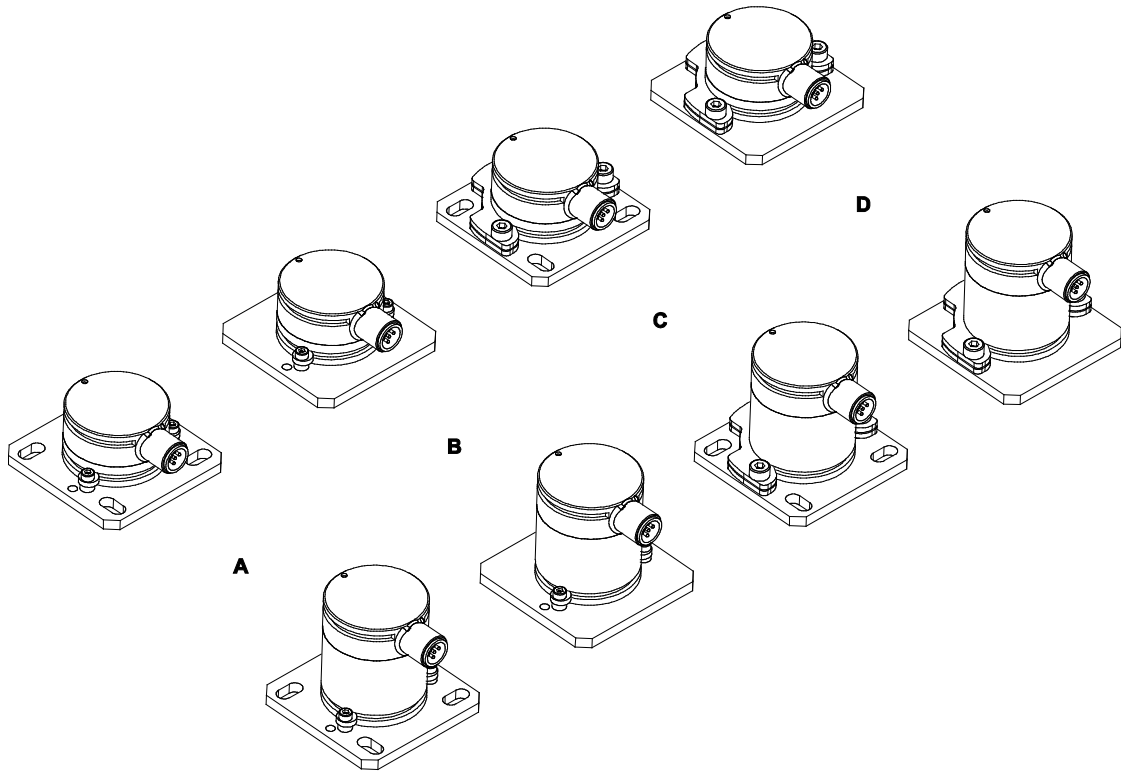
A misalignment of the position magnet has an effect on the linearity.

Dimensions in mm [inch].

Dimensions informative only.

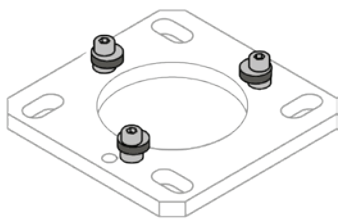
For guaranteed dimensions please consult factory.

**Mounting possibilities PRAS2/PRDS2 and PRAS3/PRDS3**

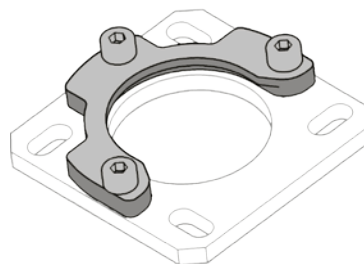


- A. **PRPT-BPL1 + PRPT-BFS1**  
(Mounting plates for screw mounting + mounting clamp)
- B. **PRPT-BPL2 + PRPT-BFS1**  
(Mounting plates for welding assembly + mounting clamp)
- C. **PRPT-BPL1 + PRPT-BFS2**  
(Mounting plates for screw mounting + mounting bracket)
- D. **PRPT-BPL2 + PRPT-BFS2**  
(Mounting plates for welding assembly + mounting bracket)

Mounting clamp BFS1



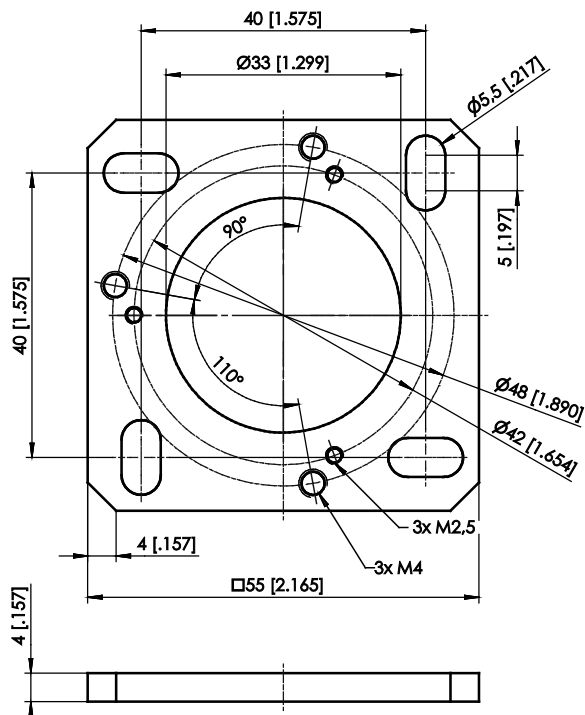
Mounting bracket BFS2



**PRPT-BPL1**

(Screw mounting)

In combination with the mounting clamps PRPT-BFS1 (3 x M2.5) or in combination with the mounting bracket PRPT-BFS2 (3 x M4).

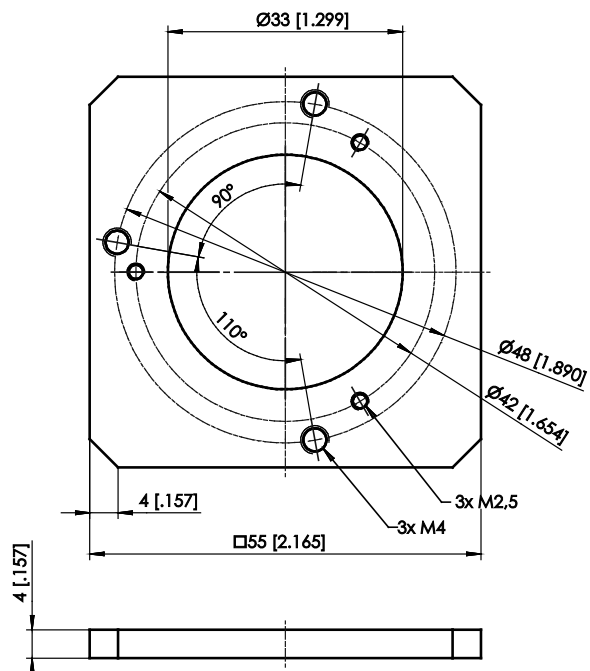


Dimensions in mm [inch]. Weight 30 g approx.  
 Dimensions informative only.  
 For guaranteed dimensions please consult factory.

**PRPT-BPL2**

(Welding assembly)

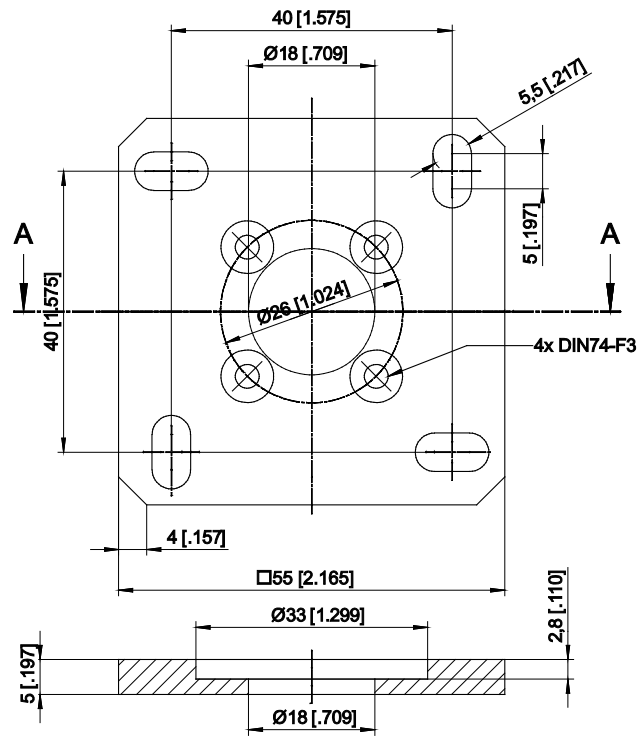
In combination with the mounting clamps PRPT-BFS1 (3 x M2.5) or in combination with the mounting bracket PRPT-BFS2 (3 x M4).



Dimensions in mm [inch]. Weight 30 g approx.  
 Dimensions informative only.  
 For guaranteed dimensions please consult factory.

PRPT-BPL3

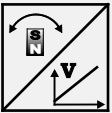
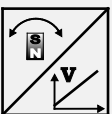
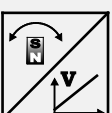
In combination with PRAS3/PRDS3 and frontal mounting.



Dimensions in mm [inch]. Weight 30 g approx.  
 Dimensions informative only.  
 For guaranteed dimensions please consult factory.

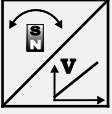
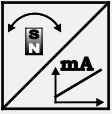
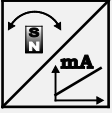
## Output specification

### Analog output

<b>U2</b> Voltage output 0.5 ... 10 V 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 10 mA max. 15 mA
	Output voltage	0.5 ... 10 V DC
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $90^\circ \dots 360^\circ$ ) $\pm 100 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $<90^\circ$ )
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013
	<b>U2B</b> Voltage output 0.5 ... 10 V 	Excitation voltage
Excitation current		typical 12 mA max. 16 mA
Output voltage		0,5 ... 10 V DC
Output current		2 mA max.
Measuring rate		1 kHz standard
Stability (temperature)		$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $90^\circ \dots 360^\circ$ ) $\pm 100 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $<90^\circ$ )
Protection		Reverse polarity, short circuit
Operating temperature		-40 ... +85 °C
EMC		DIN EN 61326-1:2013
<b>U6</b> Voltage output 10 ... 90 % ratiometric 		Excitation voltage
	Excitation current	typical 8 mA max. 12 mA
	Output voltage	10 ... 90 % of the excitation voltage
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $90^\circ \dots 360^\circ$ ) $\pm 100 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $<90^\circ$ )
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013

**Note:**

Excitation voltage for EX sensors: 24 V DC.

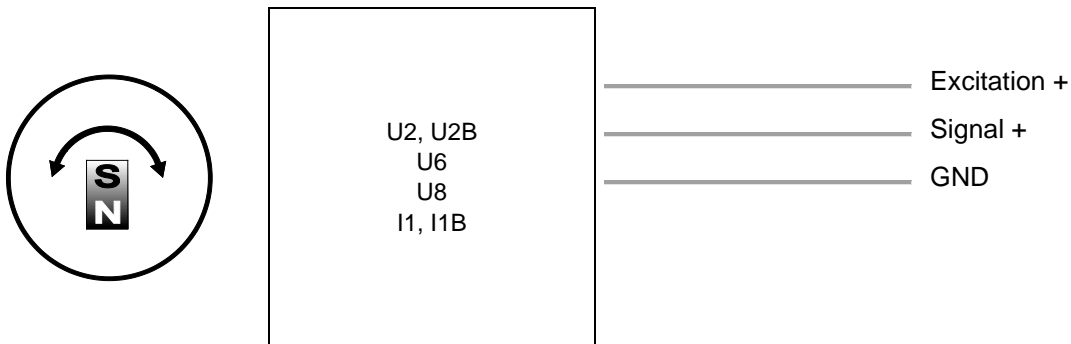
<b>U8</b> Voltage output 0.5 ... 4.5 V 	Excitation voltage	11 ... 36 V DC
	Excitation current	typical 10 mA max. 20 mA
	Output voltage	0.5 ... 4.5 V DC
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $90^\circ \dots 360^\circ$ ) $\pm 100 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $<90^\circ$ )
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013
<b>I1</b> Current output 4 ... 20 mA, 3 wires 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 30 mA max. 35 mA
	Load $R_L$	500 $\Omega$ max.
	Output current	4 ... 20 mA
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $90^\circ \dots 360^\circ$ ) $\pm 100 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $<90^\circ$ )
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013
<b>I1B</b> Current output 4 ... 20 mA, 3 wires 	Excitation voltage	10 ... 27 V DC
	Excitation current	typical 32 mA max. 36 mA
	Load $R_L$	250 $\Omega$ max.
	Output current	4 ... 20 mA
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $90^\circ \dots 360^\circ$ ) $\pm 100 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $<90^\circ$ )
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013

**Note:**

Excitation voltage for EX sensors: 24 V DC.



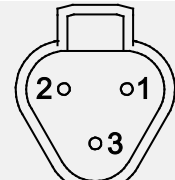
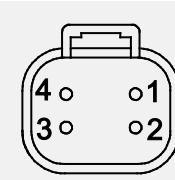
**Signal diagram**



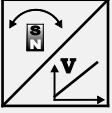
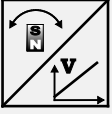
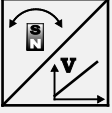
**Signal wiring  
(connector and cable output)**

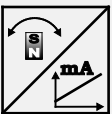
Signal	Connector pin no.	Cable color	View to the sensor connector
Excitation +	1	brown	
Signal	2	white	
GND	3	blue	
Do not connect!	4	black	
Do not connect!	5	grey	

3-wire current 4...20 mA interface: GND has to be connected!

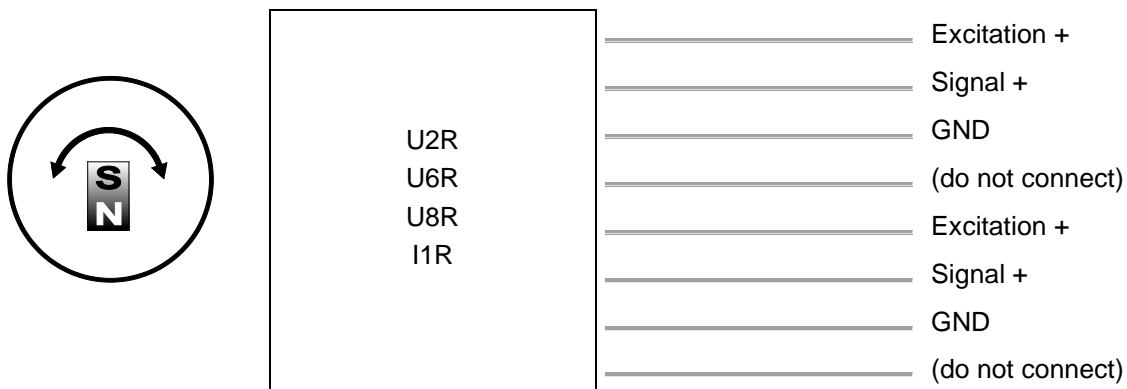
Deutsch connector DT04	 <b>DT04/3P/A</b>	 <b>DT04/4P/A</b>

### Analog output, redundant

<b>U2R</b> Voltage output 0.5 ... 10 V 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 10 mA max. 15 mA per channel
	Output voltage	0.5 ... 10 V DC
	Output current	2 mA max.
	Measuring rate	1 kHz Standard
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $90^\circ \dots 360^\circ$ ) $\pm 100 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $<90^\circ$ )
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013
	<b>U6R</b> Voltage output 10 ... 90 % ratiometric 	Excitation voltage
Excitation current		typical 8 mA max. 12 mA per channel
Output voltage		10 ... 90 % of the excitation voltage
Output current		2 mA max.
Measuring rate		1 kHz standard
Stability (temperature)		$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $90^\circ \dots 360^\circ$ ) $\pm 100 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $<90^\circ$ )
Protection		Reverse polarity, short circuit
Operating temperature		-40 ... +85 °C
EMC		EN 61326-1:2013
<b>U8R</b> Voltage output 0.5 ... 4.5 V 		Excitation voltage
	Excitation current	typical 10 mA max. 20 mA per channel
	Output voltage	0.5 ... 4,5 V DC
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $90^\circ \dots 360^\circ$ ) $\pm 100 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical for $<90^\circ$ )
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013


<b>I1R</b> Current output 4 ... 20 mA, 3 wires 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 30 mA max. 35 mA per channel
	Load R <sub>L</sub>	500 Ω max.
	Output current	4 ... 20 mA
	Measuring rate	1 kHz standard
	Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s. (typical for 90° ... 360°) ±100 x 10 <sup>-6</sup> / °C f.s. (typical for <90°)
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013

**Signal diagram**

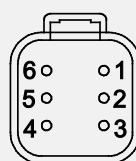


**Signal wiring**

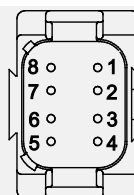
**2 channels, redundant (connector and cable output)**

Channel	Signal	Connector pin no.	Cable color	View to the sensor connector
1	Excitation +	1	white	
1	Signal	2	brown	
1	GND	3	green	
1	Do not connect!	4	yellow	
2	Excitation +	5	grey	
2	Signal	6	pink	
2	GND	7	blue	
2	Do not connect!	8	red	

**Deutsch connector DT04**

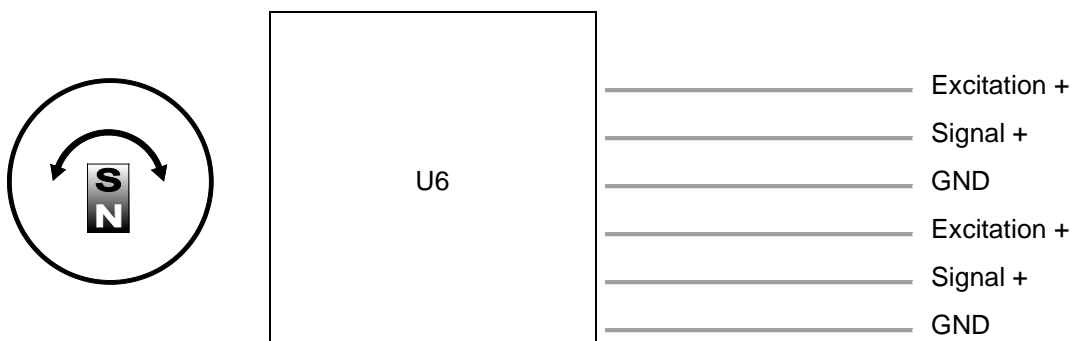


**DT04/6P/A**



**DT04/8P/A**

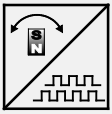
**Signal diagram PRAS20R**



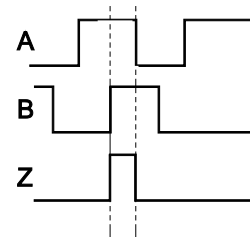
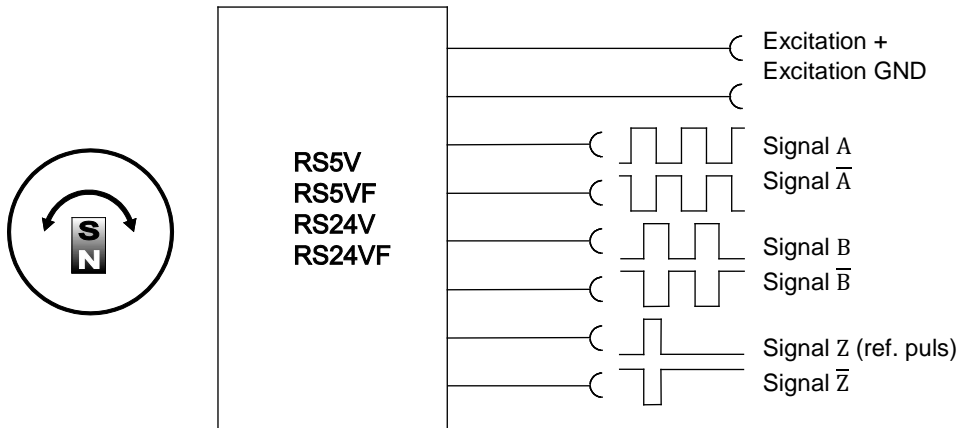
**Signal wiring PRAS20/PRAS20R/PRAS21**

Signal	Cable color
Excitation +	brown
Signal	white
GND	blue

### Incremental output

<b>RS5V(F)/RS24V(F)</b> Incremental 	Interface	EIA RS-422
	Excitation voltage	RS5V(F): 5 V DC $\pm 10\%$ RS24V(F): 10 ... 36 V DC
	Excitation current	100 mA max., depending on the load
	Pulse frequency	<500 kHz
	Output signals	A, $\bar{A}$ , B, $\bar{B}$ , Z, $\bar{Z}$ Push-Pull
	Output current	10 mA max.
	Stability (temperature)	$\pm 50 \times 10^{-6}$ / °C f.s. (typical)
	Operating temperature	-40 ... +85 °C
	Protection	Short circuit
	EMC	DIN EN 61326-1:2013

### Output signals



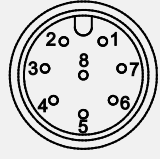
#### Unfiltered output RS5V / RS24V

A preferred maximum pulse frequency has to be defined within the product code. This will take account for limited bandwidth of downstream counter.

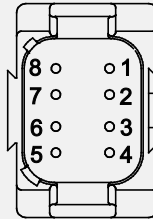
#### Filtered output RS5VF / RS24VF

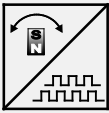
Option for filtered jitter free position value. The filter does not introduce velocity or acceleration error.

**Signal wiring**

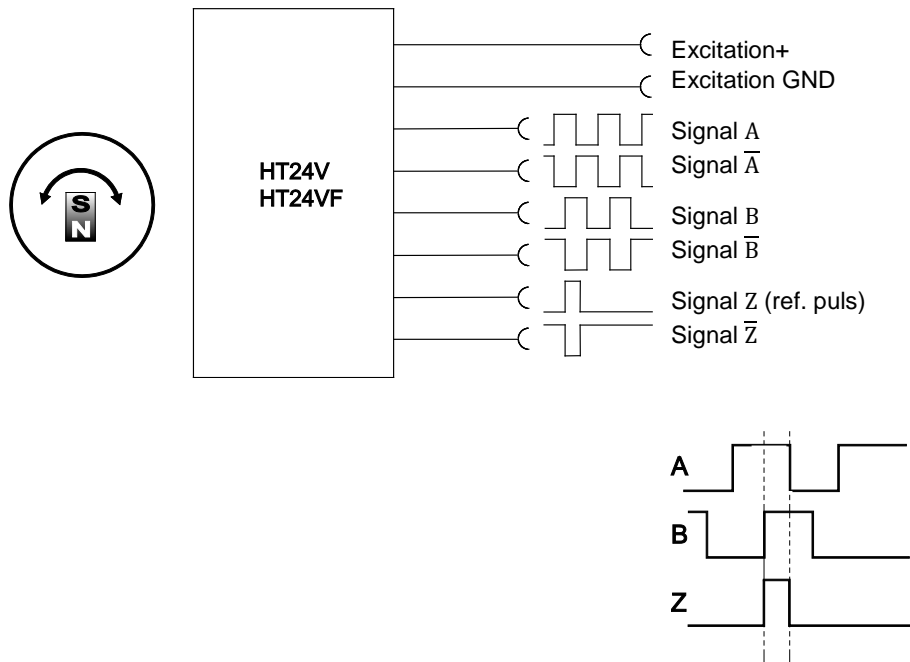
Signal	Connector pin no.	Cable color	View to the sensor connector
Excitation +	1	white	
Excitation GND	2	brown	
A	4	yellow	
$\bar{A}$	6	pink	
B	3	green	
$\bar{B}$	5	grey	
Z	7	blue	
$\bar{Z}$	8	red	

Deutsch connector DT04/8P/A



<b>HT24V(F)</b> Incremental 	Interface	HTL
	Excitation voltage	18 ... 36 V DC
	Excitation current	100 mA max., depending on the load
	Pulse frequency	<500 kHz
	Output signals	A, $\bar{A}$ , B, $\bar{B}$ , Z, $\bar{Z}$ Push-Pull
	Output current	10 mA max.
	Stability (temperature)	$\pm 50 \times 10^{-6}$ / °C f.s. (typical)
	Operating temperature	-40 ... +85 °C
	Protection	Short circuit
	EMC	DIN EN 61326-1:2013

**Output signals**



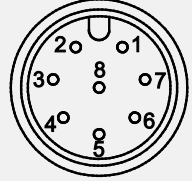
**Unfiltered output HT24V**

A preferred maximum pulse frequency has to be defined within the product code. This will take account for limited bandwidth of downstream counter.

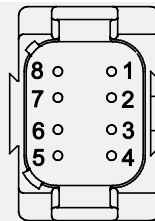
**Filtered output HT24VF**

Option for filtered jitter free position value. The filter does not introduce velocity or acceleration error.

**Signal wiring**


Output signals	Connector pin no.	Cable color	View to the sensor connector
Excitation +	1	white	
Excitation GND	2	brown	
A	4	yellow	
$\bar{A}$	6	pink	
B	3	green	
$\bar{B}$	5	grey	
Z	7	blue	
$\bar{Z}$	8	red	

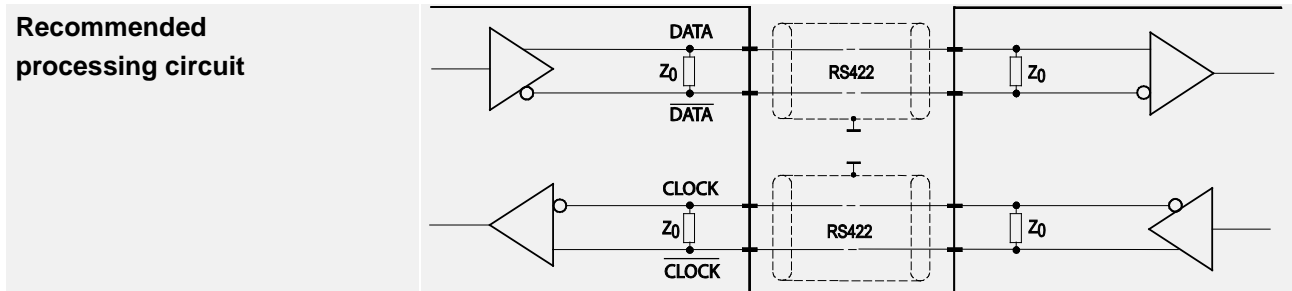
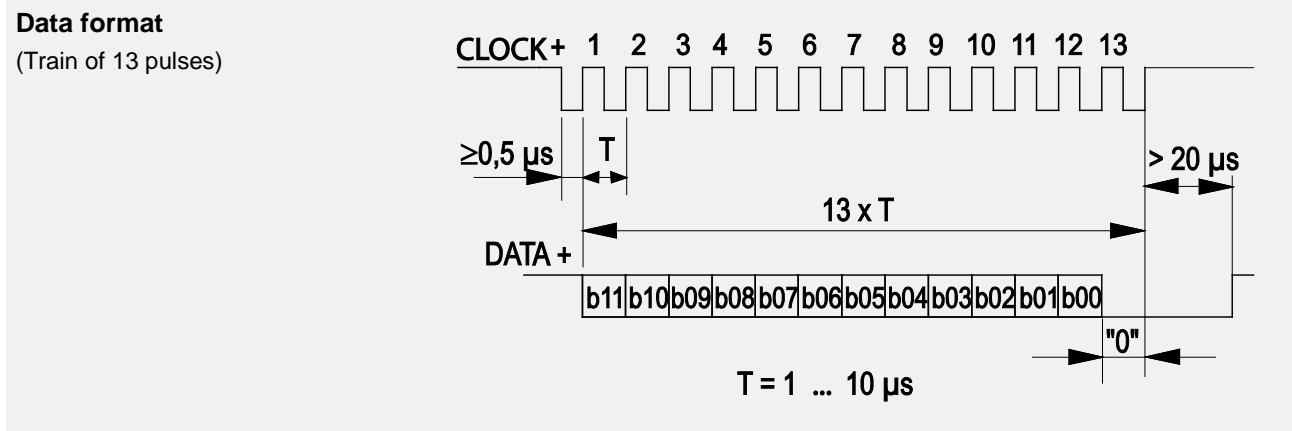
**Deutsch connector DT04/8P/A**





### SSI output

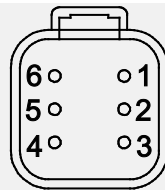
<b>RSSI5V/RSSI24V</b> Synchronous serial SSI 	Interface	EIA RS-422
	Excitation voltage	RSSI5V: 5 V DC ±10% RSSI24V: 10 ... 36 V DC
	Excitation current	100 mA max. without load
	Clock frequency	100 kHz ... 500 kHz
	Code	Gray-Code, continuous progression, 12 bit
	Delay between pulse trains	20 µs min.
	Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s. (typical)
	Operating temperature	-40 ... +85 °C
	Protection	Short circuit
	EMC	EN 61326-1:2013




Transmission rate	Cable length	Baud rate	Note:
	50 m	100 - 1000 kHz	Extension of the cable length will reduce the maximum transmission rate. The signals CLOCK / $\overline{\text{CLOCK}}$ and DATA/ $\overline{\text{DATA}}$ must be connected in a twisted pair cable, shielded per pair and common.
	100 m	100 - 300 kHz	

Signal wiring	Connector pin no.	Cable color	View to the sensor connector
Excitation +	1	brown	
Excitation GND	2	white	
CLOCK	3	green	
$\overline{\text{CLOCK}}$	4	yellow	
DATA	5	grey	
$\overline{\text{DATA}}$	6	pink	
-	7	blue	
-	8	red	

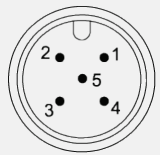
Deutsch connector DT04/6P/A

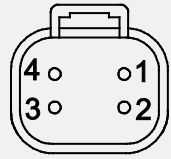



## Digital output CANopen

<b>CANOP</b> CANopen 	CAN Specification	ISO 11898, Basic and Full CAN 2.0 B
	Communication profile	CANopen CiA 301 V 4.02, Slave
	Device profile	Encoder CiA 406 V 3.2
	Configuration services	Layer Setting Service (LSS), CiA Draft Standard 305 (transmission rate, node id)
	Error Control	Node Guarding, Heartbeat, Emergency Message
	Node ID	Default: 127; programmable via LSS or SDO
	PDO	3 TxPDO, 0 RxPDO, static mapping
	PDO Modes	Event-/Time triggered, Remote-request, Sync cyclic/acyclic
	SDO	1 server, 0 Client
	CAM	8 cams
	Certified	Yes
	Transmission rates	50 kBaud to 1 MBaud, default: 125 kBaud; programmable via LSS or SDO
	Bus connection	M12 connector, 5 pin
	Integrated bus terminating resistor	Adjustable by the customer
	Bus, galvanic isolated	No

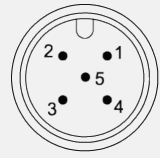
<b>Specifications</b>	Excitation voltage	8 ... 36 V DC
	Excitation current	20 mA typical at 24 V DC 40 mA typical at 12 V DC, 80 mA max.
	Resolution	0.05° max.
	Linearity	1° (optional 0.25°)
	Measuring rate	1 kHz (asynchronous)
	Stability (temperature)	±50 x 10 <sup>-6</sup> /°C f.s. (typical)
	Repeatability	1 LSB
	Operating temperature	See specification of the respective sensor
	Protection	Reverse polarity, short circuit
	Dielectric strength	1 kV (V AC, 50 Hz, 1 min.)
EMC	DIN EN 61326-1:2013	

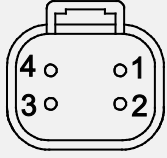
Signal wiring	Signal	Connector pin no.	Cable color	View to the sensor connector
	Shield	1	brown	
	Excitation +	2	white	
	GND	3	blue	
	CAN-H	4	black	
	CAN-L	5	grey	

Signal wiring Deutsch connector DT04/4P/A	Signal	Connector pin no.	View to the sensor connector
	Excitation+	1	
	CAN-H	2	
	GND	3	
	CAN-L	4	


<b>CANOPR</b> CANopen 	CAN Specification	ISO 11898, Basic and Full CAN 2.0 B
	Communication profile	CANopen CiA 301 V 4.02, Slave
	Device profile	Encoder CiA 406 V 3.2
	Configuration services	Layer Setting Service (LSS), CiA Draft Standard 305 (transmission rate, node id)
	Error Control	Node Guarding, Heartbeat, Emergency Message
	Node ID	Default: 127 and 126; programmable via LSS or SDO
	PDO	3 TxPDO, 0 RxPDO, static mapping
	PDO Modes	Event-/Time triggered, Remote-request, Sync cyclic/acyclic
	SDO	1 server, 0 Client
	CAM	8 cams
	Certified	Yes
	Transmission rates	50 kBaud to 1 MBaud, default: 125 kBaud; programmable via LSS or SDO
	Bus connection	M12 connector, 5 pin
	Integrated bus terminating resistor	adjustable by the customer
Bus, galvanic isolated	No	

<b>Specifications</b>	Excitation voltage	8 ... 36 V DC
	Excitation current	40 mA typical at 24 V DC 80 mA typical at 12 V DC, 120 mA max.
	Resolution	0.05° max.
	Linearity	1° (0.25° optional)
	Measuring rate	1 kHz (asynchronous)
	Stability (temperature)	$\pm 50 \times 10^{-6} / ^\circ\text{C}$ f.s. (typical)
	Repeatability	1 LSB
	Operating temperature	See specification of the respective sensor
	Protection	Reverse polarity, short circuit
	Dielectric strength	1 kV (V AC, 50 Hz, 1 min.)
	EMC	DIN EN 61326-1:2013

Signal wiring	Signal	Connector pin no.	Cable color	View to the sensor connector
	Shield	1	brown	
	Excitation +	2	white	
	GND	3	blue	
	CAN-H	4	black	
	CAN-L	5	grey	

Signal wiring Deutsch connector DT04/4P/A	Signal	Connector pin no.	View to the sensor connector
	Excitation+	1	
	CAN-H	2	
	GND	3	
	CAN-L	4	

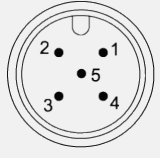
## Digital output CAN SAE J1939

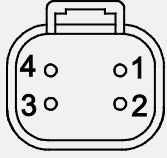
<b>CANJ1939</b> CAN SAE J1939 	CAN Specification	ISO 11898, Basic and Full CAN 2.0 B
	Transceiver	24V-compliant, not isolated
	Communication profile	SAE J1939
	Baud Rate	250 kbit/s
	Internal termination resistor	adjustable by the customer
	Address	Default 247d, configurable


<b>NAME Fields</b>	Arbitrary address capable	1	Yes
	Industry group	0	Global
	Vehicle system	7Fh (127d)	Non specific
	Vehicle system instance	0	
	Function	FFh (255d)	Non specific
	Function instance	0	
	ECU instance	0	
	Manufacturer	145h (325d)	Manufacturer ID
	Identity number	0nnn	Serial number 21 bit

<b>Parameter Group Numbers (PGN)</b>	Configuration data	PGN EF00h	Proprietary-A (PDU1 peer-to-peer)
	Process data	PGN FFnnh	Proprietary-B (PDU2 broadcast); nn Group Extension (PS) configurable

<b>Specifications</b>	Excitation voltage	8 ... 36 V DC
	Excitation current	20 mA typical at 24 V DC 40 mA typical at 12 V DC, 80 mA max.
	Resolution	0.05° max.
	Linearity	1° (0.25° optional)
	Measuring rate	1 kHz (asynchronous)
	Stability (temperature)	±50 x 10 <sup>-6</sup> /°C f.s. (typical)
	Repeatability	1 LSB
	Operating temperature	See specification of the respective sensor
	Protection	Reverse polarity, short circuit
	Dielectric strength	1 kV (V AC, 50 Hz, 1 min.)
	EMV	DIN EN 61326-1:2013

Signal wiring	Signal	Connector pin no.	View to the sensor connector
	Shield	1	
	Excitation +	2	
	GND	3	
	CAN-H	4	
	CAN-L	5	

<b>Signal wiring</b> <b>Deutsch connector</b> <b>DT04/4P/A</b>	<b>Signal</b>	<b>Connector pin no.</b>	<b>View to the sensor connector</b>
	Excitation+	1	
	CAN-H	2	
	GND	3	
	CAN-L	4	

<b>CANJ1939R</b> CAN SAE J1939 	CAN Specification	ISO 11898, Basic and Full CAN 2.0 B
	Transceiver	24V-compliant, not isolated
	Communication profile	SAE J1939
	Baud Rate	250 kbit/s
	Internal termination resistor	Adjustable by the customer
	Address	Default 247d and 246d, configurable

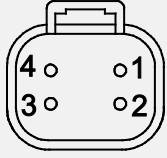
<b>NAME Fields</b>	Arbitrary address capable	1	Yes
	Industry group	0	Global
	Vehicle system	7Fh (127d)	Non specific
	Vehicle system instance	0	
	Function	FFh (255d)	Non specific
	Function instance	0	
	ECU instance	0	
	Manufacturer	145h (325d)	Manufacturer ID
	Identity number	0nnn	Serial number 21 bit

<b>Parameter Group Numbers (PGN)</b>	Configuration data	PGN EF00h	Proprietary-A (PDU1 peer-to-peer)
	Process data	PGN FFnnh	Proprietary-B (PDU2 broadcast); nn Group Extension (PS) configurable

<b>Specifications</b>	Excitation voltage	8 ... 36 V DC
	Excitation current	40 mA typical at 24 V DC 80 mA typical at 12 V DC, 120 mA max.
	Resolution	0.05° max.
	Linearity	1° (0.25° optional)
	Measuring rate	1 kHz (asynchronous)
	Stability (temperature)	±50 x 10 <sup>-6</sup> /°C f.s. (typical)
	Repeatability	1 LSB
	Operating temperature	See specification of the respective sensor
	Protection	Reverse polarity, short circuit
	Dielectric strength	1 kV (V AC, 50 Hz, 1 min.)
EMV	DIN EN 61326-1:2013	

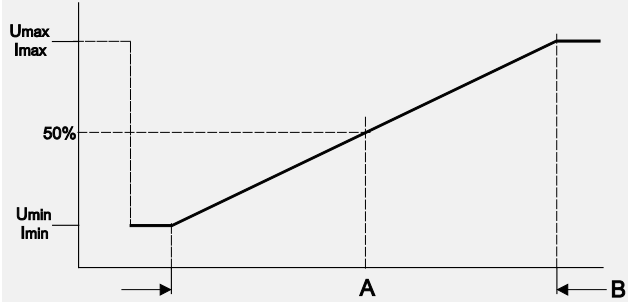
Signal wiring	Signal	Connector Pin no.	Cable color	View to the sensor connector
	Shield	1	brown	
	Excitation +	2	white	
	GND	3	blue	
	CAN-H	4	black	
	CAN-L	5	grey	



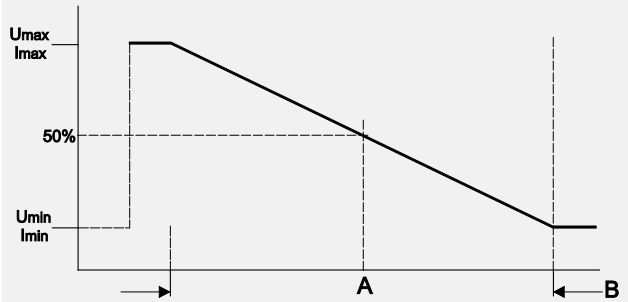
<b>Signal wiring</b> <b>Deutsch connector</b> <b>DT04/4P/A</b>	<b>Signal</b>	<b>Connector pin no.</b>	<b>View to the sensor connector</b>
	Excitation+	1	
	CAN-H	2	
	GND	3	
	CAN-L	4	

### Characteristics for magnetic angle sensors

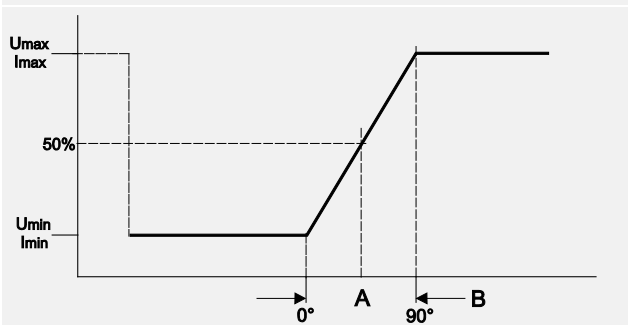
**Output signal CW**  
(clockwise increasing)



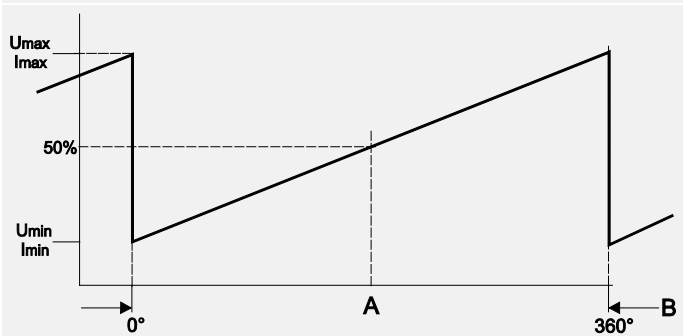
**Output signal CCW**  
(counterclockwise increasing)



Example angular range 90°



Example angular range 360°



A – Marking  
B – Measurement range [°]

**Accessories**

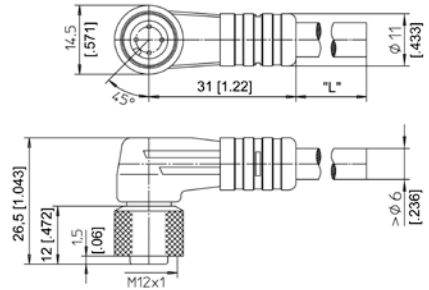
**Connector cable M12, 4 pin**

**(angular coupling)**

shielded connector

Suitable for 5-pin sensor connectors

The 4-core screened cable is supplied with a mating 4-pin 90° M12 connector at one end and 4 wires at the other end. Available lengths are 2 m, 5 m and 10 m. Wire: cross sectional area 0.34 mm<sup>2</sup> Cable diameter: 5.6 ±0.2 mm



**Order code**

**KAB - xM - M12/4F/W - LITZE**

IP69: **KAB - xM - M12/4F/W/69K - LITZE**

xM = length in m

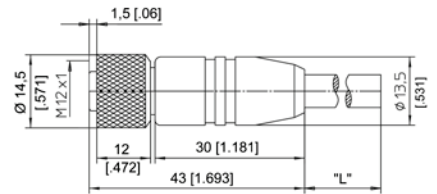
**Connector cable M12, 4 pin**

**(straight coupling)**

shielded connector

Suitable for 5-pin sensor connectors

The 4-core screened cable is supplied with a mating 4-pin M12 connector at one end and 4 wires at the other end. Available lengths are 2 m, 5 m and 10 m. Wire: cross sectional area 0.34 mm<sup>2</sup> Cable diameter: 5.6 ±0.2 mm



**Order code**

**KAB - xM - M12/4F/G - LITZE**

IP69: **KAB - xM - M12/4F/G/69K - LITZE**

xM = length in m

Signal wiring	Plug connection / cable color			
	1	2	3	4
M12, 4 pin	brown	white	blue	black

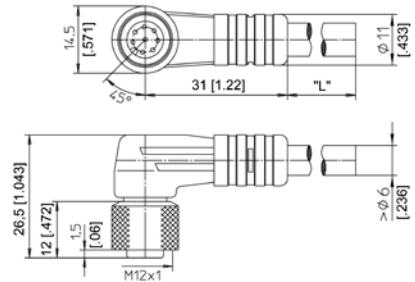
**Applicable for cable carriers**

Maximum movement speed	3 m/s
Maximum acceleration	5 m/s <sup>2</sup>
Minimum bending radius	10 x cable diameter

**Connector cable M12, 8 pin  
(angular coupling)**

shielded connector

The 8-lead shielded cable is supplied with a mating 8-pin 90° M12 connector at one end and 8 wires at the other end. Available lengths are 2 m, 5 m and 10 m. Wire: cross sectional area 0.25 mm<sup>2</sup> Cable diameter: 6.3 ±0.2 mm



**Order code**

**KAB - xM - M12/8F/W - LITZE**

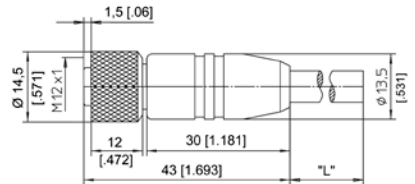
IP69: **KAB - xM - M12/8F/W/69K - LITZE**

xM = length in m

**Connector cable M12, 8 pin  
(straight coupling)**

shielded connector

The 8-lead shielded cable is supplied with a mating 8-pin M12 connector at one end and 8 wires at the other end. Available lengths are 2 m, 5 m and 10 m. Wire: cross sectional area 0.25 mm<sup>2</sup> Cable diameter: 6.3 ±0.2 mm



**Order code**

**KAB - xM - M12/8F/G - LITZE**

IP69: **KAB - xM - M12/8F/G/69K - LITZE**

xM = length in m

Signal wiring M12, 8 pin	Plug connection / cable color							
	1	2	3	4	5	6	7	8
	white	brown	green	yellow	grey	pink	blue	red

**Applicable for cable carriers**

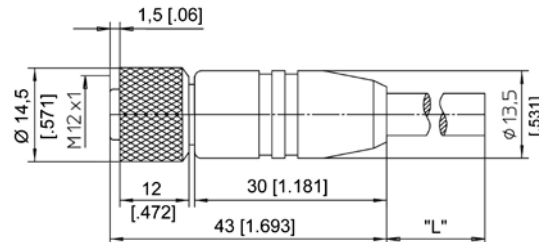
Maximum movement speed	3 m/s
Maximum acceleration	5 m/s <sup>2</sup>
Minimum bending radius	10 x cable diameter

## Connector/bus cable M12, 5 pin CAN-Bus

The 5-lead shielded cable is supplied with a female 5 pin M12 connector at one end and a male 5 pin M12 connector at the other end.

Available lengths are 0.3 m, 2 m, 5 and 10 m.

Cable diameter: 6.7 ±0.2 mm



Order code:

**KAB - xM - M12/5F/G - M12/5M/G - CAN**

IP69: **KAB - xM - M12/5F/G/69K - M12/5M/G/69K - CAN**

xM = length in m

## T-connector for bus cable M12, 5 pin CAN-Bus

Order code:

**KAB - TCONN - M12/5M - 2M12/5F - CAN**



## Terminating resistor M12, 5 pin CAN-Bus

Order code:

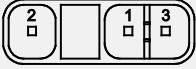
**KAB - RTERM - M12/5M/G - CAN**



### Applicable for cable carriers

Maximum movement speed	3 m/s
Maximum acceleration	5 m/s <sup>2</sup>
Minimum bending radius	10 x cable diameter

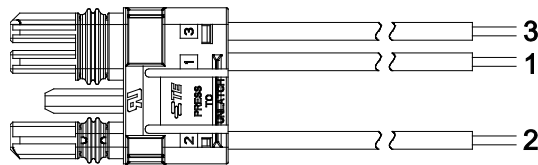
**PRAS26 – connector TE3**  
**Signal wiring**

Signal	Connector pin no.	View to sensor connector TE3
GND	1	
Excitation +	2	
Signal	3	

Mating connector: Tyco Electronics,  
SlimSeal, Part-Nr. 2106135-3, 3-pin

**PRAS26 – connector 3-pin with connecting leads**

This cable is supplied with a male 3-pin connector at one end and 3 wires at the other end.  
Cross section 0.32 mm<sup>2</sup>. Wire length 0.5 m.



Order code

**CONN-TE-3F-G-LITZE-0,5M**

Signal wiring 3-pin connector	Connector pin no. / connecting leads		
	1 blue	2 brown	3 white

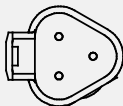
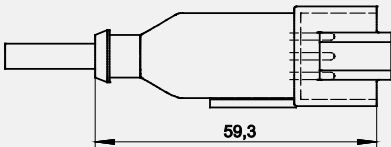
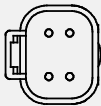
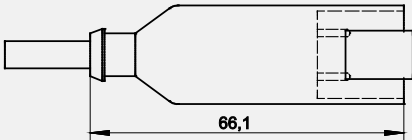
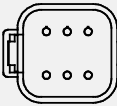
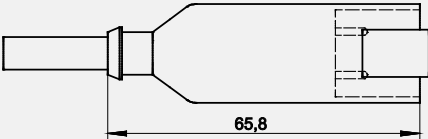
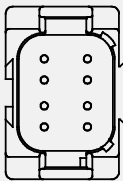
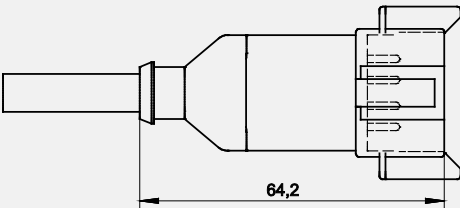
## Deutsch connector

Sensors with cable output can be delivered with Deutsch connector.

- Protection class: IP67 (while plugged)
- Connection: 3, 4, 6, 8 poles – depending on output, see table below
- Wire cross sectional area: 0.5 mm<sup>2</sup>
- Standard cable length: 2 m
- Protective cable tube: for a better mechanical protection the cable can be delivered with a protective tube



### Deutsch connector – table

Number of poles	Deutsch connector DT04		Output
3 pin			U6
4 pin			U2, U2B, U8 I1, I1B CANOP(R), CANJ1939(R)
6 pin			U6R RSSI5V RSSI24V
8 pin			U2R, U8R I1R RS5VF, RS24VF HT24VF

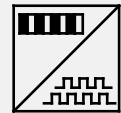
## PMIS4, PMIR5

### Magnetic incremental encoder



#### Magnetic wheels for rotative applications

- All metal housing
- Protection class IP67
- Excellent protection of the active measurement area
- Highest EMC protection
- Suitable for harsh environments
- Up to 327,680 pulses/360°



#### Specifications

<b>Output</b>	Incremental encoder output A/B with differential push-pull output, TTL/24 V-, TTL/RS-422- or HTL-compatible
<b>Excitation voltage</b>	10 ... 30 VDC oder 5 VDC ±5%
<b>Excitation current</b>	300 mA max.
<b>Magnetic period of the sensor</b>	5 mm
<b>Guided spacing between sensor and wheel <math>x_z</math></b>	0.1 ... 2 mm
<b>Side tracking tolerance of the sensor</b>	±1 mm
<b>Linearity (sensor with mag. wheel)</b>	0.1°
<b>Repeatability</b>	±1 Digit
<b>Maximum pulse frequency <math>f_p</math></b>	50 kHz, 20 kHz, 10 kHz (standard 50 kHz, max. 480 kHz)
<b>Output signals</b>	A, $\bar{A}$ , B, $\bar{B}$ / signal Z, $\bar{Z}$ (optional) / status signal $\bar{ERR}$ (optional)
<b>Material of housing</b>	Zinc die casting
<b>Connection</b>	Cable 8 wire, dia. 5 mm, open cable end. 15 pin D-Sub connector at the cable end as option. Max. length of the integrated sensor cable: output TTL: 3 m; HTL/TTL24V: 20 m
<b>Weight</b>	30 g ±5 g (without cable and connector)
<b>Protection class (EN 60529)</b>	IP67
<b>Shock</b>	DIN EN 60068-2-27:1993, 50 g 6 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:1995, 20 g, 10-2000 Hz, 10 cycles
<b>EMC</b>	DIN EN 61326-1:2013
<b>Temperature</b>	-40 ... +85°C



**Order code sensor head PMIS4**

PMIS4 – 1 – 2 – 3 – 4 – 5 – 6 – 7

**1 Magnetic period**

50 = 5 mm

**2 Scaling factor**

See table\*

**3 Maximum pulse frequency (in kHz, standard 50 kHz)**

50 / 20 / 10 (other frequencies on request, max. 480 kHz)

**4 Output**

HTL = HTL output with excitation 24 V DC, output 24 V  
 TTL = TTL output with excitation 5 V DC, output TTL/RS422  
 TTL24V = TTL output with excitation 24 V DC, output TTL/10 mA

**5 Signal Z / status signal**

Z0 = A/B without signal Z  
 Z1 = A/B with signal Z  
 Z3 = A/B with signal Z and status signal, only for non-differential outputs (single-ended)

**6 Cable length**

2M = Standard 2 m

**7 Connection**

S = open cable end  
 P15 = D-Sub connector at the cable end, 15 pin

**Order example sensor head**

**PMIS4 – 50 – 100 – 50KHZ – HTL – Z0 – 2M – S**

\*Table “Scaling factor sensor PMIS4-50...” (see page 167)



The subsequent counting device must be able to process the specified maximum pulse frequency of the sensor.

### Output signals

<b>Saturation voltage</b>	UH, UL = 0,2 V UH, UL = 0,4 V C <sub>last</sub> < 10 nF	I <sub>out</sub> = ±10 mA (UH = UB - U <sub>out</sub> ) I <sub>out</sub> = ±30 mA
<b>Short circuit current</b>	ISL, ISH < 800 mA ISL, ISH < 90 mA	(UH, UL = 0 V) (UH, UL = 1,5 V)
<b>Rise time</b>	tr, tf < 200 ns	with cable length 1 m, 10 % ... 90 %

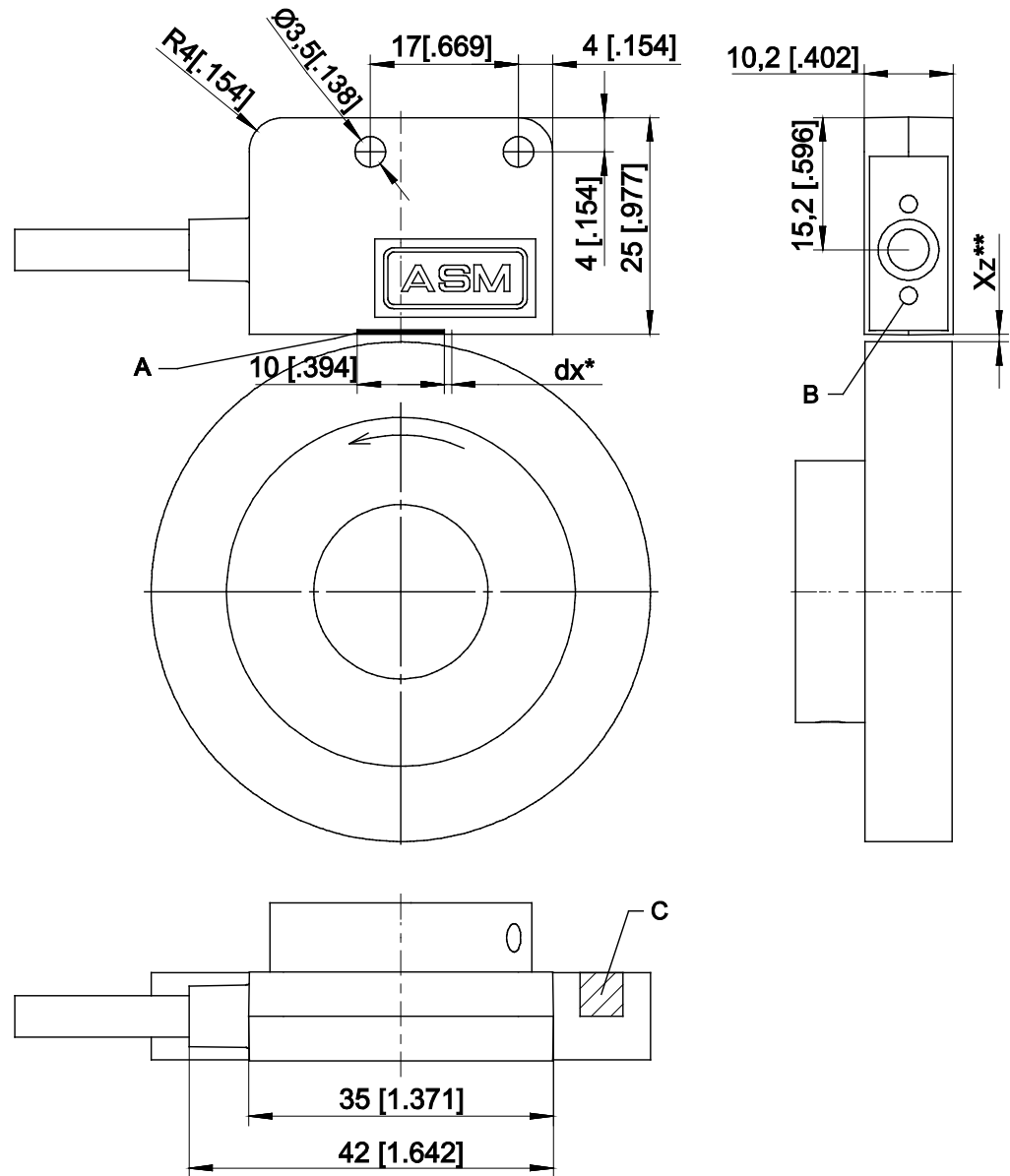
### Pulse frequency in dependence on the cable length

Load/cable length	Load/pulse frequency fp		
	HTL single ended UB = 24 V	TTL/RS422 differential UB = 5 V *	TTL/24 V UB = 24 V
Max. output current	50 mA	50 mA	10 mA
R <sub>last</sub> min.	500 Ω	100 Ω	500 Ω
C <sub>last</sub> max.	10 nF	10 nF	1 nF
200 m	15 kHz	—	—
100 m	25 kHz	100 kHz	—
50 m	50 kHz	200 kHz	50 kHz
10 m	100 kHz	300 kHz	100 kHz
	50 mA	50 mA	10 mA

\* = consider the voltage loss of the cable; the excitation voltage 5 V ± 5% of the sensor must be guaranteed.

Note: For longer distances (see specification above) you must use min. 0.5 mm<sup>2</sup> wire for „Excitation+“ and „Excitation GND“ (see signal wiring), all signal wires must be min. 0.14 mm<sup>2</sup>!

**Dimensions PMIS4**



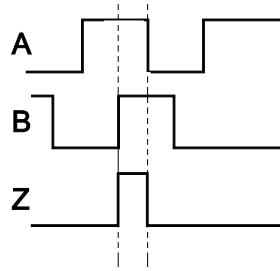
A – Active measurement area  
B – Status signal (LED)  
C – Index mark

\* = position tolerance of the active measurement area:  $dx = \pm 1$  mm  
\*\* = less masking tape

Dimensions in mm [inch]  
Dimensions informative only.  
For guaranteed dimensions please consult factory.

**Output signals**

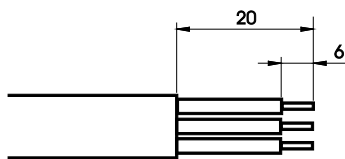
**Option Z1  
(Signal Z)**



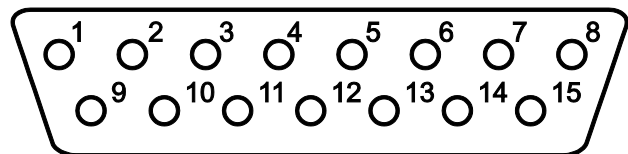
**Signal wiring/ connection**

Signal name				Cable with open end, cable color	Connector D-Sub, 15 pin
Option	Z0	Z1	Z3*		
	Excitation +			white	1
	Excitation GND (0V)			brown	2
	B	B	B	green	6
	A	A	A	yellow	4
	$\bar{B}$	$\bar{B}$	$\bar{ERR}$	grey	7
	$\bar{A}$	$\bar{A}$	–	pink	5
	–	Z	Z	blue	8
	–	$\bar{Z}$	–	red	9
	Shield			black	12

- Z = Reference pulse
- $\bar{ERR}$  = status signal, periodical approx. 16 Hz, for side tracking and velocity errors
- \* = status signal ERR available only with HTL (single ended) output



Cable output dimensions, open end



Connector D-Sub (Pin)  
View to connector pins

**PMIR5 - Incremental magnetic rings**

**Specifications PMIR5**

<b>Material</b>	Plastic bonded magnetic scale
<b>Base material</b>	Aluminium, stainless steel
<b>Signal periods per revolution</b>	64 / 96 / 160 poles per revolution
<b>Magnetic period</b>	5 mm
<b>Temperature range</b>	-40 ...+120°C
<b>Linearity with sensor PMIS4</b>	Approx. ± 0.1°

**Standard magnetic rings**

Type	Poles	Ø	Width	Signal periods/revolution	Inner diameter Ø
PMIR5-50-64-O/M-83	64	102.3	14	Divisions see table below	Ø83 H7
PMIR5-50-96-O/M-133	96	153.2	14	Divisions see table below	Ø133 H7
PMIR5-50-160-O/M-233	160	255.1	14	Divisions see table below	Ø233 H7

Position magnet rings with other number of poles, diameters or magnetic periods on request.

Scaling factor sensor PMIS4-50- ...	PMIR5-50-64-O/M-83		PMIR5-50-96-O/M-133		PMIR5-50-160-O/M-233	
	Signal periods	r.p.m. 1/min * (at 480 kHz)	Signal periods	r.p.m. 1/min * (at 480 kHz)	Signal periods	r.p.m. 1/min (at 480 kHz) *
1	64	3000	96	3000	160	3000
2	128	3000	192	3000	320	3000
4	256	3000	384	3000	640	3000
8	512	3000	768	3000	1280	3000
10	640	3000	960	3000	1600	1800
16	1024	3000	1536	3000	2560	3000
20	1280	3000	1920	3000	3200	1800
25	1600	3000	2400	3000	4000	2880
32	2048	3000	3072	3000	5120	3000
40	2560	3000	3840	3000	6400	1800
50	3200	3000	4800	3000	8000	2880
64	4096	3000	6144	3000	10 240	2250
80	5120	3000	7680	3000	12 800	1800
100	6400	3000	9600	2400	16 000	1440
125	8000	2880	12 000	1920	20 000	1152
128	8192	2813	12 288	1875	20 480	1125
200	12 800	1800	19 200	1200	32 000	720
250	16 000	1440	24 000	960	40 000	576
256	16 384	1406	24 576	938	40 960	563
400	25 600	900	38 400	600	64 000	360
500	32 000	720	48 000	480	80 000	288
512	32 768	703	49 152	469	81 920	281
1024	65 536	352	98 304	234	163 840	141
2048	131 072	176	196 608	117	327 680	70

\* Maximum revolution per minute mechanically 3,000 r.p.m.

**Order code magnetic ring PMIR5**

PMIR5 - 1 - 2 - 3 - 4 - 5

**1 Magnetic period**

50 = 5 mm

**2 Number of poles**

64 / 96 / 160 (other pole numbers on request)

**3 Z signal mark**

O = without

M = with

**4 Inner diameter**

83/133/233 (depending on the number of poles, see table)

**5 Option**

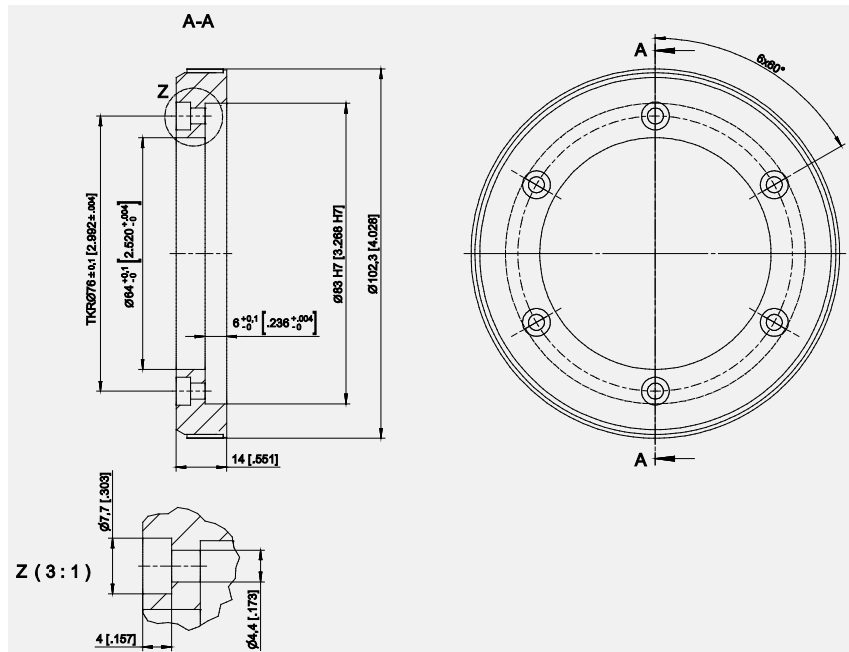
AB = Masking tape

**Order example magnetic ring**

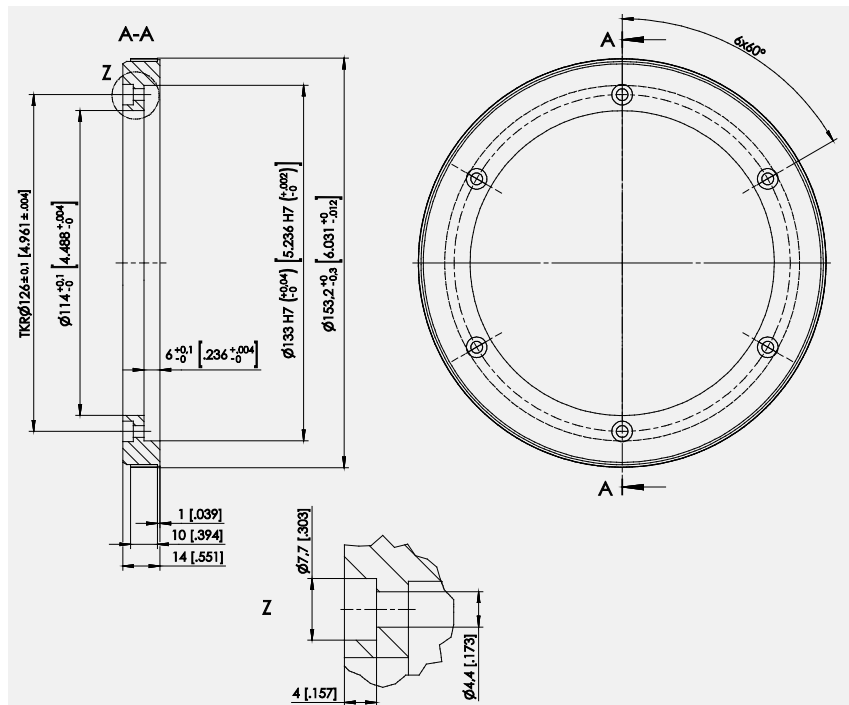
PMIR5 - 50 - 64 - M - 83 - AB

**Magnetic rings PMIR5**

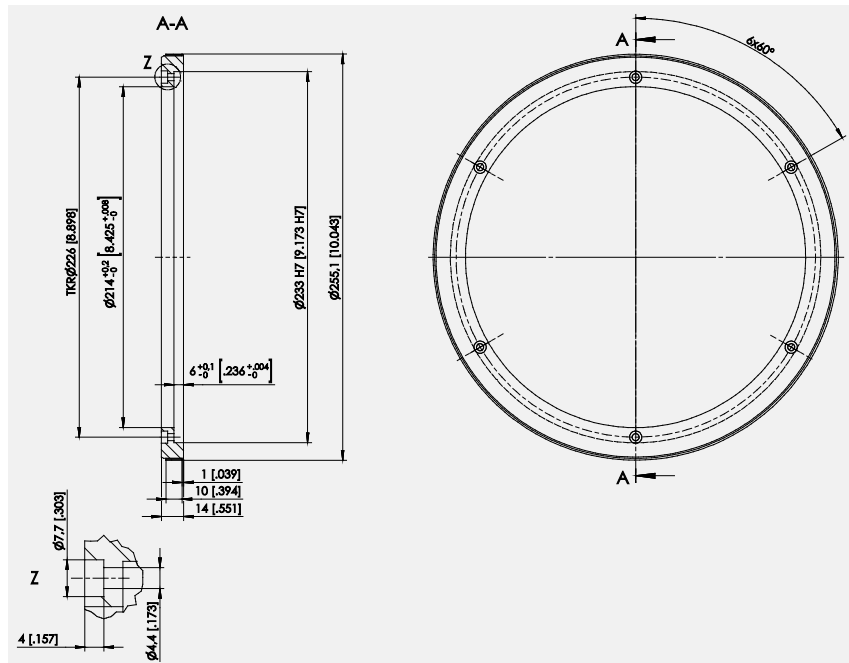
**PMIR5-50-64-O/M-83**



**PMIR5-50-96-O/M-133**



**PMIR5-50-160-O/M-233**



Dimensions in mm [inch].  
 Dimensions informative only.  
 For guaranteed dimensions consult factory.

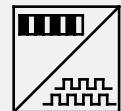


**PMIS4, PMIR7, PMIR7N**  
**Magnetic incremental encoder**



**Magnetic wheels for rotative applications**

- All metal housing
- Protection class IP67
- Excellent protection of the active measurement area
- Highest EMC protection
- Suitable for harsh environments
- Up to 184,320 pulses/360°



**Specifications**

<b>Output</b>	Incremental encoder output A/B with differential push-pull output, TTL/24 V-, TTL/RS-422- or HTL-compatible
<b>Excitation voltage</b>	10 ... 30 VDC oder 5 VDC ±5%
<b>Excitation current</b>	300 mA max.
<b>Magnetic period of the sensor</b>	2 mm
<b>Guided spacing between sensor and wheel <math>x_z</math></b>	0.1 ... 0,8 mm
<b>Side tracking tolerance of the sensor</b>	±1 mm
<b>Linearity (sensor with mag. wheel PMIR4)</b>	0.1°
<b>Repeatability</b>	±1 Digit
<b>Maximum pulse frequency <math>f_p</math></b>	50 kHz, 20 kHz, 10 kHz (standard 50 kHz, max. 480 kHz)
<b>Output signals</b>	A, $\bar{A}$ , B, $\bar{B}$ / signal Z, $\bar{Z}$ (optional) / status signal $\bar{ERR}$ (optional)
<b>Material of housing</b>	Zinc die casting
<b>Connection</b>	Cable 8 wire, dia. 5 mm, open cable end. 15 pin D-Sub connector at the cable end as option. Max. length of the integrated sensor cable: output TTL: 3 m; HTL/TTL24V: 20 m
<b>Weight</b>	30 g ±5 g (without cable and connector)
<b>Protection class (EN 60529)</b>	IP67
<b>Shock</b>	DIN EN 60068-2-27:1993, 50 g 6 ms, 100 shocks
<b>Vibration</b>	DIN EN 60068-2-6:1995, 20 g, 10-2000 Hz, 10 cycles
<b>Temperature</b>	-40 ...+85°C
<b>EMC</b>	DIN EN 61326-1:2013

**Order code sensor head PMIS4**

PMIS4 – 1 – 2 – 3 – 4 – 5 – 6 – 7

**1 Magnetic period**

20 = 2 mm

**2 Scaling factor**

See table\*

**3 Maximum pulse frequency (in kHz, standard 50 kHz)**

50 / 20 / 10 (other frequencies on request, max. 480 kHz)

**4 Output**

HTL = HTL output with excitation 24 V DC, output 24 V  
TTL = TTL output with excitation 5 V DC, output TTL/RS422  
TTL24V = TTL output with excitation 24 V DC, output TTL/10 mA

**5 Signal Z / status signal**

Z0 = A/B without signal Z  
Z1 = A/B with signal Z  
Z3 = A/B with signal Z and status signal, only for non-differential (single-ended) outputs

**6 Cable length**

2M = Standard 2 m

**7 Connection**

S = open cable end  
P15 = D-Sub connector at the cable end, 15 pin

**Order example sensor head**

PMIS4 – 20 – 100 – 50KHZ – HTL – Z0 – 2M – S

\*Table “Scaling factor sensor PMIS4-50...” (see page 175)



The subsequent counting device must be able to process the specified maximum pulse frequency of the sensor.

### Output signals

<b>Saturation voltage</b>	UH, UL = 0,2 V UH, UL = 0,4 V C <sub>last</sub> < 10 nF	I <sub>out</sub> = ±10 mA (UH = UB - U <sub>out</sub> ) I <sub>out</sub> = ±30 mA
<b>Short circuit current</b>	ISL, ISH < 800 mA ISL, ISH < 90 mA	(UH, UL = 0 V) (UH, UL = 1,5 V)
<b>Rise time</b>	tr, tf < 200 ns	with cable length 1 m, 10 % ... 90 %

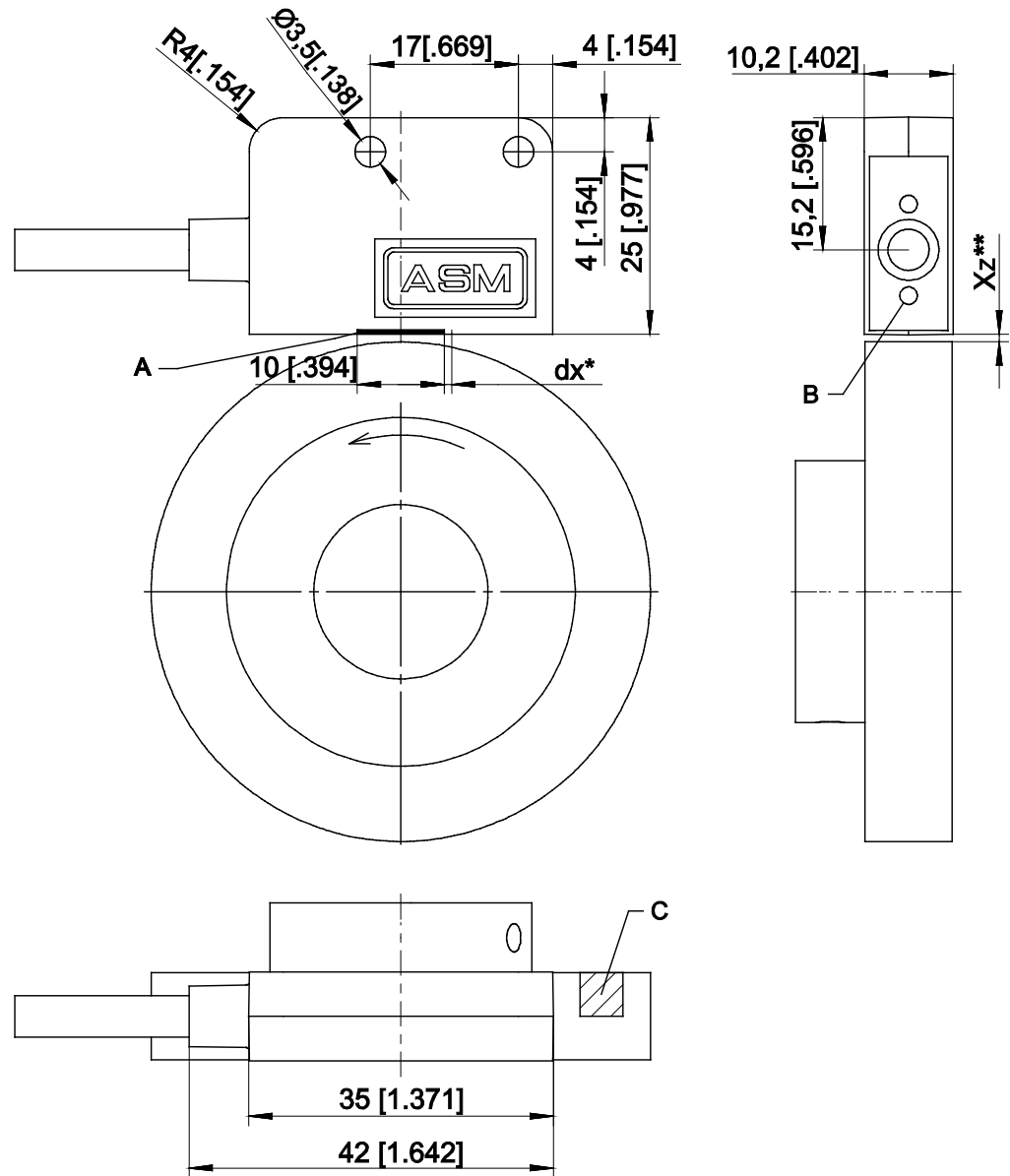
### Pulse frequency in dependence on the cable length

Load/cable length	Load/pulse frequency fp		
	HTL single ended UB = 24 V	TTL/RS422 differential UB = 5 V *	TTL/24 V UB = 24 V
Max. output current	50 mA	50 mA	10 mA
R <sub>last</sub> min.	500 Ω	100 Ω	500 Ω
C <sub>last</sub> max.	10 nF	10 nF	1 nF
200 m	15 kHz	—	—
100 m	25 kHz	100 kHz	—
50 m	50 kHz	200 kHz	50 kHz
10 m	100 kHz	300 kHz	100 kHz
	50 mA	50 mA	10 mA

\* = consider the voltage loss of the cable; the excitation voltage 5 V ± 5% of the sensor must be guaranteed.

Note: For longer distances (see specification above) you must use min. 0.5 mm<sup>2</sup> wire for „Excitation+“ and „Excitation GND“ (see signal wiring), all signal wires must be min. 0.14 mm<sup>2</sup>!

**Dimensions PMIS4**



A – Active measurement area  
 B – Status signal (LED)  
 C – Index mark

\* = position tolerance of the active measurement area:  $dx = \pm 1 \text{ mm}$   
 \*\* = less masking tape

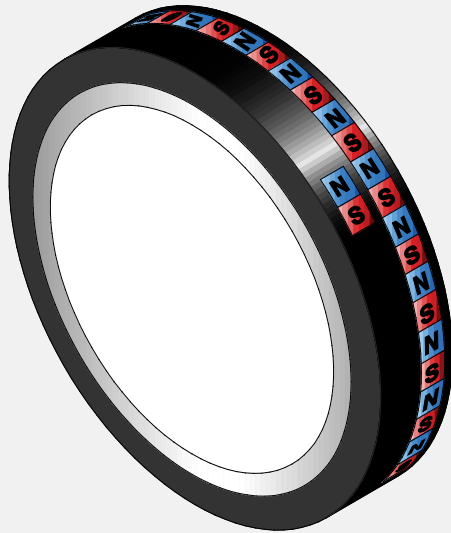
Dimensions in mm [inch]  
 Dimensions informative only.  
 For guaranteed dimensions please consult factory.

**PMIR7(N) - Incremental magnetic rings**

**Specifications PMIR7, PMIR7N**

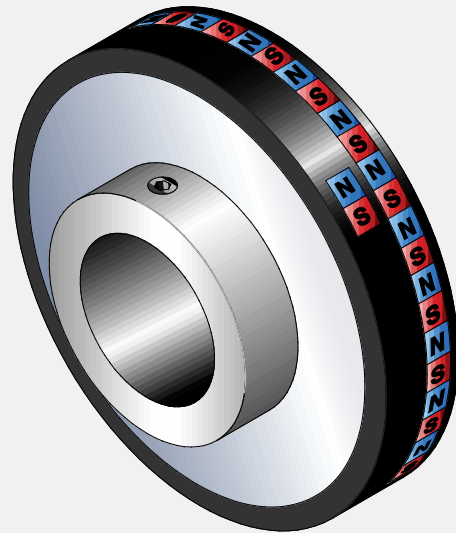
**PMIR7**

Magnetic rings



**PMIR7N**

Magnetic rings with hub



<b>Material</b>	Elastomer bonded hard ferrite
<b>Base material</b>	PMIR7: stainless steel PMIR7N: stainless steel (hub: aluminium)
<b>Poles per revolution</b>	50 / 64 / 90 poles/360°
<b>Magnetic period</b>	2 mm
<b>Temperature range</b>	-40 ...+85°C
<b>Linearity with sensor PMIS4</b>	Approx. ± 0.1°

**Standard magnetic rings**

Type	Poles	∅	Width	Signal periods/rotation	Inside diameter
PMIR7(N)-20-50-M-27(20)	50	31.8	10	50 to 102 400 (refer to the table below)	27H7 (20H7)
PMIR7(N)-20-64-M-35(20)	64	40.7	10	64 to 131 072 (refer to the table below)	35H7 (20H7)
PMIR7(N)-20-90-M-50(20)	90	57.3	10	90 to 184 320 (refer to the table below)	50H7 (20H7)

Scaling factor sensor PMIS4-50- ...	PMIR7(N)-20-50-M-27(20)		PMIR7(N)-20-64-M-35(20)		PMIR7(N)-20-90-M-50(20)	
	Signal periods	r.p.m. * (at 480 kHz)	Signal periods	r.p.m. * (at 480 kHz)	Signal periods	r.p.m. * (at 480 kHz) *
1	50	6000	64	6000	90	6000
2	100	6000	128	6000	180	6000
4	200	6000	256	6000	360	6000
8	400	6000	512	6000	720	6000
10	500	5760	640	4500	900	3200
16	800	6000	1024	6000	1440	6000
20	1000	5760	1280	4500	1800	3200
25	1250	6000	1600	6000	2250	5120
32	1600	6000	2048	6000	2880	6000
40	2000	5760	2560	4500	3600	3200
50	2500	6000	3200	6000	4500	5120
64	3200	6000	4096	5625	5760	4000
80	4000	5760	5120	4500	7200	3200
100	5000	4608	6400	3600	9000	2560
125	6250	3686	8000	2880	11 250	2048
128	6400	3600	8192	2813	11 520	2000
200	10 000	2304	12 800	1800	18 000	1280
250	12 500	1843	16 000	1440	22 500	1024
256	12 800	1800	16 384	1406	23 040	1000
400	20 000	1152	25 600	900	36 000	640
500	25 000	922	32 000	720	45 000	512
512	25 600	900	32 768	703	46 080	500
1024	51 200	450	65 536	352	92 160	250
2048	102 400	225	131 072	176	184 320	125

\* Maximum revolution per minute mechanically 6.000 r.p.m.

**Order code**

**Order code magnetic ring PMIR7**

**PMIR7** -  -

**1 Magnetic period**

20 = 2 mm

**2 Number of poles and inner diameter [in mm]**

50 - M - 27  
64 - M - 35  
90 - M - 50

**Order example magnetic ring**

**PMIR7 - 20 - 64 - M - 35**

**Order code magnetic ring PMIR7N**

**PMIR7N** -  -

**1 Magnetic period**

20 = 2 mm

**2 Number of poles and inner diameter [in mm]**

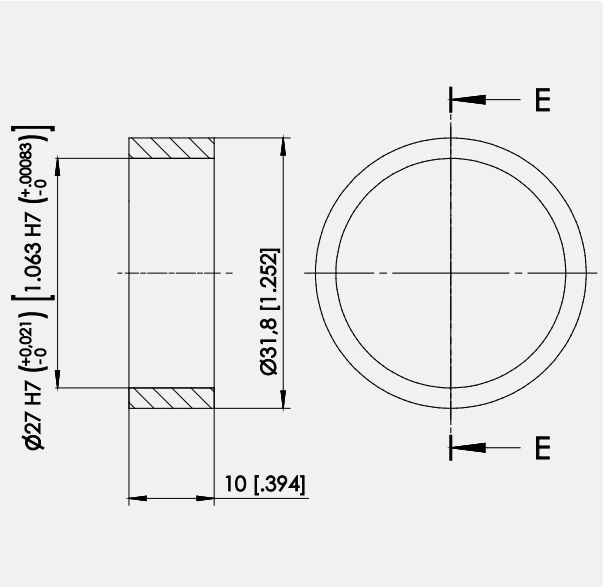
50 - M - 20  
64 - M - 20  
90 - M - 20

**Order example magnetic ring**

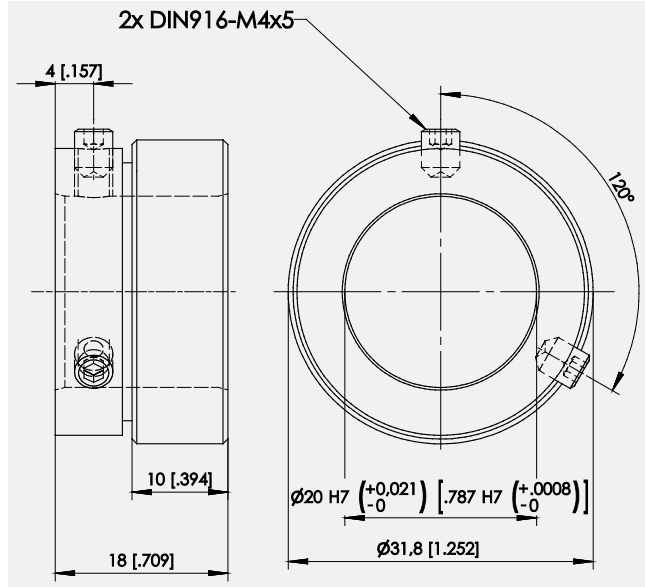
**PMIR7N - 20 - 64 - M - 20**

**Dimensions**

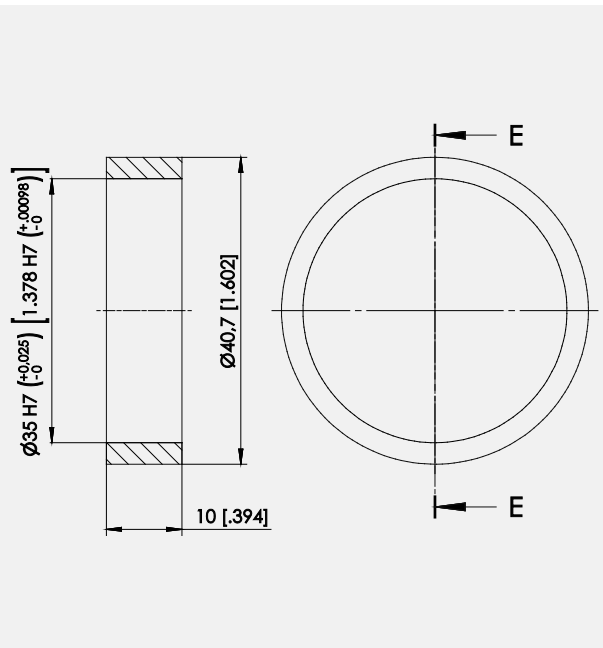
**PMIR7-20-50-M-27**



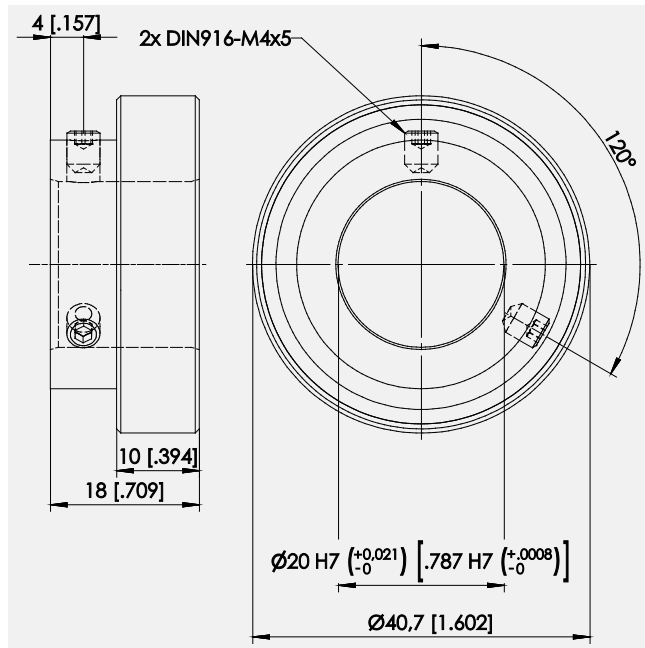
**PMIR7N-20-50-M-20**



**PMIR7-20-64-M-35**



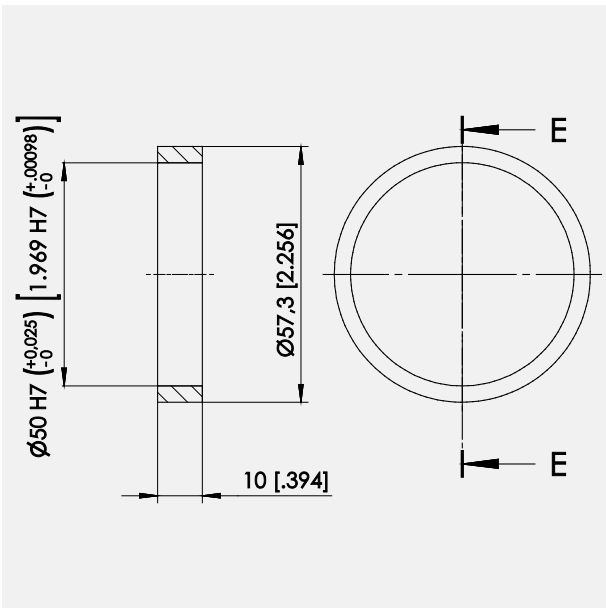
**PMIR7N-20-64-M-20**



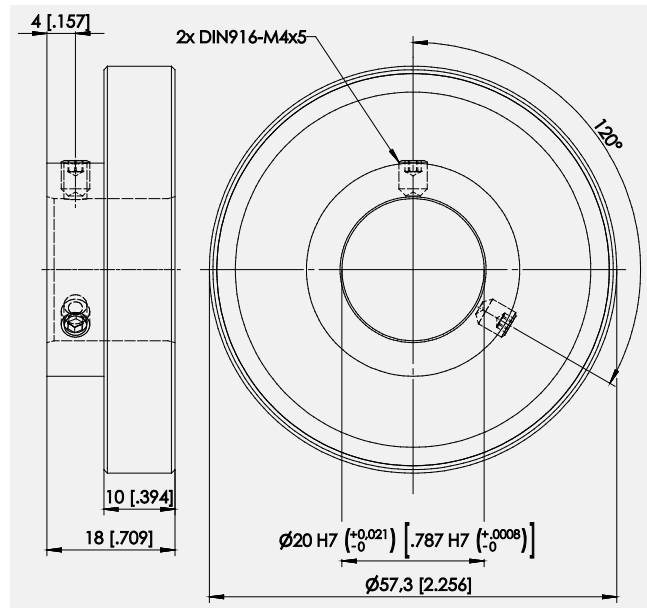
Dimensions in mm [inch].  
 Dimensions informative only.  
 For guaranteed dimensions consult factory.



**PMIR7-20-90-M-50**



**PMIR7N-20-90-M-20**

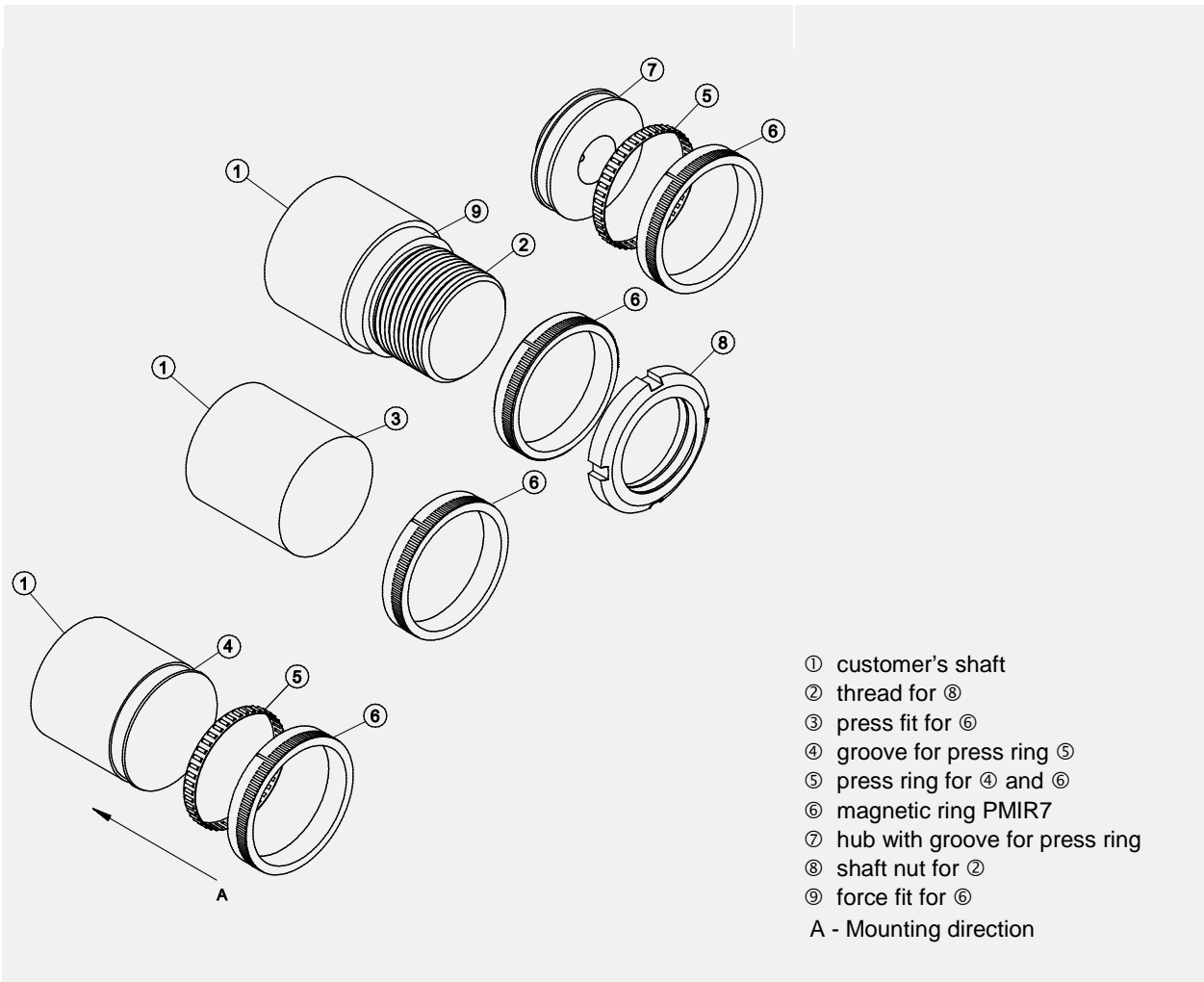


Dimensions in mm [inch].  
 Dimensions informative only.  
 For guaranteed dimensions consult factory.

### How to mount the PMIR7/PMIR7N magnetic rings

The PMIR7/PMIR7N magnetic rings can be mounted in several ways on the customer's shaft resp. hub:

- press ring
- press fit
- bonding
- shaft nut

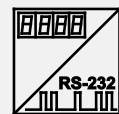
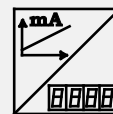
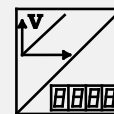


## PRODIS-ADC



### Digital Process Meter for sensors with analog output

- Voltage (e.g. 0 ... 10 V)  
 Current (e.g. 4 ... 20 mA)  
 Voltage divider (Potentiometer)
- Integrated sensor supply
- 6-digit LED display
- RS-232-interface



### Description and specifications

PRODIS®-ADC is designed for use with analog position sensors to display angles and -displacements. A high resolution A/D converter processes signals from sensors with voltage or current output. The meter is programmable to display values within preset start/end range or values in units as inches, mm or degrees. A tare function or programming lock can be activated with two control terminals. Sensor excitation is supplied by the meter. With four membrane keys all parameters can be programmed for the special applications. Optional comparator functions with 4 NPN open-collector output are available, additional 2 of them have relay output.

### Specifications

<b>Display</b>	6-digit, 7-segment LED, height 14 mm,
<b>Counting rate</b>	decimal point programmable
<b>Measurement accuracy</b>	1 ... 25/s programmable
<b>Excitation voltage/current</b>	24 V DC $\pm 10\%$ /150 mA, residual ripple 1%SS; 85-250 V AC, 50-60 Hz/180 mA max.
<b>Sensor excitation</b>	24 V DC/300 mA / voltage divider 5 V, 10 mA
<b>Input</b>	Two channels each for: Voltage: 0 ... 10 V; 0.5 ... 4.5 V, 0.5 ... 10 V, max. 24V, Current: 0...20 mA 3 wires; 4 ... 20 mA 2 wires/3 wires Voltage divider $R_{min}=500\Omega$ , 0 ... 5 V Load 100 $\Omega$ , $I_{max}<30$ mA One input or the difference between both inputs can be chosen by programming.
<b>Control input</b>	2 control inputs 24 V, active low
<b>Comparator output (option)</b>	Relay: 250 V AC/5 A, 30 V DC/5 A NPN: 24 V max./50 mA to GND
<b>Connection</b>	Terminal strip 12 pole, excitation 3 pole
<b>Temperature coefficient</b>	$\pm 20 \times 10^{-6} / ^\circ\text{C}$

<b>Operating temperature</b>	-10...+40 °C
<b>Storage temperature</b>	-20...+85 °C
<b>Weight</b>	24 V DC: approx. 250 g 230 V AC: approx. 400 g
<b>Protection class</b>	Front IP60, rear IP40
<b>Humidity</b>	Max. 80 % R. H., non-condensing
<b>Safety of equipment</b>	Directive 2014/35/EU: EN 61010-1:2010
<b>EMC</b>	Directive 2014/30/EU: EN 61326-1:2013

**Programmable parameters / value range**

<b>Value range offset</b>	-999999 to +999999
<b>Divisor, multiplier</b>	0 to 999999
<b>Other programmable parameters</b>	Decimal point position, display brightness
<b>Control input terminals</b>	Key lock, display value hold, tare function

**Interface RS-232**

<b>Level</b>	RS-232: $\pm 8$ V, galvanically isolated
<b>Data format</b>	1 start bit, 8 data bits, 1 stop bit, no parity
<b>Transmission rate</b>	9600 Baud

**Order code**

PD-ADC – 1 – 2

**1 Excitation voltage**

**24VDC** = 24 V DC

**230VAC** = 85 ... 230 V AC

**2 Options**

**REL2** = Comparator

**DT** = Desktop version

**Order example**

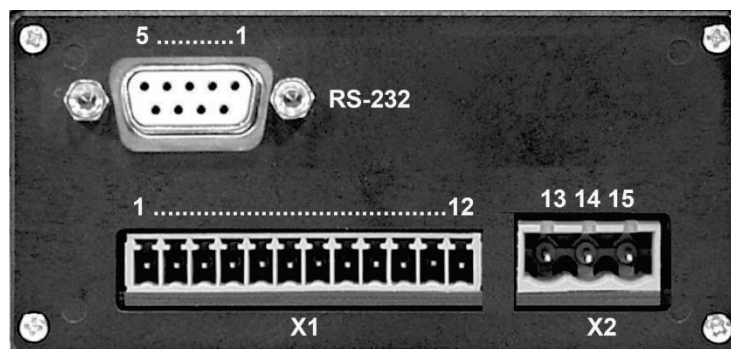
PD – ADC – 24VDC – REL2

**Wiring basic unit**

Signals	Connector X1 Pin no.	Connector X2 Pin no.
Sensor excitation +UB 24 V	1	
Sensor excitation 0 V (GND)	2	
Control input terminal 1: tare function	3	
Control input terminal 2: programming lock	4	
Voltage input terminal (e.g. 0 ... 10 V), channel 1	5	
Voltage input terminal (e.g. 0 ... 10 V), channel 2	6	
Current input terminal (e.g. 0 ... 20 mA), channel 1	7	
Current input terminal (e.g. 0 ... 20 mA), channel 2	8	
Voltage divider input terminal, channel 1	9	
Voltage divider input terminal, channel 2	10	
Reference voltage 5 V for voltage divider	11	
GND	12	
PD-ADC-24VDC Excitation +24 V Excitation 0 V (GND)		13 14
PD-ADC-230VAC Excitation Protective ground		13, 15 14

Signals	D-Sub, pin no.
TxD	2
RxD	3
GND	5

**Rear view without comparator output**



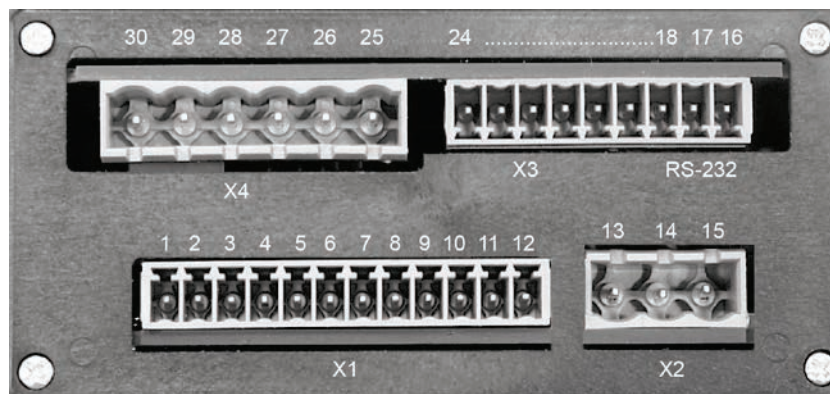
**Wiring basic unit**

Signals	Connector X1 Pin no.	Connector X2 Pin no.
Sensor excitation +UB 24 V	1	
Sensor excitation 0 V (GND)	2	
Control input terminal 1: tare function	3	
Control input terminal 2: programming lock	4	
Voltage input terminal (e.g. 0 ... 10 V), channel 1	5	
Voltage input terminal (e.g. 0 ... 10 V), channel 2	6	
Current input terminal (e.g. 4 ... 20 mA), channel 1	7	
Current input terminal (e.g. 4 ... 20 mA), channel 2	8	
Voltage divider input terminal, channel 1	9	
Voltage divider input terminal, channel 2	10	
Reference voltage 5 V for voltage divider	11	
GND	12	
PD-ADC-24VDC Excitation +24 V Excitation 0 V (GND)		13 14
PD-ADC-230VAC Excitation Protective ground		13, 15 14

Signals	Connector X3 Pin no.
TxD	17
RxD	16
GND	18

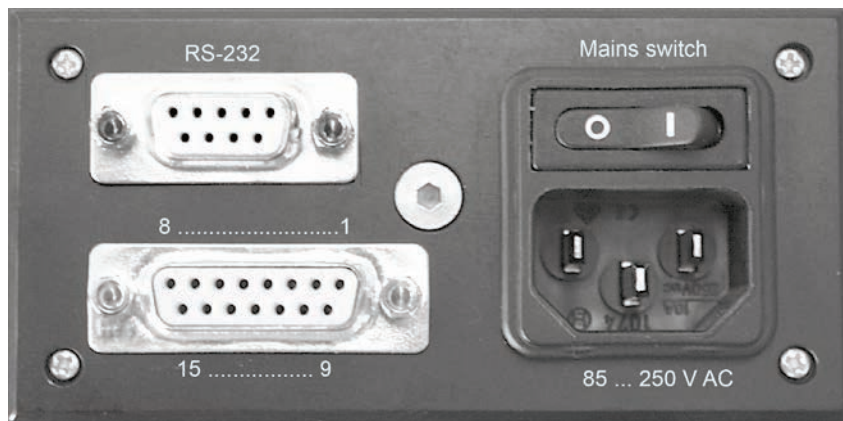
**Rear view with comparator output (option „REL2“)**



**Comparator function (option)**

Comparator	Comparator output				
	NPN collector	Connector X3 Pin no.	Relay	Connector X4 Pin no.	LED
Comparator 1	NPN1	20	Relay 1 NO NC Common	25 27 26	LED1
Comparator 2	NPN2	21	Relay 2 NO NC Common	28 30 29	LED2
Comparator 3	NPN3	22			
Comparator 4	NPN4	23			
	NPN GND	24			
	NPN U <sub>8</sub> (+24V)	19			

**Desktop version (option „DT”)**

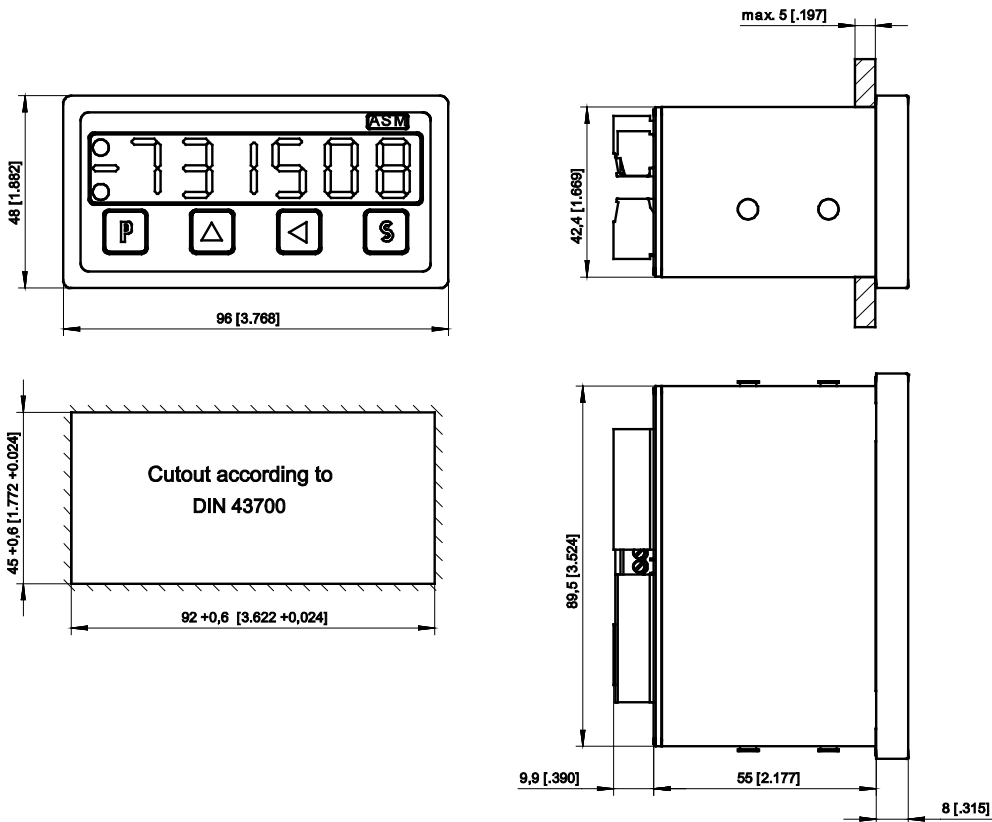


Wiring of connector X1 see table "Wiring basic unit".

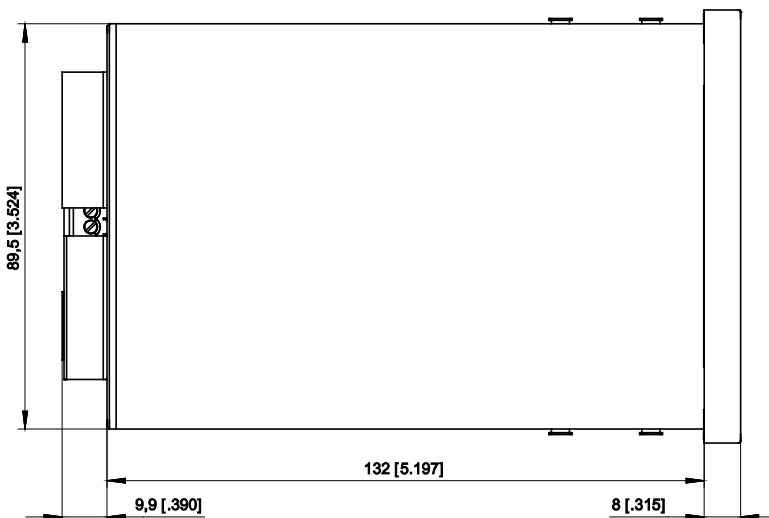


**Dimensions**

**PD-ADC-24VDC**



**PD-ADC-230VAC**



Dimensions in mm [inch]

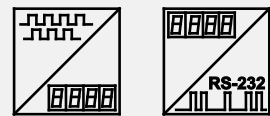
Dimensions informative only. For guaranteed dimensions consult factory.

**PRODIS-INC**



**Digital Process Meter for position sensors with incremental output**

- Counting rate up to 250 kHz (<1 MHz edge frequency)
- Integrated sensor supply
- 6-digit LED display
- RS-232 interface



**Description and specifications**

PRODIS®-INC is designed for use with incremental position sensors to display angles and displacements. The fast counter processes 90° phase shifted A, B signals (quadrature signals) for direction and counting information. Sensor excitation is supplied from the meter. With four membrane keys all parameters can be programmed for the special application. A zero signal and a reference signal can be used for calibration of the measurement system. Optional comparator functions with 4 NPN open-collector outputs are available, additional 2 of them have relay output.

**Specifications**

<b>Display</b>	6-digit, 7-segment LED, height 14 mm, decimal point programmable
<b>Counting frequency</b>	250 kHz max., 1 MHz edge frequency
<b>Excitation voltage/current</b>	24 V DC ±10%/150 mA, residual ripple 1% <sub>SS</sub> ; 85-250 V AC, 50-60 Hz/180 mA max.
<b>Sensor excitation</b>	24 V DC/300 mA or 5V DC/500 mA
<b>Inputs</b>	A, B, Z, T (reference signal)
<b>Comparator outputs (option)</b>	Relais: 250 V AC/5 A, 30 V DC/5 A NPN: 24 V max./50 mA to GND
<b>Connection</b>	Terminal strip 12 pole, excitation 3 pole
<b>Temperature coefficient</b>	±20 x 10 <sup>-6</sup> /°C
<b>Operating temperature</b>	-10...+40°C
<b>Storage temperature</b>	-20...+85°C
<b>Weight</b>	24 V DC: approx. 250 g; 230 V AC: approx. 400 g
<b>Protection class</b>	Front IP60, rear IP40
<b>Humidity</b>	Max. 80% R.H., non condensing
<b>Safety of equipment</b>	Directive 2014/35/EU: EN 61010-1:2010
<b>EMC</b>	Directive 2014/30/EU: EN 61326-1:2013

**Programmable parameters / value range**

<b>Value range display, offset, limit values</b>	-999999 to +999999
<b>Divisor, Multiplier</b>	0 to 999999
<b>Other programmable parameters</b>	Counting direction, decimal point position, last-value memory, Z signal evaluation, display brightness
<b>Signal T</b>	Manual zero, key lock, display value hold, Z release, relative measurement activation

**Interface RS-232**

<b>Level</b>	RS-232: $\pm 8$ V, galvanically isolated
<b>Data format</b>	1 start bit, 8 data bits, 1 stop bit, no parity
<b>Transmission rate</b>	4800 / 9600 / ... / 115200 Baud

**Order code**

PD-INC – 1 – 2 – 3 – 4

**1 Excitation voltage**

**24VDC** = 24 V DC

**230 VAC** = 85 ... 230 V AC

**2 Sensor excitation voltage**

**G24V** = 24 V DC

**G5V** = 5 V DC

**3 Sensor signal**

**HTL** = HTL level with excitation voltage G24V

**TTL** = TTL level with excitation voltage G5V or G24V

**4 Options**

**REL2** = Comparator

**DT** = Desktop version

**Order example**

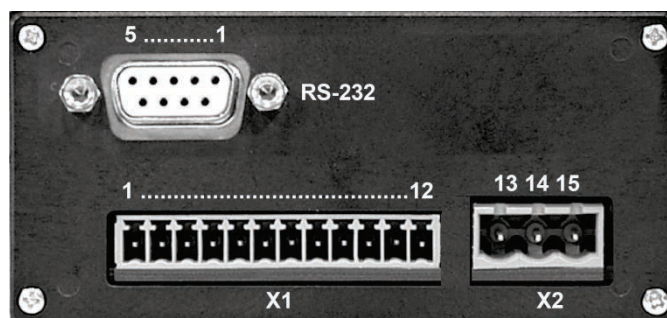
PD – INC – 24VDC – G24V – HTL – REL2

**Wiring basic unit**

Signals	Connector X1 Pin no.	Connector X2 Pin no.
Sensor excitation +U <sub>B</sub>	1	
Sensor excitation 0 V (GND)	2	
Signal A	4	
Signal $\bar{A}$	5	
Signal B	6	
Signal $\bar{B}$	7	
Signal Z (zero signal)	8	
Signal $\bar{Z}$ (zero signal)	9	
Signal T (reference signal)	10	
Signal $\bar{T}$ (reference signal)	11	
GND	12	
PD-INC-24VDC Excitation +24 V Excitation 0 V (GND)		13 14
PD-INC-230VAC Excitation Protective ground		13, 15 14

Signals	D-Sub Pin no.
TxD	2
RxD	3
GND	5

**Rear view without comparator output**

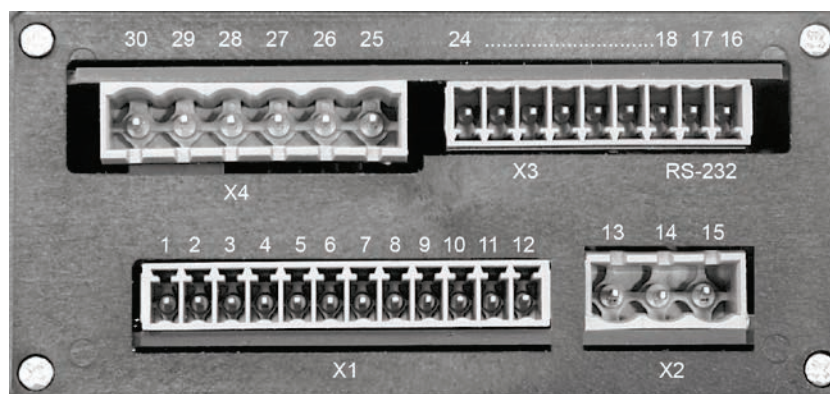


**Wiring basic unit**

Signals	Connector X1 Pin no.	Connector X2 Pin no.
Sensor excitation +U <sub>B</sub>	1	
Sensor excitation 0 V (GND)	2	
Signal A	4	
Signal $\bar{A}$	5	
Signal B	6	
Signal $\bar{B}$	7	
Signal Z (zero signal)	8	
Signal $\bar{Z}$ (zero signal)	9	
Signal T (reference signal)	10	
Signal $\bar{T}$ (reference signal)	11	
GND	12	
PD-ADC-24VDC Excitation +24 V Excitation 0 V (GND)		13 14
PD-ADC-230VAC Excitation +24 V Protective ground		13, 15 14

Signals	Connector X3 Pin no.
TxD	17
RxD	16
GND	18

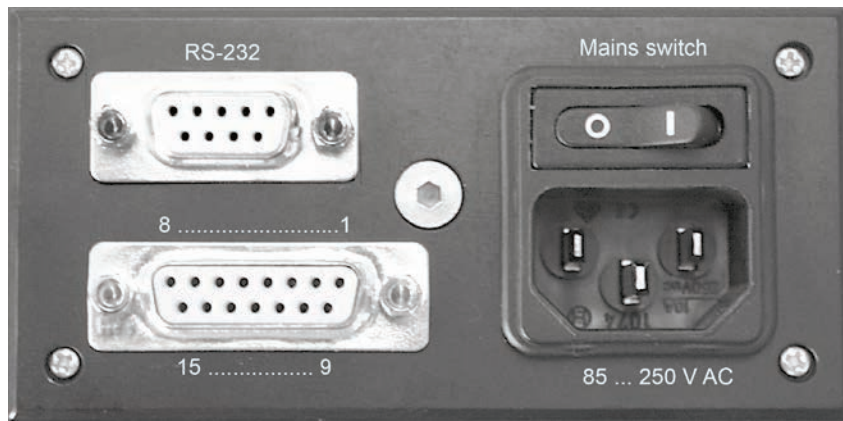
**Rear view with comparator output (option „REL2“)**



**Comparator function (option)**

Comparator	Comparator output				
	NPN collector	Connector X3 Pin no.	Relay	Connector X4 Pin no.	LED
Comparator 1	NPN1	20	Relay 1 NO NC Common	25 27 26	LED1
Comparator 2	NPN2	21	Relay 2 NO NC Common	28 30 29	LED2
Comparator 3	NPN3	22			
Comparator 4	NPN4	23			
	NPN GND	24			
	NPN U <sub>8</sub> (+24V)	19			

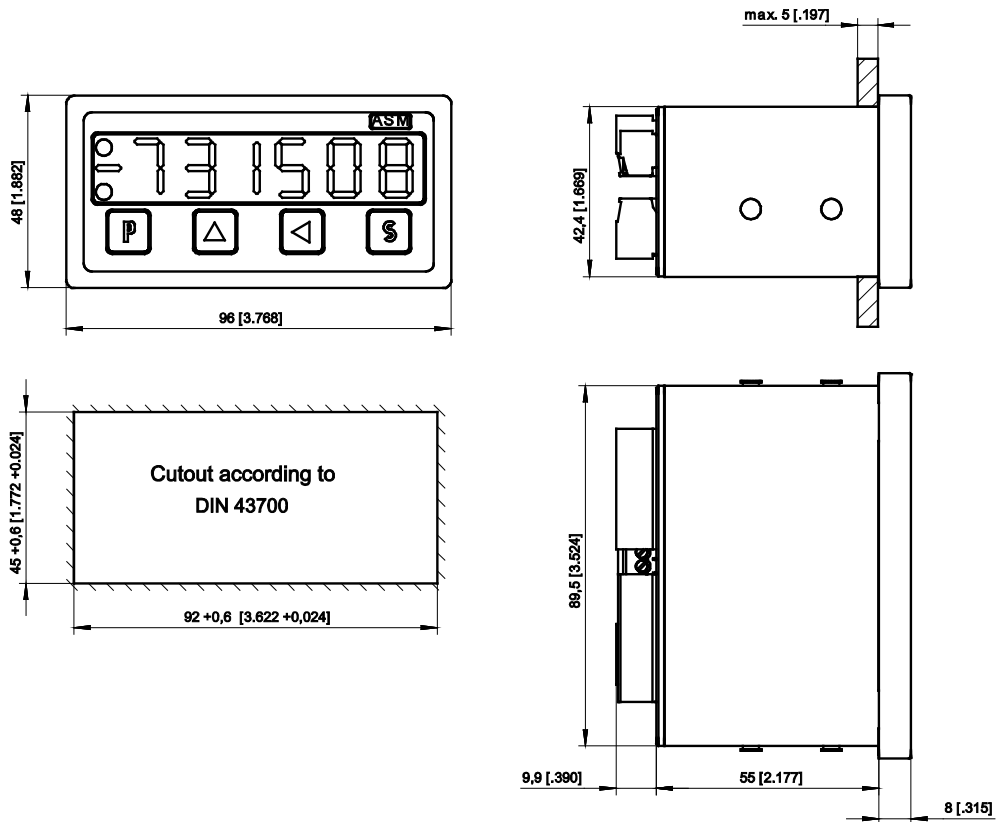
**Desktop version (option „DT”)**



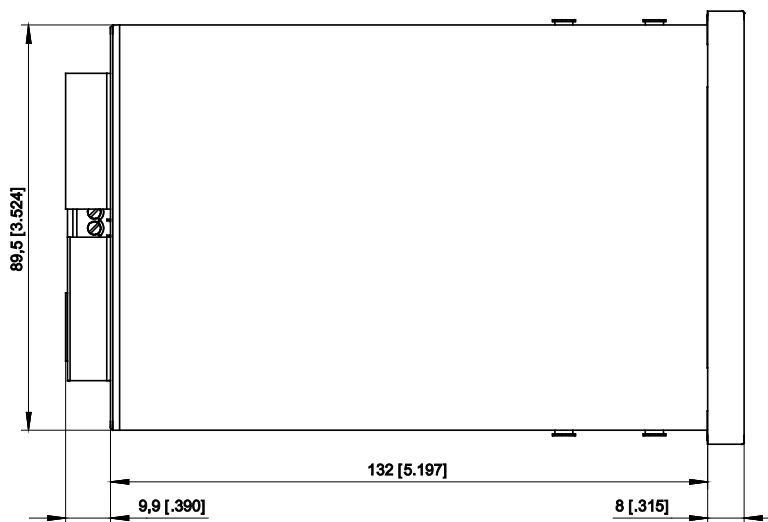
Wiring of connector X1 see table "Wiring basic unit".

**Dimensions**

**PD-INC-24VDC**



**PD-INC-230VAC**



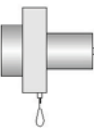
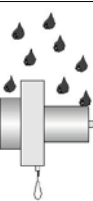
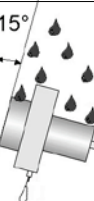

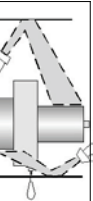
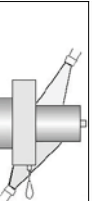
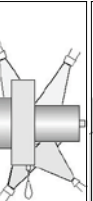
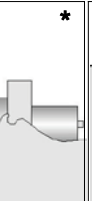
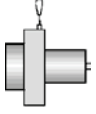


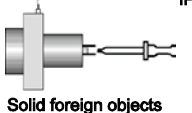


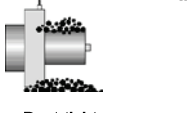
Dimensions in mm [inch]

Dimensions informative only. For guaranteed dimensions consult factory.



## General Information

### Protection Classes according to DIN EN 60529

2nd char. numeral: Protection against ingress of water  1st char. numeral: Protection against solid foreign objects									
Protection against...	Not protected	Falling water drops vertical / 15°		Spraying water	Splashing water	Water jets	Powerful water jets	Temporary immersion	Continuous immersion
DIN EN 60529	IP .. 0	IP .. 1	IP .. 2	IP .. 3	IP .. 4	IP .. 5	IP .. 6	IP .. 7	IP .. 8
 IP 0 .. Not protected	IP 00								
 IP 1 .. Solid foreign objects diameter ≥ 50 mm	IP 10	IP 11	IP 12						
 IP 2 .. Solid foreign objects diameter ≥ 12,5 mm	IP 20	IP 21	IP 22	IP 23					
 IP 3 .. Solid foreign objects diameter ≥ 2,5 mm	IP 30	IP 31	IP 32	IP 33	IP 34				
 IP 4 .. Solid foreign objects diameter ≥ 1 mm	IP 40	IP 41	IP 42	IP 43	IP 44				
 IP 5 .. Dust-protected	IP 50		IP 52	IP 53	IP 54	IP 55	IP 56		
 IP 6 .. Dust-tight	IP 60				IP 64	IP 65	IP 66	IP 67	IP 68*

\* Depth and duration of immersion must be specified!

## ASM Product Catalogs



**POSIWIRE®** – Cable Extension Position Sensors



**POSITAPE®** – Tape Extension Position Sensors



**POSICHRON®** – Magnetostrictive Position Sensors



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